

# The drivers of the Martian bow shock location: a statistical analysis of Mars Atmosphere and Volatile EvolutionN and Mars Express observations

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## Key Points:

- The relative importance of the drivers of the Martian shock location is studied according to the AIC and LASSO model selection methods
- The mach number and EUV fluxes are the primary drivers of the shock location, crustal fields and solar wind pressure are secondary drivers
- The angle between the shock normal and the Interplanetary Magnetic Field appears as a significant driver of the shock location

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## Abstract

The Martian interaction with the solar wind leads to the formation of a bow shock upstream of the planet. The shock dynamics appears complex, due to the combined influence of external and internal drivers. The extreme ultraviolet fluxes and magnetosonic mach number are known major drivers of the shock location, while the influence of other possible drivers is less constrained or unknown such as crustal magnetic fields, solar wind dynamic pressure or the Interplanetary Magnetic Field (IMF) intensity and orientation.

In this paper we compare the influence of the main drivers of the Martian shock location, based on several methods and published datasets from Mars Express (MEX) and Mars Atmosphere Volatile Evolution (MAVEN) missions. We include here the influence of the crustal fields, extreme ultraviolet fluxes, solar wind dynamic pressure, as well as (for MAVEN, thanks to magnetic field measurements) magnetosonic mach number and Interplanetary Magnetic Field parameters (intensity and orientation angles).

The bias due to the cross-correlations among the possible drivers is investigated with a partial correlations analysis. Several model selection methods (Akaike Information Criterion and Least Absolute Shrinkage Selection Operator regression) are also used to rank the relative importance of the physical parameters. We conclude that the major drivers of the shock location are extreme ultraviolet fluxes and magnetosonic mach number, while crustal fields and solar wind dynamic pressure are secondary drivers at a similar level. The IMF orientation also plays a significant role, with larger distances for perpendicular shocks rather than parallel shocks.

## 1 Introduction

Due to the absence of global dynamo magnetic field, the dynamics of the Martian environment is complex with a variety of drivers shaping the induced magnetosphere. The Martian interaction with the solar wind leads to the presence of a bow shock upstream of the planet, as well as several other plasma boundaries, i.e. the Induced Magnetospheric Boundary or the PhotoElectron Boundary. The boundaries are dynamic and depend on internal and external drivers (see e.g. Matsunaga et al. (2017), Garnier et al. (2017)), and studying their dynamics is crucial to better understand the evolution of the Martian environment with time.

50 In the literature, several drivers were considered for the Martian bow shock (here-  
51 after BS) location, based on the data obtained by the Mars Global Surveyor (MGS), Mars  
52 Express (MEX) and Mars Atmosphere and Volatile Evolution (MAVEN) missions. The  
53 first driver analyzed was the solar wind (SW) dynamic pressure (Vignes et al. (2002),  
54 Crider (2004)). Edberg et al. (2010) later showed that the magnetosonic mach number  
55 ( $M_{ms}$ ) of the SW influences significantly the BS. Hall et al. (2016b) (hereafter BH16)  
56 analyzed MEX data and showed the BS location is more sensitive to seasonal variations  
57 in the solar extreme ultraviolet (EUV) irradiance than to SW dynamic pressure varia-  
58 tions, and Hall et al. (2019) also showed the influence of solar cycle EUV dynamics. Halekas  
59 et al. (2017) confirmed the major influence of the magnetosonic mach number and EUV  
60 based on MAVEN data, as well as a significant influence of SW dynamic pressure and  
61 a weak longitudinal dependence due to crustal fields.

62 Beyond these main drivers (EUV,  $M_{ms}$  and SW dynamic pressure), the influence  
63 of other potential drivers is less understood. In particular, the crustal fields influence is  
64 poorly constrained by previous studies. Most of the works suggested a possible influence  
65 of the crustal fields, based on hemispheric differences between the north and south lo-  
66 cations of BS (e.g. Mazelle et al. (2004), Edberg et al. (2008)) or on the dayside vs night-  
67 side location of the strongest crustal source region located in the southern hemisphere  
68 (Gruesbeck et al., 2018). Overall, the influence of the crustal fields on the BS varies in  
69 the literature from no or little influence (Edberg et al., 2009) to strong variabilities, up  
70 to above 1000 km influence based on North/South asymmetries (Edberg et al. (2008), Gruesbeck  
71 et al. (2018)) and is considered through either a local impact (Nemec et al., 2020) or a  
72 global influence (Fang et al. (2015), Fang et al. (2017)).

73 In a companion paper, Garnier et al. (2022a) - hereafter referred to G22 - analyzed  
74 in detail the influence of the crustal fields on the Martian BS location by combining datasets  
75 from MAVEN and MEX. They showed the crustal fields influence is significant (with sev-  
76 eral hundreds of km of induced variation) with a primary influence of the strongest crustal  
77 field source region in the southern hemisphere, seen first through a clear dependence on  
78 the angular distance to this region. The BS location also varies with the crustal field pres-  
79 sure integrated over large areas, or with the planetary longitude when focusing around  
80 southern latitudes instead of considering all latitudes as previous studies. Moreover, they  
81 showed a modulation of this influence that maximizes when the strongest crustal source  
82 region is located closer to noon, with no clear influence observed beyond the termina-

83 tor. They also found a lower limit of the crustal field pressure to observe a related mod-  
84 ification of the BS location, and showed that rapid rotations of the IMF apparently hide  
85 the influence of the crustal fields. They revealed the presence of a bias in the MAVEN  
86 data, due to a cross correlation between crustal fields regions and the EUV fluxes, which  
87 underlines that using the North/South asymmetry of physical parameters as a proxy for  
88 the crustal field influence as performed by several works provides incorrect estimations  
89 of this influence. Moreover, they provided a simple composite parameter that is repre-  
90 sentative of the overall behavior of the BS location with respect to EUV and magnetosonic  
91 mach number (the two major drivers) as well as crustal fields. Finally, they showed the  
92 existence of a seasonal variability of the influence of the crustal fields on the BS, strongly  
93 correlated to the MARSIS Total Electronic Content variability, which reveals the exist-  
94 ence of a large scale coupling between the BS, the crustal fields and the ionosphere.

95 The influence of the IMF parameters - intensity, orientation - was widely discussed  
96 in the literature of the Venusian and terrestrial BS to explain BS asymmetries observed  
97 by several missions. The Venusian BS showed indeed evidence at the Pioneer era for sig-  
98 nificant influence of the IMF parameters on BS asymmetries in the VSE frame (Venus-  
99 Solar-Electric field coordinates, with x axis pointing to the Sun and z axis along the up-  
100 stream solar wind motional electric field). Pole vs equator, dawn/dusk, or north/south  
101 asymmetries were observed depending on the authors, and often interpreted as the re-  
102 sult of the strong mass loading of pickup ions, or of anisotropies of the magnetosonic wave  
103 velocity (Alexander et al. (1986), Russell et al. (1988), Khurana and Kivelson (1994),  
104 Jarvinen et al. (2013)). At Earth, a number of authors also linked dawn/dusk or North/South  
105 BS asymmetries observed to the IMF orientation (Peredo et al. (1995), Dmitriev et al.  
106 (2003), Chapman et al. (2004), Wang et al. (2016)). At Mars, few studies investigated  
107 the influence of the orientation. Vignes et al. (2002) suggested the presence of a North  
108 vs South asymmetry (in the MSE frame), consistent with the idea of asymmetric mass  
109 loading by picked-up oxygen ions (e.g. Fang et al. (2008)), but the authors mentioned  
110 the need for uncoupling from other major factors. Later, Edberg et al. (2009) also sug-  
111 gested an influence of the convection electric field on the martian shock location, how-  
112 ever based on a proxy of the IMF direction based on MGS data since MEX could not  
113 provide such information. Wang et al. (2020) recently proposed a 3D parametric model  
114 of the Martian BS based on a MHD model, suggesting that the IMF components have  
115 differential effects, but neither EUV nor crustal fields were included in this model.

116 In this paper we investigate the possible drivers of the BS location based on both  
 117 MAVEN and MEX BS crossings datasets. Instead of focusing on only few drivers (and  
 118 independently from each other) as most authors, we compare and rank the relative im-  
 119 portance of the drivers of the Martian BS based on several methods, including a partial  
 120 correlation approach to take into account possible biases due to mutual correlation, and  
 121 the Akaike Information Criterion (AIC) and Lasso regularization model selection meth-  
 122 ods to compare the relative importance of the drivers. This allows to provide a compre-  
 123 hensive view of the Martian BS dynamics with respect to internal and external drivers.  
 124 Figure 1 shows a sketch of the Martian interaction, with the possible drivers of the BS  
 125 investigated in this work and detailed later: crustal fields parameters (angular distance  
 126 from the strongest crustal field region center, crustal field pressure, longitude vs Sun of  
 127 the strongest crustal field region), solar Extreme UltraViolet fluxes, SW magnetosonic  
 128 mach number, SW dynamic pressure, IMF intensity and orientation ( $\theta_{bn}$  angle between  
 129 the normal of the BS and the IMF vector;  $\theta_{vn}$  angle between the normal of the BS and  
 130 the SW velocity vector;  $\theta_{bv}$  angle between the SW velocity vector and the IMF vector,  
 131 also called cone angle).

132 The paper is organized as follows: in Section 2 we first describe the MAVEN and  
 133 MEX datasets used (2.1) as well as the methods considered in this study (2.2). Then,  
 134 in Section 3, we first show the results of the direct analysis of the possible drivers of the  
 135 Martian BS location (3.1) and then we show how cross-correlations are considered to ap-  
 136 propriately interpret the influence of minor drivers (3.2). A focus is then made on the  
 137 influence of parallel vs perpendicular BS (3.4), before we compare the relative influence  
 138 of the BS drivers with the Akaike Information Criterion or Lasso regularization techniques  
 139 (3.5). We then end the paper with a discussion (Section 4) and a conclusion (Section 5).

## 140 2 Datasets and methods

### 141 2.1 Description of the datasets

142 We use in this study the same datasets as G22, which we refer to for a more de-  
 143 tailed description of the lists of MAVEN and MEX crossings considered. Here we pro-  
 144 vide a brief description.

145 The MEX BS crossings dataset was derived by BH16 from the MEX ASPERA-3  
 146 ELS data Barabash et al. (2006), including 11,820 crossings from January 2004 to May

147 2015. The MAVEN BS crossings dataset is a combination of the lists of crossings pub-  
 148 lished by Fang et al. (2017) and Gruesbeck et al. (2018), derived from the analysis of the  
 149 MAVEN magnetic field MAG data (Connerney et al., 2015), electron SWEA data (Mitchell  
 150 et al., 2016), and ion SWIA data (Halekas et al., 2015). The MAVEN dataset comprises  
 151 3837 BS crossings from November 2014 to April 2017.

152 The large number of BS crossings for MEX and MAVEN - due to their respective  
 153 orbital periods of 6.7 and 4.5 hours - allows for a large spatial and temporal coverage that  
 154 enables statistical analyses. Significant differences between both datasets need to be con-  
 155 sidered. First, MEX covers a large period through a whole solar cycle, while the MAVEN  
 156 dataset corresponds to a shorter period where the mean EUV level (given by the solar  
 157 10.7 *cm* radio flux) was larger by  $\sim 14\%$  compared with the MEX dataset. We thus fo-  
 158 cus on the dynamics rather than on absolute BS location due to the different solar con-  
 159 ditions encountered. Second, the MEX spacecraft is not equipped with a magnetic field  
 160 instrument, which prevents us from using MEX data to investigate the influence of IMF  
 161 related parameters (such as IMF intensity and orientation, magnetosonic mach number).

162 We derive and analyze the extrapolated terminator altitude already used by pre-  
 163 vious authors (Edberg et al. (2008), Hall et al. (2016b), Fang et al. (2017)). It allows to  
 164 represent the variability of the BS location by removing the strong solar zenith angle in-  
 165 fluence, assuming an axisymmetric symmetry. The crossings location are transformed  
 166 in the SW aberrated cylindrical MSO system (rotated by  $4^\circ$  for both MAVEN and MEX).  
 167 The extrapolated terminator altitude,  $R_{TD}$ , is calculated by :

$$R_{TD} = \sqrt{L^2 + (e^2 - 1) \cdot X_0^2 + 2 \cdot e \cdot L \cdot X_0} - R_M \quad (1)$$

168 where  $R_M$  is the Martian radius (3390 *km*),  $L$  and  $e$  are the semi-latus rectum and ec-  
 169 centricity, and the focus of the conic is located at  $(X_0, 0, 0)$ . We used for the MEX cross-  
 170 ings the  $(X_0, e)$  values by Hall et al. (2016b), and for MAVEN the values by Fang et al.  
 171 (2017). The choice of the conic parameters may introduce some uncertainties in the ab-  
 172 solute values of  $R_{TD}$ , but the variabilities basically remain unchanged in our experiments  
 173 of using several conic fit parameters (e.g. Edberg et al. (2008), Hall et al. (2016b), Fang  
 174 et al. (2017)) for both the MAVEN and MEX crossings. The impact of the conic param-  
 175 eters is discussed in Section 3.4.

176 Note the one dimensional approach allows to investigate the presence of any large  
 177 scale and permanent influence on the BS location, including asymmetries of the BS shape

178 or a permanent influence of IMF intensity and orientation angles, as studied by numer-  
179 ous previous authors (e.g. Alexander et al. (1986), Russell et al. (1988), Zhang and K. Schwin-  
180 genschuh (1991), Vignes et al. (2002), Edberg et al. (2009), Chai et al. (2014), Chai et  
181 al. (2015), Wang et al. (2020)); let us consider for example a strong local time asymme-  
182 try or further shocks at low cone angles: propagating the location of the respective cross-  
183 ings at dawn vs dusk or low vs large cone angles would lead to very different values of  
184 the distance to the conic focus, resulting in very different values of the recalculated semi-  
185 latus rectum  $L$  (that depends on the distance from the focus), which would finally lead  
186 to very different  $R_{TD}$  values according to the above equation.

## 187 **2.2 Description of the methods**

### 188 *2.2.1 Zero-order correlations and partial correlations*

189 Beyond the direct analysis of the extrapolated terminator altitude, we use in this  
190 paper correlation approaches defined below (for more details, see G22): zero-order lin-  
191 ear Pearson correlation coefficients, unpaired t-tests and partial correlations.

192 First, simple linear Pearson correlation coefficients are used to investigate linear  
193 relationships between two variables. Hypothesis tests are used to calculate the signifi-  
194 cance of the correlation. A t-test evaluates the test statistics associated with the corre-  
195 lation, and compares it with the statistics of the null hypothesis  $H_0$ : if the test statis-  
196 tics  $t$  is larger than a threshold (i.e. the null hypothesis statistics  $t_{H_0}$ ) defined for a given  
197 risk, or equivalently if the p-value is smaller than the risk considered (5% by default),  
198 then the correlation is considered significant, otherwise the correlation factor is consid-  
199 ered not significantly different from 0. We will in the rest of the paper mention that p-  
200 values are negligible when they are smaller than  $10^{-5}$  and tag them with "(n)". Unpaired  
201 t-tests can also be used to determine if there is a significant difference between two groups  
202 of data. They assess whether the two groups show different mean values, with p-values  
203 providing the significance of this difference. Throughout the paper, correlations factors  
204 as well as significance tests statistics or p-values by default correspond to direct linear  
205 correlations.

206 Second, we use a partial correlation approach in Section 3.2 to investigate possi-  
207 ble biases due to cross correlations between parameters, and thus more appropriately quan-  
208 tify the influence of the drivers. The partial correlation approach (see Baba et al. (2004)

209 or Appendix A of G22) allows to investigate linear relations, calculate correlation coef-  
 210 ficients - and estimate their significance - between e.g. two variables  $y$  and  $x_0$ , after con-  
 211 trolling for the influence of other variables  $x_i$ . G22 successfully used this technique to  
 212 disentangle the influence of the crustal fields on the Martian BS location despite a sig-  
 213 nificant cross correlation with EUV in the MAVEN data. It was also used by several au-  
 214 thors for the solar wind Earth interaction (Simms et al., 2021), solar physics (Le & Zhang,  
 215 2017), or galaxies and compact objects (Yesuf and Ho (2019), Ni et al. (2020)). This method  
 216 allows to investigate cross correlations in a rigorous manner, without using sub-selections  
 217 of the dataset to control specific parameters, which reduces the number of samples in  
 218 each dataset by a factor  $2^n$  ( $n$  number of variables) which becomes critical in the case  
 219 of the Martian BS that may be influenced by a number of parameters.

220 The correlations are considered linear ( $y = a + \sum_i x_i \cdot b_i$  with  $a$  constant and  $b_i$   
 221 slopes), but can alternatively correspond to power laws ( $y = a \prod_i x_i^{b_i}$ ) then linearized  
 222 by a logarithm. Note that the linear assumption is weak and our method does not need  
 223 true linear relationships to remain valid, since at first order most of the regular relation-  
 224 ships can be considered as linear (or power law like). The significance of the partial cor-  
 225 relation factors is given by a t-test to compare the statistics with the null assumption  
 226  $H_0$ , and provides p-values that need be smaller than the risk chosen (5% by default) to  
 227 consider to the partial correlation as significant. The 5% risk level corresponds to a 2  
 228 standard deviations tolerance interval for a gaussian probability distribution.

### 229 ***2.2.2 The Akaike Information Criterion and Lasso regularization***

230 Understanding the dynamics of the plasma boundaries implies understanding both  
 231 the relationship with individual drivers (as can be performed through correlations, or  
 232 partial correlations to minimize biases) and the relative influence of each of these drivers.  
 233 Ranking the relative importance of the drivers can be achieved by model selection ap-  
 234 proaches such as the Akaike information criterion or the LASSO method.

235 The Akaike information criterion (AIC; see more details in Appendix A) is a model  
 236 selection method based on information theory that allows to rank the variables influenc-  
 237 ing a specific parameter (Akaike, 1974). Biesiada (2007) for example used the AIC ap-  
 238 proach to rank competing dark energy models based on supernovae data, while Kubo  
 239 (2008) compared several models for the probability density functions of solar flare in-

240 interval, in order to develop probabilistic solar flare forecasting for space weather appli-  
241 cations. In our case, the model considered is a linear regression (or a power law regres-  
242 sion as described above) including a number of possible drivers of the BS (Section 3.5).

243 The Least Absolute Shrinkage Selection Operator (LASSO; see a detailed descrip-  
244 tion in section Appendix B) is the second model selection approach that is used in Sec-  
245 tion 3.5 to compare the relative importance of the BS location. LASSO is one of the most  
246 commonly used supervised regularization method for regression (Tibshirani, 1996), where  
247 a penalty term allows the identification of the significance of predictors in a regression  
248 model. In a similar manner as in classical linear regression, it minimizes the residual sum  
249 of squares to determine the regression coefficients of each predictor, but here by penal-  
250 izing the sum by the absolute values of the regression coefficients. LASSO is widely used  
251 in a variety of domains, such as space weather for solar flare detection/prediction (Benvenuto  
252 et al. (2018), Benvenuto et al. (2020)), identification of explanatory variables of super-  
253 novae magnitude (Uemura et al., 2015), or star formation model selection and stellar pa-  
254 rameters estimation (Lu and Li (2015), Dey et al. (2019)).

255 We use in Section 3.5 AIC and LASSO approaches to investigate the relative im-  
256 portance of the Martian BS location drivers. These methods allow for selecting the best  
257 model with the smallest number of predictors by applying recent statistical techniques  
258 and avoiding overfitting compared with common multivariate regression models. Our aim  
259 is not to provide detailed functional forms of the Martian BS  $R_{TD}$  variability with re-  
260 spect to its drivers (which would need a theoretical description of these influences, and  
261 are not directly derived from either AIC or LASSO methods), but to provide a better  
262 understanding of the drivers of the BS location, and compare their relative importance.

### 263 **3 Results**

#### 264 **3.1 Direct analysis of the drivers influence**

265 In this section, we study the influence of the following possible drivers for the BS  
266 location, previously mentioned in Section 1 and derived as detailed below:

- 267 • Solar Extreme UltraViolet fluxes (EUV) for MAVEN and MEX: the EUV values  
268 were determined for MAVEN from the FISM model (Chamberlin et al. (2007); avail-  
269 able for MAVEN but not MEX on the CDPP/AMDA database - <http://amda.cdpp.eu/>)

for 10–120 *nm* wavelengths, and for MEX from the solar 10.7 *cm* radio flux index extrapolated to Mars assuming a  $1/r_{Mars\ Sun}^2$  law; using solar radio flux values for MAVEN leads to almost identical results, since both parameters are strongly correlated (with a correlation factor of 0.98 (n)); however, we choose the FISM model for MAVEN since it is available and slightly more precise than the radio flux proxy, and the absolute values of EUV are of no interest in our study where we focus on methods which are unit independent

- SW dynamic pressure for MAVEN and MEX: the SW dynamic pressure is derived from the SW parameters (plasma density, velocity) provided by respectively MEX/IMA and MAVEN/SWIA data; a restriction on the quality factor values for MEX/IMA data is applied, which reduces the number of MEX crossings available with this driver (this explains why the median  $R_{TD}$  value for SW dynamic pressure in the Figure 3 discussed below is different from the others)
- SW magnetosonic mach number ( $M_{ms}$ ) for MAVEN: the MAVEN  $M_{ms}$  (no magnetic field measurements were available for MEX) is calculated by  $M_{ms} = v_{sw} / \sqrt{c_s^2 + v_A^2}$  with  $v_{sw}$  SW speed,  $c_s$  sound speed,  $v_A$  Alfvén speed, with the electron temperature assumed equal to the proton temperature and a polytropic index  $\gamma = 5/3$
- crustal magnetic fields for MAVEN and MEX: several parameters for the crustal field were used and derived in particular from the Morschhauser et al. (2014) model at 400 *km* altitude, directly based on the results by G22:
  - crustal field pressure ( $B^2/(2\mu_0)$ ) at the sub-spacecraft longitude/latitude of the crossing
  - crustal field pressure averaged over an angular range of 75° around the local coordinates to account for the large spatial extent of crustal fields effects (the angular range value of 75° provides the strongest correlation between the crustal field pressure and the shock variability according to G22)
  - averaged crustal field pressure convolved with a Gaussian-like weighting function (with  $\sigma = 60^\circ$ , based on G22), to increase the local influence of crustal fields in the averaging procedure
  - angular distance to the strongest crustal source region located in the southern hemisphere (assumed centered at  $\sim -45^\circ$  latitude and  $\sim 180^\circ$  longitude) to focus on the influence of the strongest crustal source region

- MSO longitude ( $\phi_{MSO}$ ) of this strongest crustal source region to account for the larger impact of crustal fields when this crustal fields region is on the dayside
- IMF intensity and orientation for MAVEN: the IMF vector is measured by the MAVEN MAG instrument, allowing to derive several parameters
  - IMF intensity
  - the clock angle of the IMF:  $\tan^{-1}(B_{Z_{IMF}}/B_{Y_{IMF}})$
  - $\theta_{bn}$  angle between the normal of the BS (calculated from the axisymmetric shock shape based on the conic parameters by Fang et al. (2017) for MAVEN) and the IMF vector; this angle is used to determine whether BS are "parallel" (low  $\theta_{bn}$  values) or perpendicular (large  $\theta_{bn}$  values)
  - $\theta_{vn}$  angle between the normal of the BS and the SW velocity vector
  - $\theta_{bv}$  angle between the SW velocity vector and the IMF vector, also called cone angle
  - the MSE pole vs equator asymmetry, determined by the absolute cosine of the angle between the IMF and the location of the crossing projected in the terminator plane (equivalent to the MSE frame representation); this angle was called "clock angle" of the crossing by several authors for studies of Venus (Alexander et al. (1986) and Russell et al. (1988)) and can be used to show the influence of the mass loading of planetary ions picked up by the electric field, with possible enhanced BS location asymmetry in the direction perpendicular to the IMF

Note we use cosine or sine of the angles considered in this study to use comparable parameter ranges, but the use of direct angles leads to unchanged qualitative results.

Figure 2 shows the MAVEN and MEX extrapolated terminator altitudes of the BS crossings as a function of the drivers considered significant in the literature: EUV,  $Mms$  (for MAVEN only), SW dynamic pressure, and the crustal fields through the angular distance from the strongest crustal source region introduced by G22. As shown by previous authors, the BS is located at higher altitudes in response to stronger EUV fluxes or lower  $Mms$  values, as well as under weaker SW dynamic pressures or spacecraft locations closer to the strongest crustal source region in the southern hemisphere. The MAVEN panels (upper panels) clearly show that larger  $Mms$  values lead to smaller  $R_{TD}$  values. Enhanced EUV lead to higher BS altitudes for both MAVEN and MEX datasets. The

334 influence of SW dynamic pressure and angular distance to the strongest crustal source  
335 region are also visible in the observations by both missions: the mean profile (black dashed  
336 line) show that despite very strong data scattering (due to the presence of other signif-  
337 icant drivers at the same time and possibly spatial asymmetry of the boundary) the MAVEN  
338 and MEX BS  $R_{TD}$  values decrease with increasing SW dynamic pressure by hundreds  
339 of km; the panels b and f show the same results as G22, with decreasing  $R_{TD}$  values (by  
340 several hundreds of km) from the region around the strongest crustal fields - with an an-  
341 gular extent of  $40/50^\circ$  corresponding to the size of the strongest crustal source region  
342 - to regions away from the strongest crustal source region, with slight peaks around an-  
343 gular distances of  $120-150^\circ$  that may correspond to the influence of localized crustal  
344 sources indeed present at such angular distances. Note that the ranges of SW dynamic  
345 pressures are different between both missions: this may be due to either different time  
346 periods, or to the different types of instruments and methods used to extract the dynamic  
347 pressure; however, even if a real difference was existing, this would not impact our con-  
348 clusions that are based on the variability of the drivers, with analysis for both missions  
349 that independent from each other.

350 In order to show the influence of the possible drivers of the BS altitude in a com-  
351 prehensive and comparable manner, Figure 3 shows a simple and classic approach, based  
352 on direct correlation coefficients and  $R_{TD}$  values (see details below) for both MAVEN/MEX  
353 missions.

354 The figure provides two different ways of comparison between the various drivers.  
355 The lower panel provides the linear Pearson correlation coefficients between the termi-  
356 nator altitudes of the BS and the parameters. The upper panel uses the following ap-  
357 proach: each set of parameters (EUV, Mms, etc.) was separated into low (= below the  
358 median value of the parameter) and high (= above the median value of the parameter)  
359 subsets; the median terminator altitudes of the "low" (blue) and "high" (red) subsets  
360 are then determined for each parameter to show how low/high regimes of each driver in-  
361 fluences the terminator altitude of the BS.

362 The main differences between both missions are the smaller changes observed (in  
363 both altitude variations and correlations) for MEX compared to MAVEN, and lower ter-  
364 minator altitudes for MEX. Regarding the first difference, the much larger dataset for  
365 MEX (11820 crossings compared to 1760) induces a stronger mixing of different influ-

366 ences and a greater difficulty to distinguish one driver from another. Systematic differ-  
 367 ences may also exist between MAVEN and MEX due to different instruments and meth-  
 368 ods for determining the BS locations. The second difference most probably originates  
 369 from the EUV levels encountered at the MAVEN and MEX crossings. The large MEX  
 370 dataset allows for a wide range of EUV conditions, with a full solar cycle (including the  
 371 lower and extended ever recorded solar minimum), while the MAVEN dataset corresponds  
 372 to a period with an active Sun in 2014 and 2015 (where most of our MAVEN crossings  
 373 occurred) below a declining activity in 2016-2017. The mean EUV level of the MAVEN  
 374 crossings (given by the solar  $10.7\text{ cm}$  radio flux:  $49 \cdot 10^{-22}\text{ W/m}^2/\text{Hz}$ ) was thus larger  
 375 by  $\sim 14\%$  compared with the MEX dataset ( $43 \cdot 10^{-22}\text{ W/m}^2/\text{Hz}$ ). Given the major  
 376 influence of EUV on the BS location (see below), the larger EUV conditions associated  
 377 to the MAVEN dataset certainly contribute to the slightly larger BS distances observed  
 378 (by  $\sim 5\%$ ) for MAVEN than for MEX. The compared magnetosonic mach number con-  
 379 ditions, which also have a major influence on the BS location, may also have induced this  
 380 absolute difference in the BS altitude between both missions, however these conditions  
 381 are not known precisely for the pre-MAVEN period.

382 Overall, based on the correlation coefficients or absolute variations related to in-  
 383 dividual parameters, the BS terminator altitude seems to increase with (in a descend-  
 384 ing order of importance and for both MAVEN/MEX) 1) and 2) increasing EUV fluxes  
 385 or decreasing magnetosonic mach number (MAVEN case, MEX probably as well given  
 386 the results by Edberg et al. (2010)), 3) either over stronger crustal field regions or near  
 387 perpendicular BS (large sine of  $\theta_{bn}$ ) or stronger IMF intensity, 4) decreasing SW dynamic  
 388 pressure, 5) large cosine of clock and cone angles, and 6) other angular parameters of  
 389 the IMF ( $\theta_{vn}$  or the MSE pole vs equator asymmetry). The apparent relative influence  
 390 of the (non-IMF related) drivers are consistent between the two spacecraft, with smaller  
 391 variabilities and lower absolute altitudes for MEX than for MAVEN due to a larger amount  
 392 of data and to the different EUV conditions. A small difference can however be noticed  
 393 in the relative importance of crustal fields vs SW dynamic pressure or EUV from MAVEN  
 394 to MEX, with crustal fields appearing slightly more influent in the case of MAVEN: this  
 395 is due to mutual correlation between parameters, i.e. between EUV and crustal fields  
 396 as discussed in details by G22, or between EUV and SW dynamic pressure as detailed  
 397 in the next section that discusses the cross correlations between parameters. The appar-  
 398 ent strong influence of the IMF intensity will also be discussed.

399 Note that using the averaged crustal field intensity instead of the averaged crustal  
 400 field pressure, or an even smaller power law index of the pressure such as  $(B^2/(2\mu_0))^{1/6}$   
 401 as used by XF17, also leads to similar results with close correlation factor values or ab-  
 402 solute variations that may vary by  $\pm 10\%$  maximum with no change of the above rank-  
 403 ing conclusions.

404 An illustration of the complex dynamics of the Martian BS that involves a com-  
 405 bination of various physical drivers is the comparison between the extreme BS locations  
 406 observed and the extreme solar events encountered by the MAVEN and MEX missions,  
 407 which shows a variety of situations. The maximum  $R_{TD}$  value (7913 km altitude) for the  
 408 MEX dataset was reached on 22<sup>nd</sup> October 2014, and was induced by a combination of  
 409 large crustal fields, a relatively low SW dynamic pressure and most importantly one of  
 410 the largest EUV conditions encountered. These extreme EUV conditions were related  
 411 to the event consisting of M and X type solar flares originating from the same active re-  
 412 gion 12192 from 19<sup>th</sup> to 22<sup>nd</sup> October 2014, surprisingly not accompanied with coronal  
 413 mass ejections (Sun et al. (2015), Thalmann et al. (2015)). Over the three days of the  
 414 solar flares event, all BS crossings  $R_{TD}$  values were among the 7% largest of the MEX  
 415 dataset. The smallest  $R_{TD}$  value (1614 km altitude) for the MEX dataset was reached  
 416 on 25<sup>nd</sup> June 2010, at a period with very low EUV (but not among the extreme low val-  
 417 ues), relatively strong SW dynamic pressure and over the strongest crustal source region.  
 418 No extreme solar CME-type event happened closely before this crossing to our knowl-  
 419 edge, except for the slow CME mentioned by Manchester et al. (2017) but which hap-  
 420 pened probably too early (on 16<sup>th</sup> June 2010) to be related with the extreme low Mar-  
 421 tian BS crossing location.

422 Regarding the MAVEN BS dataset, neither the extreme low (on 4<sup>th</sup> March 2016;  
 423  $R_{TD} = 2016$  km altitude) nor the extreme high (on 31<sup>th</sup> January 2015;  $R_{TD} = 9243$   
 424 km altitude) BS terminator distances correspond to extreme solar events as listed by Lee  
 425 et al. (2017) who provided a comprehensive overview of the space weather events dur-  
 426 ing the first 2 years of the MAVEN mission. These two extreme BS locations were due  
 427 to a combination of both strong/low EUV and magnetosonic mach number, but not among  
 428 the most extreme values. Another typical example of the complex influence of solar events  
 429 on the BS is the early March 2015 period where MAVEN encountered one of the stormi-  
 430 est space weather conditions, with a series of solar flare and CME activity (including a  
 431 strong ICME impact on 8<sup>th</sup> March 2015). Despite extreme external conditions (in EUV,

432 SW dynamic pressure) leading to strong consequences (Jakosky et al., 2015) on the plasma  
433 escape rate, formation of diffuse aurora, magnetosheath dynamics, or on the BS shape  
434 according to simulations, the magnetosonic mach number still kept moderate during the  
435 event (i.e. between 5.6 and 7.2 during the strong ICME) which prevented the BS from  
436 a strong compression. Moreover, EUV enhancements induced by solar flares counteract  
437 the influence of solar wind dynamic pressure pulses related to concomitant CMEs. The  
438 Martian BS location variability thus appears complex, with a variety of internal phys-  
439 ical drivers that influence its location at the same time, in contrast with the Earth's BS  
440 driven primarily by the SW dynamic pressure and in a secondary way by magnetosonic  
441 mach number (Cairns et al., 1995). This difference is due to the presence of an intrin-  
442 sic magnetosphere at the Earth: the large scale dynamo magnetic field defines indeed  
443 the size of the obstacle at Earth, while the martian obstacle is defined essentially by the  
444 thin ionized atmosphere, with EUV and crustal fields thus playing roles that are minor  
445 at Earth, all the more the presence of an intrinsic magnetic field creates a magnetopause  
446 at Earth that is known to shape the bow shock (Wang et al. (2016)) which is not the case  
447 at Mars.

### 448 **3.2 Investigating cross correlations with the partial correlation approach**

449 The previous section suggested that a number of parameters simultaneously play  
450 a significant role in the BS location, although the simple approach used above consid-  
451 ers the parameters independently from each other. Investigating the detailed influence  
452 of the parameters of influence, in particular the minor drivers, needs to consider the pos-  
453 sible intercorrelations between them regardless of whether they are physically meaning-  
454 ful. G22 e.g. highlighted how strong EUV fluxes were observed at the time of BS cross-  
455 ings observations where the spacecraft flew over the strongest crustal field regions of the  
456 planet, a coincidence due to observation conditions and to the spacecraft orbit preces-  
457 sion during the mission.

458 Figure 4 shows a diagram of how physical parameters that potentially influence the  
459 Martian BS location may be intercorrelated. The figure shows the same figure as Fig-  
460 ure 1 where we superimposed the direct linear Pearson correlation factors between the  
461 BS terminator altitude and the possible drivers of the BS location, as well as between  
462 the possible drivers themselves. The thickness of the lines is proportional to the corre-  
463 lation factor, while the color gives the sign of the correlation.

464 The schematics shows, beyond the statistically significant correlation (p-values be-  
 465 low 5%) between a number of drivers and the BS location (with in particular the ma-  
 466 jor influence of EUV and Mms), cross correlations between most of the drivers themselves.  
 467 One notes that the direct correlations between the major drivers and the BS  $R_{TD}$  are  
 468 stronger than the cross correlations, which increases the confidence in their direct influ-  
 469 ence on the BS location. For example, the EUV correlation with  $R_{TD}$  is stronger than  
 470 the correlation of EUV with other possible drivers. This is the case for EUV (with both  
 471 MEX and MAVEN datasets),  $Mms$  (MAVEN dataset) and crustal fields (with the MEX  
 472 dataset, see below for the MAVEN dataset).

473 The cross correlations among the drivers must be considered to avoid biased in-  
 474 terpretations, particularly when they are comparable or even greater than the direct zero-  
 475 order correlation with  $R_{TD}$ . In the case of the MAVEN dataset, the cross correlations  
 476 between the crustal fields parameters considered and the BS location is e.g. smaller than  
 477 the cross correlations between the crustal fields parameters and the EUV. At least a part  
 478 of the influence of the crustal fields in the MAVEN dataset shows up through the cross  
 479 influence of EUV that is a major driver of the BS location. G22 investigated this issue  
 480 and used the partial correlation approach to investigate whether the crustal fields had  
 481 a significant influence not only in the MEX dataset (where no such bias exists) but also  
 482 in the MAVEN dataset. They concluded that indeed a part of the apparent crustal fields  
 483 influence was due to the cross correlation with the EUV conditions, but controlling for  
 484 the EUV influence in the analysis still leads to very significant partial correlations of the  
 485 angular distance to the strongest crustal source region or of  $\phi_{MSO}$  the MSO longitude  
 486 of the strongest crustal source region center with the BS  $R_{TD}$  (with negligible p-values  
 487 of respectively  $10^{-11}$  and  $10^{-7}$ ). Controlling over the EUV then leads to similar corre-  
 488 lations factors and similar relative influence of the EUV and crustal fields parameters  
 489 between MEX and MAVEN based on the slopes of the multivariate regression performed  
 490 with the partial correlation analysis.

491 Even when cross correlations are not strong enough to interfere the influence of a  
 492 driver, they can lead to an overestimation or an underestimation of the influence of the  
 493 drivers. If one considers two variables  $x_1$  and  $x_2$  that influence the parameter  $y$  (in our  
 494 case  $R_{TD}$ ) and that can be cross correlated to each other, three correlation factors can  
 495 be considered :  $r_{12}$ ,  $r_{1y}$  and  $r_{2y}$ . When the product of the signs of the three correlation  
 496 factors is positive (e.g.  $r_{12} > 0$ ,  $r_{1y} < 0$  and  $r_{2y} < 0$ ), this means the influence of vari-

497 ables  $x_1$  and  $x_2$  on  $y$  is to some extent overestimated when considering only the direct  
 498 correlation factors  $r_{1y}$  and  $r_{2y}$ , while their influence is underestimated when the prod-  
 499 uct of the signs of the correlation factors is negative. Depending on the relative signs of  
 500 the correlations, a part of the increase or decrease of  $y$  due to a correlation with one of  
 501 the variables (e.g.  $x_1$ ) may be indeed partially due to or hidden by the increase of the  
 502 second variable (e.g.  $x_2$ ) that is not only correlated with  $y$  but also with  $x_1$ . This can  
 503 be illustrated by the example of the influence of the SW dynamic pressure, as detailed  
 504 below.

505 The SW dynamic pressure influence on the BS location is clearly visible when sim-  
 506 ple scatter plots with the BS location are performed, with in particular fewer high al-  
 507 titudes crossings at pressures above 1  $nPa$  (in a similar manner to the MGS results by  
 508 Crider et al. (2003)). However, the (linear or power law) negative correlation with  $R_{TD}$   
 509 is relatively small ( $-0.12/-0.10$  (n) with a linear assumption for MAVEN/MEX) com-  
 510 pared to the correlations of  $R_{TD}$  with EUV fluxes (strong positive correlation) or mag-  
 511 netosonic mach number (strong negative correlation), and also smaller than correlations  
 512 with crustal field pressure or angular distance. However, these direct correlations of the  
 513 SW dynamic pressure previously mentioned in Section 3.1 may be slightly underestimated  
 514 in both MAVEN and -to a lesser extent - MEX datasets due to a small positive cross cor-  
 515 relation between SW dynamic pressure and EUV fluxes (correlations of respectively 0.12  
 516 (n) and 0.09 (n) for MAVEN and MEX datasets): the solar wind dynamic pressure was  
 517 e.g. for MAVEN on average of  $\sim 0.8$   $nPa$  during the low EUV periods, and of  $\sim 1$   $nPa$   
 518 during the high EUV periods. Enhanced EUV fluxes push the BS to higher altitudes,  
 519 so that enhanced EUV fluxes occurring at the same time as slightly enhanced solar wind  
 520 dynamic pressure may partially hide the compression of the BS due to small solar wind  
 521 dynamic pressure pulses. With a partial correlation analysis assuming a linear regres-  
 522 sion (or power law with similar results) and a control over the EUV fluxes and - for MAVEN  
 523 only - magnetosonic mach number, the partial correlations between the solar wind dy-  
 524 namic pressure and the BS  $R_{TD}$  altitude become larger at  $-0.24$ (n) and  $-0.14$ (n) respec-  
 525 tively for MAVEN and MEX. After controlling for cross-correlations with the major drivers,  
 526 the solar wind dynamic pressure thus appears as a driver with a similar influence (re-  
 527 garding correlation factors) as the crustal fields pressure or angular distance.

528 We show in Figure 5 the residuals of the  $R_{TD}$  terminator altitude of the MAVEN  
 529 and MEX BS crossings vs candidate drivers, after removing the linear dependance on

530 the major drivers (EUV and *Mms* for MAVEN, EUV for MEX). The resulting p-values  
 531 of the partial linear correlation coefficients are also shown. After controlling for the ma-  
 532 jor drivers of the BS location, most of the possible drivers still keep a significant corre-  
 533 lation with the BS location. This includes the crustal fields (described by the indepen-  
 534 dent variables that are angular distance and  $\phi_{MSO}$  MSO longitude of the strongest crustal  
 535 source region center), SW dynamic pressure, as well as the IMF intensity and several IMF  
 536 orientation angles ( $\theta_{bn}$ ,  $\theta_{vb}$ , clock angle, but not  $\theta_{vn}$ ) and the MSE pole vs equator asym-  
 537 metry, with correlations that are more or less obvious by eye (less for MSE pole vs equa-  
 538 tor,  $\theta_{vb}$  or clock angle). However, if these residuals confirm that a number of physical  
 539 parameters can be possible secondary drivers of the Martian BS location, the schemat-  
 540 ics in Figure 4 underline the need to consider secondary drivers one by one, in partic-  
 541 ular the IMF and its orientation angles that are strongly cross correlated to each other  
 542 and not only to the major drivers EUV and *Mms*. The IMF intensity appears also com-  
 543 plex with e.g. a reversal of the influence on the BS location after controlling over *Mms*  
 544 and EUV, which is discussed in the next section focusing on the influence of the IMF  
 545 characteristics.

### 546 3.3 The influence of the Interplanetary Magnetic Field

547 We focus on the MAVEN dataset in this section to analyze the influence of the IMF  
 548 (intensity and orientation) on the Martian BS location. We discuss with more details  
 549 the impact of the IMF, whose characteristics include complex cross correlations beyond  
 550 those with the major drivers. We also compare with results obtained in the literature  
 551 at planets where the IMF influence was more widely investigated. The specific influence  
 552 of the  $\theta_{bn}$  angle is discussed in Section 3.4.

553 The IMF intensity is apparently significantly positively correlated with the  $R_{TD}$   
 554 altitudes (Pearson correlation factor of 0.26 (n)), in contradiction with the simple effect  
 555 of an increased external magnetic pressure. A positive correlation could be due to the  
 556 fact that an enhanced IMF induces a stronger draping around the planet, which could  
 557 consequently push the BS further. However, Figure 4 shows that the IMF is even more  
 558 strongly correlated with the SW dynamic pressure or the magnetosonic mach number  
 559 (*Mms* includes both parameters in its definition, with the IMF intensity through the Alfvén  
 560 velocity). The control for both EUV and *Mms* (see Figure 5) thus changes strongly the  
 561 apparent influence of the IMF intensity, with even a reversal of the correlation that be-

562 comes negative with the MAVEN BS  $R_{TD}$  (Pearson correlation factor of  $-0.21$  (n)). In-  
 563 cluding also the SW dynamic pressure in the partial correlation in addition to EUV and  
 564  $Mms$  shows a much reduced correlation between the IMF and  $R_{TD}$  with a Pearson lin-  
 565 ear correlation coefficient of  $-0.07$  (p-value of  $0.01\%$ ). The real influence (if any) of the  
 566 total IMF intensity on the BS location thus is difficult to be distinguished due to com-  
 567 plex mutual correlations with other significant drivers.

568 Wang et al. (2020) recently proposed a 3D parametric model of the Martian BS  
 569 based on a MHD model, including solar wind parameters (dynamic pressure, IMF in-  
 570 tensity and orientation,  $Mms$ ) but not EUV or crustal fields. Beyond the strong influ-  
 571 ence of  $Mms$  (and of SW dynamic pressure according to the authors), they suggested  
 572 that the IMF components have differential effects, with the BS expanding along the MSO  
 573  $Y/Z$  axis for respectively increasing  $B_Z/B_Y$  IMF components and a stronger influence  
 574 of  $B_X$  in the tail. However, the analysis of our dataset does not show such differential  
 575 influence on the BS  $R_{TD}$  altitudes: the IMF components have little influence compared  
 576 to the total IMF on  $R_{TD}$ , with e.g. a partial correlation significance of  $B_Z$  with  $R_{TD}$  be-  
 577 low the null  $H_0$  assumption when focusing on BS crossings around the MSO Y axis sec-  
 578 tor. An influence of the IMF  $B_X$  component in the tail is however difficult to identify,  
 579 due to the limited number of MAVEN crossings in the tail (only 24 crossings occurred  
 580 at  $X < -1 R_M$ ).

581 Beyond the IMF intensity, the orientation of the IMF is often considered as a pos-  
 582 sible driver of planetary BS through various angular characteristics. First, the cosine of  
 583 the angle  $\theta_{vn}$  has an apparent small negative but still statistically significant direct cor-  
 584 relation with the BS  $R_{TD}$  values, but controlling for the EUV fluxes (or for the other main  
 585 drivers) with the partial correlation approach reduces the significance of the correlation  
 586 well below the  $H_0$  null assumption (p-value of  $49\%$ ). Similarly, the significance of the  
 587 already small correlation between the cosine of the cone angle  $\theta_{bv}$  and the BS distance  
 588 becomes non-significant (p-value of  $31\%$ ) after controlling for the  $\theta_{bn}$  influence. No sig-  
 589 nificant cone angle dependence can thus be seen as was observed at Venus by Alexander  
 590 et al. (1986), where the authors interpreted BS variations as possibly due to a more ef-  
 591 ficient mass loading through an enhanced conventional electric field  $\vec{E} = -\vec{V} \times \vec{B}$  cross  
 592 product for incident flows perpendicular to the IMF. At Earth, Wang et al. (2020) showed  
 593 that the flaring of the Earth's BS increases at low cone angles, leading to further shocks

594 in the tail and closer shocks near the nose, which is not observed with our martian dataset  
595 based on partial correlations and direct plotting of the crossings location.

596 The clock angle of the IMF appeared as a significant driver in the previous anal-  
597 ysis based on direct correlations, with BS located farther in response to low clock an-  
598 gles, i.e. for an IMF along the MSO Y axis, thus corresponding to an electric field along  
599 the Z axis. However, cautions must be taken regarding this possible influence for two main  
600 reasons : 1) the clock angle distributions is highly inhomogeneous with  $\sim 70\%$  of the  
601 crossings with an IMF lying within  $30^\circ$  around the MSO Y axis; 2) cross-correlations mod-  
602 ify the apparent influence of the clock angle of the IMF. The residuals of the  $R_{TD}$  de-  
603 pendance after controlling for both EUV fluxes and  $Mms$  already reduces the clock an-  
604 gles influence (Figure 4), but the cross correlation with the  $\theta_{bn}$  angle (Figure 5) is even  
605 larger: a partial correlation analysis shows that controlling simply for the sine of  $\theta_{bn}$  re-  
606 duces significantly the remaining correlation between the clock angle (its cosine) and the  
607 BS location close to the significance limit (p-value of 5.3%). An influence of the clock  
608 angle thus appears still possible but small, which agrees with the findings by XF17.

609 In the literature, a number of studies make use of the "clock angle" of BS cross-  
610 ings to reveal IMF related asymmetries. This "clock angle" of a crossing actually cor-  
611 responds to the angle between the IMF and the location of the crossing projected in the  
612 MSO  $Y-Z$  plane, equivalent to the MSE frame representation. At Venus, Alexander  
613 et al. (1986) and Russell et al. (1988) showed based on Pioneer Venus Orbiter data that  
614 the terminator distance of the Venusian BS was maximum along the E-field leading to  
615 apparent "pole/equator" asymmetry in the MSE frame, attributed to either a consequence  
616 of mass loading of planetary ions (picked up by the electric field) or to the fast mode mag-  
617 netosonic wave speed dependence on the IMF orientation. Later, Chai et al. (2014) and  
618 Chai et al. (2015) used the "clock angle" variability based on Venus Express measure-  
619 ments to reveal the presence of north vs south, pole vs equator and dawn vs dusk asym-  
620 metries of the Venusian BS. Chai et al. (2014) first suggested that the underlying rea-  
621 son for the pole/equator and dawn/dusk asymmetries was the influence of the tangen-  
622 tial (to the BS surface) component of the IMF. In their following work, Chai et al. (2015)  
623 showed a decrease of the pole vs equator asymmetry at low SZA, which lead the authors  
624 to conclude this asymmetry was rather caused by the anisotropic magnetosonic wave speed  
625 whose influence is expected to increase with travel time (which itself increases with SZA).  
626 Earth models by Wang et al. (2016) showed a larger shock tail cross section in the di-

627 rection perpendicular to the IMF, most probably due to the influence of the  $\theta_{bn}$  angle  
 628 on the magnetosonic wave speed. At Mars, Zhang and K. Schwingenschuh (1991) used  
 629 Phobos magnetometer data from only 27 BS crossings and concluded about pole vs equa-  
 630 tor asymmetries similar to the Venus case. Vignes et al. (2002) used the "clock angle"  
 631 variability of the Martian BS extrapolated terminator distance from MGS data to sug-  
 632 gest the presence of a North vs South asymmetry (in the MSE frame), with larger  $R_{TD}$   
 633 values along the upward electric field, consistent with the idea of asymmetric mass load-  
 634 ing of the magnetosheath by the picked-up oxygen ions. This asymmetry appeared stronger  
 635 at large cone angles, in agreement with an enhanced influence of the  $\vec{E} = -\vec{V} \times \vec{B}$  cross  
 636 product. The authors however mentioned the need for uncoupling from other factors in  
 637 the future and also advised to check whether this asymmetry was enhanced during so-  
 638 lar maximum where EUV induced ionization is increased. Later, Edberg et al. (2009)  
 639 also suggested the presence of larger martian shock  $R_{TD}$  values along the convection elec-  
 640 tric field direction than on the opposite side, however based on a proxy of the IMF di-  
 641 rection based on MGS data since MEX could not provide such information.

642 Figure 6 provides the MAVEN BS  $R_{TD}$  altitudes in the MSE frame (upper panel),  
 643 as a function of the angle from the IMF vector in a radial way as performed by Russell  
 644 et al. (1988), or in a linear way for low vs large cone angles (lower panel) as performed  
 645 in numerous previous studies (Zhang and K. Schwingenschuh (1991), Vignes et al. (2002),  
 646 Chai et al. (2014), Chai et al. (2015), Wang et al. (2020)). The upper panel does not show  
 647 strong equator vs pole, or north vs south asymmetries. However, it suggests a small asym-  
 648 metry with enhanced  $R_{TD}$  values along the axis defined by  $(120^\circ, 300^\circ)$  (thus similar to  
 649 a polar vs equator asymmetry but shifted by  $\sim 30-45^\circ$ ), an asymmetry also suggested  
 650 when focusing around close to terminator BS crossings only. The lower panel also sug-  
 651 gests this asymmetry appears stronger at large cone angles, in agreement with an increased  
 652  $\vec{V} \times \vec{B}$  influence. Unpaired Student's t-tests were performed and infirm the presence of  
 653 a North vs South asymmetry suggested by Edberg et al. (2009) or Vignes et al. (2002)  
 654 (even at high cone angles following the suggestions by Vignes et al. (2002)) or of a pole  
 655 vs equator asymmetry (with large p-values above 50%), but suggest the shifted pole vs  
 656 equator asymmetry is a priori statistically significant (with p-values of  $3.3 \cdot 10^{-4}$  /  $5.6 \cdot$   
 657  $10^{-5}$  for cone angles below / larger than  $60^\circ$ ) before considering possible cross correla-  
 658 tions. The partial correlation between the absolute cosine of the angle from the IMF and  
 659 the BS location after controlling over EUV and  $Mms$  keeps significant (p-value of 2.0·

660  $10^{-5}$ , see Figure 5). However, a radial representation of the residuals shows little asym-  
 661 metry. Moreover, the unpaired student t-test mentioned above confirming an a priori shifted  
 662 pole vs equator asymmetry becomes poorly significant (the p-value rises up to 2%) as  
 663 soon as we remove the EUV and Mms influence by considering residuals. A close to equa-  
 664 tor vs pole asymmetry is thus suggested by the MAVEN direct data analysis. Chai et  
 665 al. (2014) mentioned that the Venusian BS equator vs pole asymmetry was stronger at  
 666 the terminator or beyond for large IMF  $B_Y$  intensities, which is not observed with our  
 667 dataset, but our tail coverage is poor. Overall, it is very difficult to conclude on the in-  
 668 fluence of a specific minor driver such as the "clock angle" of the crossings based solely  
 669 on a direct analysis such as provided in Figure 6, due to the combined influence of other  
 670 important parameters (EUV, Mms...). Specific methods shall be used, such as partial  
 671 correlations, AIC or LASSO (see section 3.5), that are able to take into account the cross  
 672 correlations between a number of possible drivers: their influence can indeed eventually  
 673 hide or lead to an underestimation / overestimation of the influence of minor drivers when  
 674 simple direct analysis are performed such as in Figure 6.

### 675 3.4 Quasi-perpendicular vs quasi-parallel shocks

676 Another parameter suggested as significant in Section 3.1 is  $\theta_{bn}$  the angle between  
 677 the BS normal and the IMF direction, available for the MAVEN dataset. This angle is  
 678 a distinguishing indicator between quasi-parallel (low  $\theta_{bn}$  values) and quasi-perpendicular  
 679 (large  $\theta_{bn}$  values) BS. Our correlation analysis revealed a rather strong correlation (0.19  
 680 (n)) between the MAVEN BS  $R_{TD}$  altitude and the sine of  $\theta_{bn}$  (or 0.22 (n) with  $\theta_{bn}$  it-  
 681 self). Figure 7 shows the MAVEN BS altitude dataset organized as a function of the sine  
 682 of  $\theta_{bn}$  ( $\theta_{bn}$  is considered positive). This profile suggests indeed that perpendicular BS hap-  
 683 pen on average at higher altitudes than parallel BS, which is also observed in the resid-  
 684 uals of Figure 7 after removing the linear dependance with respect to EUV and Mms.  
 685 We performed partial correlation analysis that confirm the statistical significance of the  
 686  $\theta_{bn}$  influence, with a large  $t/t_{H_0}$  ratio above 8 (leading to negligible p-value) when con-  
 687 trolling over the magnetosonic mach number, EUV and any of the other variables con-  
 688 sidered in this study (solar wind dynamic pressure or other IMF angle, angular distance...  
 689 Below, we investigate the physical reasons that could induce an influence of the  $\theta_{bn}$  an-  
 690 gle with perpendicular BS at higher terminator altitudes than parallel BS.

Several authors mentioned a similar influence at planetary BS, with further perpendicular BS than parallel BS, usually for the reason detailed below. The (Martian) BS is indeed a fast mode type of BS (Mazelle et al., 2004), with a fast mode magnetosonic wave velocity  $\nu_{ms}$  defined by:

$$\nu_{ms} = \sqrt{\frac{1}{2} \left[ (c_s^2 + V_A^2) + \sqrt{(c_s^2 + V_A^2)^2 - 4c_s^2 V_A^2 \cos^2 \theta_{Bn}} \right]} \quad (2)$$

with  $c_s$  sound speed and  $v_A$  Alfvén speed. Based on this equation, it appears that perpendicular BS ( $\theta_{bn}$  close to  $90^\circ$ ) lead to larger velocity values of the magnetosonic wave (the wave velocity being thus anisotropic), which could induce a further location of the BS.

In the literature, Alexander et al. (1986) or Russell et al. (1988) suggested at Venus that the asymmetries observed could be a consequence of an anisotropic magnetosonic wave velocity, instead of an increased mass loading effect. Khurana and Kivelson (1994) modeled this anisotropic velocity at Venus to account for an elliptic cross section of the BS in the tail. At Earth, Peredo et al. (1995) confirmed, based on a more than 1000 BS crossings dataset issued from 17 spacecraft, previous analysis suggesting a north-south vs east-west asymmetry in the Mach cone. They suggested that the differential Mach cone extension was a consequence of the anisotropy of the magnetosonic wave velocity depending on the IMF orientation (through  $\theta_{bn}$ ), with an influence mostly expected in the tail and for low Mach values (where the anisotropy has more time to develop). Dmitriev et al. (2003) then compared several BS models with Geotail and Wind crossings datasets (with > 4000 crossings) and mentioned the important role of the dawn-dusk asymmetry of the BS tail region that was mostly controlled by a faster magnetosonic wave due a perpendicular configuration. Chapman et al. (2004) confirmed with MHD modeling the significant influence of the  $\theta_{bn}$  angle due to enhanced wave velocity on the Earth's BS asymmetries, in particular at low Mach numbers. Later, Chai et al. (2015) analyzed the pole vs equator asymmetry observed at Venus, and concluded on the influence of an anisotropic wave speed (due to  $\theta_{bn}$ ) in particular since this asymmetry reduced at low SZAs where the wave anisotropy is expected to lead to less influence than at higher SZAs where the BS is further and the travel time of the wave is larger. Wang et al. (2016) also investigated with MHD modeling the long debated influence of the IMF orientation on the Earth's BS. They showed that the enhanced magnetosonic wave velocity plays an important role in the tail asymmetries observed at low Mach numbers, with a maximum

722 cross section in the direction perpendicular to the IMF. The Earth's BS thus appears  
 723 controlled mostly by the solar wind dynamic pressure and the mach number on the day-  
 724 side, but the IMF orientation plays a major role in the tail with mach number.

725 At Mars, a few early works also mentioned an influence of  $\theta_{bn}$ . Zhang and K. Schwin-  
 726 genschuh (1991) first used Phobos magnetometer data from 27 BS crossings to investi-  
 727 gate the IMF control of the BS. They concluded that the Martian BS exhibited asym-  
 728 metries similar to the Venus case in a magnetic frame (MSE equivalent), i.e. North vs  
 729 South, pole vs equator and perpendicular vs parallel with respect to the IMF, the lat-  
 730 ter being presumably the consequence of an anisotropic wave velocity. Later, Vignes et  
 731 al. (2002) mentioned a possible difference between perpendicular and parallel BS cross-  
 732 ings (with perpendicular BS at  $R_{TD}$  values  $\sim 3\%$  above) but could not explain it. Over-  
 733 all, a number of Earth and Venus studies, as well as few Mars studies, thus mentioned  
 734 a possible influence of the anisotropic wave velocity on the BS, essentially based on ge-  
 735 ometrical arguments rather than based on quantitative arguments.

736 However, in our case calculating the wave speed with Equation 2 reveals that it barely  
 737 depends on the orientation of the IMF with respect to the BS normal. First, the wave  
 738 speed appears essentially given by the combination of the sound and Alfvén speeds  $\sqrt{c_s^2 + V_A^2}$ ,  
 739 with 90% of the MAVEN BS crossings showing a ratio  $\frac{a_{fast}}{\sqrt{c_s^2 + V_A^2}}$  above 0.9. Second, one  
 740 would expect, if an anisotropic wave speed was the reason for the  $\theta_{bn}$  influence, that the  
 741 BS  $R_{TD}$  altitude would be more strongly correlated with  $\nu_{ms}$  rather than with  $\theta_{bn}$  or its  
 742 sine. The direct correlations of  $\nu_{ms}$  and the sine of  $\theta_{bn}$  with  $R_{TD}$  are actually similar (re-  
 743 spectively 0.20(n) and 0.19 (n)), but much of the influence of the wave speed on the BS  
 744 location is due to the  $Mms$  influence through the Alfvén velocity that is closely related  
 745 to the wave speed  $\nu_{ms}$  (with a very strong correlation of  $-0.71$  (n)): the partial corre-  
 746 lation of  $\nu_{ms}$  with  $R_{TD}$  becomes small and even slightly negative ( $-0.06$ ) after control-  
 747 ling over the influence (assumed linear at first order) of EUV and (mostly)  $Mms$ . Simi-  
 748 larly, the partial correlation between the sine of  $\theta_{bn}$  and  $R_{TD}$  keeps strong and almost  
 749 unchanged (correlation factor 0.16 (n)) when controlling for the fast magnetosonic wave  
 750 speed value, thus suggesting an independent influence of the  $\theta_{bn}$ . The apparent influence  
 751 of the wave speed is thus due to the magnetosonic Mach number influence rather than  
 752 the IMF orientation. Moreover, the analysis of the influence of  $\theta_{bn}$  shows no specifically  
 753 stronger influence at low SZAs or low Mach number regimes that would be expected with  
 754 an anisotropic wave speed influence (Peredo et al. (1995), Chai et al. (2015)). One can

755 note Chai et al. (2014) suggested that the influence of  $\theta_{bn}$  on the differential perpendicular  
 756 vs parallel BS at Venus was due to the influence of the tangential component of the  
 757 IMF rather than the anisotropic wave velocity (the latter explanation being preferred  
 758 in their following paper in Chai et al. (2015)). However, if the direct correlation of this  
 759 tangential component with the BS location also appears strong in our dataset (correla-  
 760 tion factor of 0.30 (n)), it is due to the cross-correlation with  $Mms$  that is a major driver  
 761 of the BS location: the partial correlation of the IMF tangential component with  $R_{TD}$   
 762 becomes very small ( $-0.03$ , with a p-value of 2.3% only) after controlling over  $Mms$  and  
 763 EUV, while the  $\theta_{bn}$  influence does not reduce after controlling for a linear influence of  
 764  $Mms$  or other variables.

765 Apart from the anisotropy of the wave speed explanation, several authors linked  
 766 the perpendicular vs parallel BS differences to dawn vs dusk asymmetries observed at  
 767 planetary BS, in particular since the Parker spiral average configuration implies (depend-  
 768 ing on the IMF  $B_X$  component) that parallel/perpendicular BS correspond to respec-  
 769 tively dawn/dusk sectors (see expectations at Earth by Walters (1964) and Dmitriev et  
 770 al. (2003), or Vignes et al. (2002) results at Mars, and Chai et al. (2014) at Venus). Gruesbeck  
 771 et al. (2018) mentioned a possible dawn vs dusk asymmetry of the Martian BS based on  
 772 MAVEN data, but could not explain its absence at low SZAs. Our analysis of the local  
 773 time variation of the MAVEN BS  $R_{TD}$  values reveals a complex situation: dusk BS oc-  
 774 cur indeed at higher altitudes at intermediate SZAs above  $45^\circ$ , but the situation reverses  
 775 when reaching the terminator region, with overall a noisy profile that makes it difficult  
 776 to conclude on a possible global dusk dawn asymmetry of the BS that could be related  
 777 to the  $\theta_{bn}$  influence. T-tests and partial correlation analysis confirm the absence of sig-  
 778 nificant influence of local time at a global scale (with associated risks of non partial cor-  
 779 relation above 5%). Moreover, the MEX dataset shows a reversed situation, with dawn  
 780 BS occurring at further altitudes for intermediate SZAs until the terminator where the  
 781 situation is reversed with dusk shocks at further altitudes than dawn shocks.

782 The distribution of the  $\theta_{bn}$  angle values encountered in the MAVEN dataset is not  
 783 Gaussian, with significantly more perpendicular BS than parallel ones: 80% of the cross-  
 784 ings occurred at  $\theta_{bn}$  values above  $60^\circ$ . It should be pointed out that this inhomogeneous  
 785 sampling is not the result of a bias of detection of parallel BS being more difficult to iden-  
 786 tify from the data visual analysis: this  $\theta_{bn}$  distribution is very similar to the distribu-  
 787 tion of the  $\theta_{bn}$  values expected from the crossings by the MAVEN spacecraft with the

788 modeled conic shape published by Edberg et al. (2008) - and included in the 3DView webtool  
 789 <http://3dview.irap.omp.eu/> - during the same period as our dataset. Note that updated  
 790 crossing lists would not change the situation with more perpendicular than parallel BS  
 791 encountered due to the spacecraft trajectory until 2021.

792 Parallel BS are usually more difficult to identify than perpendicular BS where the  
 793 transition is more abrupt. In the case of perpendicular BS, one usually has a 'clean' so-  
 794 lar wind upstream with an absence of particles reflected. On the contrary, the transi-  
 795 tion at almost parallel BS is disturbed and wide, with a foreshock consisting of ions go-  
 796 ing up the solar wind (Meziane et al., 2017) and with different transients whose signa-  
 797 tures may resemble those of a BS, including hot flow anomalies found at Mars (Collinson  
 798 et al., 2015). The extension of the foreshock and the presence of transients could thus  
 799 have resulted in an overestimation of the BS distance. However, our analysis shows that,  
 800 on the contrary, perpendicular BS are located at higher altitudes than parallel ones.

801 A last possible uncertainty on the influence of the  $\theta_{bn}$  angle on the BS location could  
 802 be from the conic section assumption that is made in the derivation of the terminator  
 803 distance  $R_{TD}$  in this study. In principle, if the eccentricity chosen was not appropriate  
 804 with our dataset, extrapolating from the BS crossing location to the terminator could  
 805 lead to an overestimation or underestimation of the  $R_{TD}$  value. However, this method  
 806 is rather robust with respect to our conclusions. Let us choose only a subset of our dataset,  
 807 i.e. the list published by XF17 instead of a combination with the list by Gruesbeck et  
 808 al. (2018), to keep consistent with the choice made of the conic parameters given by XF17.  
 809 In this case the correlation of the sine of  $\theta_{bn}$  with  $R_{TD}$  is unchanged (the Pearson cor-  
 810 relation coefficient is changed by only 0.01 with negligible p-value). If we keep the same  
 811 dataset but use other conic parameters by Edberg et al. (2008) - i.e.  $(X_0, L, e) = (0.55, 2.10, 1.05)$   
 812 instead of  $(0.42, 2.30, 0.87)$  for XF17 - again the correlation factor is changed by only 0.01  
 813 with negligible p-value. The choice of the conic parameters thus does not affect our ob-  
 814 servation of the  $\theta_{bn}$  influence.

815 Finally, alternative explanations were provided by several authors to explain the  
 816 presence of BS expansions. Thomas and Winske (1990) developed two dimensional hy-  
 817 brid simulations of planetary BS to study the foreshock ion population. They mentioned  
 818 a similar asymmetry with the BS being closer on the quasi-parallel side than on the quasi-  
 819 perpendicular side, and considered this was a kinetic behavior, since the asymmetry de-

820 creased during the simulations while the BS radius increased compared to the gyroradius.  
 821 At Earth, magnetopause and BS expansions were also linked to radial (low cone  
 822 angle) IMF configurations by several authors (e.g. Suvorova et al. (2010) or Wang et al.  
 823 (2020)), possibly due to the dependence of the magnetosonic wave velocity on the  $\theta_{bn}$   
 824 angle. This is however not observed in our Martian dataset where the cone angle has no  
 825 significant influence, with even slightly smaller BS  $R_{TD}$  values for radial IMF orienta-  
 826 tions.

827 The analysis of the MAVEN dataset thus shows that quasi-perpendicular BS oc-  
 828 curs at higher altitudes than quasi-parallel ones, independently from the influence of other  
 829 possible drivers. However, the exact origin of this influence is unclear. The common ex-  
 830 planation of the fast magnetosonic wave speed dependance on the  $\theta_{bn}$  angle of the IMF,  
 831 suggested by a number of authors in the Earth and Venusian BS literature based essen-  
 832 tially on geometric arguments, does not appear convincing in our quantitative analysis  
 833 of the MAVEN data.

### 834 **3.5 The relative importance of the drivers**

835 Understanding the dynamics of the plasma boundaries includes understanding both  
 836 the relationship with individual drivers (as can be performed through correlations, or  
 837 partial correlations to investigate biases) and the relative importance of each driver. The  
 838 results discussed in Sections 3.1, 3.2, 3.3, suggested a ranking of the parameters of in-  
 839 fluence for the Martian BS location, but the methods used cannot appropriately quan-  
 840 tify them. We use in this section two methods (described in Section 2.2), called Akaike  
 841 information criterion and Lasso that are model selection methods that enable ranking.

#### 842 ***3.5.1 The Akaike Information Criterion***

843 The Akaike information criterion (AIC; see Appendix A) is a method based on in-  
 844 formation theory that is dedicated to perform model selection (Akaike, 1974). AIC es-  
 845 timates, among several models fitting an observed dataset, the amount of information  
 846 lost by each model to reproduce the data regularized by the dimension of the model. The  
 847 model with minimum AIC value is considered as the best candidate (with no judgment  
 848 on its absolute quality), and only the relative AIC difference value among two models  
 849 is meaningful to compare their relative likelihood.

**Table 1.** Akaike Information Criterion results for MAVEN and MEX linear regression models of the Martian BS terminator distance

Variable removed from model	MAVEN AIC	MEX AIC
No variable removed	36405	60072
IMF intensity	36408 (9)	
$\cos(\text{clockangle})$	36410 (8)	
MSE pole vs equator	36411 (7)	
$\cos(\phi_{MSO})$	36419 (6)	60105 (4)
SW dynamic pressure	36461 (4)	60171 (3)
Angular distance	36423 (5)	60174 (2)
Magnetosonic mach	36626 (3)	
$\sin(\theta_{bn})$	36661 (2)	
EUV	37049 (1)	60620 (1)

The ranking number of each driver suggested by AIC analysis is added between parenthesis for MAVEN and MEX

850 We performed AIC calculations with a dedicated R code, assuming either a linear  
851 dependence of the Martian BS terminator distance  $R_{TD}$  with respect to several param-  
852 eters ( $RTD = a + \sum_i X_i \cdot b_i$ ), or a power law dependence ( $RTD = a \prod_i X_i^{b_i}$ ). Table 1  
853 shows the result of an AIC approach, where the AIC is calculated after each parameter  
854 of influence is removed one after the other in decreasing importance order (backward re-  
855 gression). AIC thus compares several models, each model including all drivers but one.  
856 For example, if EUV is removed from the MAVEN model including initially all drivers,  
857 the AIC value given is 37049, which is larger than if IMF intensity is instead removed  
858 from the initial model (AIC value of 36408): removing EUV leads to a model with more  
859 information loss compared to measurements, it is thus ranked as a more important driver  
860 than IMF intensity.

861 The AIC approach applied to linear regression models - see below for power law  
862 models - for MAVEN and MEX thus confirms the main conclusions brought in the pre-  
863 vious sections, with EUV fluxes and magnetosonic mach number (for MAVEN) being  
864 the major drivers whose removal imply very strong loss of information, with the  $\theta_{bn}$  an-

865 gle of the IMF on a similar level as well, before crustal fields (angular distance to or  $\phi_{MSO}$   
 866 MSO longitude of the strongest crustal source region, or even crustal magnetic field pres-  
 867 sure when included in AIC) and solar wind dynamic pressure at a comparable level. Re-  
 868 garding these two, the ranking differs between MAVEN and MEX, with angular distance  
 869 ranked above solar wind dynamic pressure for MEX but after it in the MAVEN case (thus  
 870 confirming that lower direct correlations do not necessarily mean reduced influence, in  
 871 particular due to complex cross-correlations).  $\phi_{MSO}$  appears less than or as influent as  
 872 the angular distance depending on the mission. The IMF intensity and clock angle are  
 873 also parameters of influence whose removal lead to information loss, but less than other  
 874 parameters. This is also the case for the equator to pole asymmetry in the MSE frame  
 875 discussed in Section 3.3, estimated by the absolute value of the cosine of the "clock an-  
 876 gle" shown in Figure 6, i.e. the angle of the BS crossing from the IMF vector in the ter-  
 877 minator plane.

878 Moreover, the  $\theta_{bv}$  and  $\theta_{vn}$  parameters removal do not imply information loss (com-  
 879 pared to a simple constant) and are thus considered not significant by AIC analysis.

880 The use of power law functional forms instead of linear relationships leads only to  
 881 slight ranking changes for the MAVEN least influent parameters ( $\theta_{vn}$  and  $\theta_{bv}$ ). One can  
 882 note that linear or power law dependence laws are widely considered for EUV, magne-  
 883 tosonic mach number or crustal field pressure, but it is difficult to anticipate functional  
 884 forms for the angular characteristics of the IMF, however the robustness of the AIC re-  
 885 sults for both linear and power law models and their coherence with more direct previ-  
 886 ous analysis suggests the ranking proposed is consistent. Moreover, at first order most  
 887 of the relationships can be considered as linear (or power laws) which makes the linear  
 888 model a weak assumption.

### 889 **3.5.2 The LASSO regularization**

890 As a complementary approach to the AIC results, we performed an analysis with  
 891 the Least Absolute Shrinkage Selection Operator method (LASSO; see a detailed descrip-  
 892 tion in Appendix B) which is another model selection approach. LASSO is a commonly  
 893 used supervised regularization method (Tibshirani, 1996), where a penalty term allows  
 894 the identification of the significance of predictors in a regression model, with possible cross  
 895 correlations. Compared to classical regression, the coefficients of each variable are con-

896 strained by the sum of the modulus or absolute values of the coefficients being as small  
 897 as possible, the sum of the coefficients being multiplied by a regularization parameter  
 898  $\lambda$ . When increasing the regularization parameter  $\lambda$  from zero (i.e. LASSO switched off  
 899 or the classical multivariate regression), the weight of the sum of the coefficients in the  
 900 optimization process becomes eventually strong, which leads the algorithm to eventu-  
 901 ally set to zeros some of the coefficients, thus selecting the most significant variables only.  
 902 For large  $\lambda$  values, more coefficients of the regression are set to zero, thus removing the  
 903 associated predictors from the model selected.

904 We used the `glmnet` R package to compute the LASSO procedure. The variables  
 905 introduced in the linear regression model are the same as for the AIC procedure, and  
 906 were at first standardized ( $x_{i_{std}} = (x_i - m_i)/\sigma_i$  with  $m_i$  and  $\sigma_i$  mean and standard de-  
 907 viations of the variables  $x_i$ ) to remove the specific dynamics of each predictor (e.g. cosines  
 908 range from  $-1$  to  $1$  while the MEX EUV ranges from  $0$  to  $100$ ) and thus allow to make  
 909 the regression coefficients comparable to each other with the same mean ( $0$ ) and stan-  
 910 dard deviation ( $1$ ) values for each driver distribution. The definition of the training set  
 911 to learn from and of the test set and the determination of the best regularization  $\lambda$  value  
 912 is obtained from a cross-validation procedure with 10-folds to avoid overfitting.

913 Figure 8 provides the results of the LASSO procedure for both MAVEN and MEX  
 914 Martian BS crossings datasets. The figure shows the coefficients associated with the vari-  
 915 ables included in the regression to predict the extrapolated terminator altitude of the  
 916 BS  $R_{TD}$ , as a function of the penalty term  $\lambda$ . Low  $\lambda$  values in the figure correspond a  
 917 close to classic regression procedure, while large  $\lambda$  values correspond to a strong regu-  
 918 larization in the algorithm to select the most important predictors and put the coeffi-  
 919 cient of the least important to  $0$ . Positive and negative coefficients correspond to the sign  
 920 of the slope of the  $R_{TD}$  vs the predictors, with e.g. the BS location increasing for large  
 921 EUV fluxes (positive coefficient) but decreasing for larger Mms (negative coefficient).

922 The MEX results show that EUV displays for all  $\lambda$  values the largest coefficient  
 923 among the four variables included (i.e. EUV, SW dynamic pressure, angular distance  
 924 and the cosine of  $\phi_{MSO}$ ). The SW dynamic pressure and angular distance coefficients  
 925 are close with no penalty (slightly larger for angular distance), while the SW dynamic  
 926 pressure coefficient drops more rapidly than the one for angular distance with increas-  
 927 ing penalties, reaching zero at large penalties. The coefficient for  $\phi_{MSO}$  the longitude of

928 the strongest crustal source region is the fourth coefficient in absolute value, and reaches  
929 0 at large penalty.

930 The MAVEN curves, which include the IMF intensity and orientation parameters,  
931 show first that EUV and magnetosonic mach number are always the largest coefficients.  
932 Then the largest coefficients are those of the sine of  $\theta_{bn}$ , and then of solar wind dynamic  
933 pressure, which do not reach zero values at high penalty. The angular distance coeffi-  
934 cient is also significant at low penalty, before the cosine of  $\phi_{MSO}$ . The lowest coefficients  
935 are then those of the clock angle and MSE pole vs equator parameter. The lowest co-  
936 efficients, that are non zero with no penalty but are set to zero rapidly by the penalty  
937 term are the cosines of the IMF orientation angles  $\theta_{bv}$  (cone angle) and  $\theta_{vn}$ , and to a lesser  
938 extent the IMF intensity.

939 Table 2 provides the final coefficients corresponding to the best model for MAVEN  
940 and MEX  $R_{TD}$  predictors. The best model corresponds to small penalty terms (respec-  
941 tively 1.2 and 2.4 for MEX and MAVEN), confirming the significance of most of the vari-  
942 ables included in the model according to LASSO. However, if the cross validation pro-  
943 cedure leads to non zero coefficients for the least significant variables ( $\theta_{bv}$ ,  $\theta_{vn}$  and IMF  
944 intensity), several of the folds lead to zero values of these coefficients (mostly for  $\theta_{bv}$ ,  $\theta_{vn}$ ),  
945 making their significance weak or inexistent according to LASSO. One can note that us-  
946 ing an initial power law functional form (linearized with a logarithm) for the LASSO re-  
947 gression instead of an initial linear form leads to similar results: this leads to different  
948 coefficients but the relative values are very close to the linear form conclusions, as well  
949 as the evolution of the coefficients as a function of the penalty term.

950 Overall, the LASSO results are consistent with the previous results based on par-  
951 tial correlations and AIC approach. The EUV and magnetosonic mach are the major drivers  
952 of the BS location, before parallel vs perpendicular BS ( $\theta_{bn}$  angle), and then solar wind  
953 dynamic pressure or crustal fields (depending on the dataset). The IMF intensity and  
954 orientation angles (mostly the clock angle and MSE pole vs equator) are predictors of  
955 non null importance (except probably  $\theta_{bv}$  and  $\theta_{vn}$ ) but are weak.

956 We shall remind that the use of the LASSO approach does not aim at providing  
957 precise functional forms of the Martian BS location variability with respect to its drivers,  
958 that needs a theoretical understanding of the influence of each predictor, but to com-

**Table 2.** Lasso regularization regression results for the MAVEN and MEX shock terminator altitude

Variable	MAVEN Lasso coefficient	MEX Lasso coefficient
Constant	5155.5	5209.3
$\cos(\theta_{bv})$	-2.7 (11)	
$\cos(\theta_{vn})$	-10.3 (10)	
IMF intensity	-47.3 (7)	
$\cos(\text{clock angle})$	30.7 (9)	
MSE pole vs equator	33.9 (8)	
$\cos(\phi_{MSO})$	49.0 (6)	73.0 (4)
SW dynamic pressure	-122.0 (4)	-120.3 (3)
Angular distance	-59.4 (5)	-126.9 (2)
Magnetosonic mach	-293.7 (2)	
$\sin(\theta_{bn})$	207.9 (3)	
EUV	344.2 (1)	291.4(1)

The same ordering as in Table 1 was used. The ranking number of each driver suggested by LASSO analysis is added between parenthesis for MAVEN and MEX

959 pare the relative importance of the various possible drivers by assuming at first order  
960 a linear regression model (or a power law model).

#### 961 4 Discussion

962 Based on the previous analyses - direct analysis of the drivers, as well as partial  
963 correlations or model selection methods such as AIC or LASSO methods -, the statis-  
964 tical study of the Martian BS crossings datasets by MAVEN and MEX show that the  
965 terminator distance of the BS increases:

- 966 • when the magnetosonic mach number decreases ( $1^{st}$  order importance): the BS  
967 is a fast magnetosonic standing wave induced by the supersonic flow encounter-  
968 ing the ionized Mars obstacle, which propagates with a velocity determined by the  
969 magnetosonic Mach number; the magnetosonic Mach drives not only the jump con-

970 ditions at the shock through Rankine-Hugoniot relations, but also the shape of  
971 the BS, in particular the flaring of the BS with a shock cone inversely proportional  
972 to the Mach number according MHD modeling, which modifies the cross section  
973 of the BS and its terminator distance

- 974 • for enhanced extreme ultraviolet fluxes (1<sup>st</sup> order importance): the EUV fluxes  
975 increase the ionization rate of both the Martian collisional atmosphere and its ex-  
976 osphere, which adds mass to the solar wind flow through pickup of ions and thus  
977 slows down the solar wind, then creating a larger apparent obstacle that pushes  
978 the BS further; the EUV fluxes also heat the atmosphere, thus increasing the iono-  
979 spheric scale height and expanding the exosphere; this influence of EUV happens  
980 at various timescales, from intense brutal solar flares to seasonal variations induced  
981 by the eccentricity of Mars' orbit and depending on the hemisphere
- 982 • in the case of perpendicular BS: our statistical analysis of the MAVEN data shows  
983 the  $\theta_{bn}$  angle between the IMF and the normal to the BS is a significant driver of  
984 the Martian BS, with several possible reasons but none being conclusive; the most  
985 probable physical process is the expected dependance of the anisotropic wave ve-  
986 locity of fast mode magnetosonic waves on the  $\theta_{bn}$  angle that is often mentioned  
987 in the Earth's and Venusian BS literature based on MHD modeling (but not on  
988 data analysis); however, the anisotropy of the wave speed is expected to be sig-  
989 nificant mostly for low mach numbers and in the tail, i.e. when and where the BS  
990 cross section is maximum, as the travel time of the wave; moreover, our data anal-  
991 ysis suggests that the observed influence of  $\theta_{bn}$  on the BS is not associated with  
992 a significant anistropy of the wave speed
- 993 • with crustal magnetic fields (2<sup>nd</sup> order importance) through two ways: though an  
994 influence at the spacecraft location (through the local crustal field pressure or the  
995 angular distance from the strongest crustal source region, with a large extent), and  
996 through an amplification of this influence all the more than the strongest crustal  
997 source region center is located close to noon; the crustal fields may impact through  
998 several processes on the BS: they first add internal magnetic pressure, increasing  
999 the apparent size of the obstacle, then they modify and induce currents that prop-  
1000 agate through the induced magnetosphere, interacting with the magnetosheath  
1001 plasma and the draping of the IMF around the planet, which in the end pushes  
1002 further the BS ; moreover, when the strongest crustal source region is located close

1003 to noon (compared to midnight), the travel time for the magnetosonic wave is re-  
 1004 duced allowing the BS standing wave to form further upstream the solar wind flow;  
 1005 finally, G22 revealed the existence of a strong coupling between the crustal field  
 1006 influence on the BS and the ionosphere, through a strong correlation with the To-  
 1007 tal Electronic Content that is a tracer of the ionospheric variability (due to solar  
 1008 irradiance that is the major ionization source of the sunlit ionosphere), but also  
 1009 for the thermosphere-ionosphere coupling (Sánchez-Cano et al. (2018)); a part of  
 1010 the crustal field influence on the BS is thus probably related to the increased life-  
 1011 time (and thus density) of plasma trapped on closed field lines in the crustal mag-  
 1012 netic field regions where they are protected from the loss mechanisms induced by  
 1013 the solar wind interaction, then increasing the local internal plasma pressure and  
 1014 the size of the apparent obstacle to the supersonic solar wind.

- 1015 • with reduced solar wind dynamic pressure ( $2^{nd}$  order importance): the solar wind  
 1016 dynamic pressure is widely known as the major driver of Earth's bow shock, and  
 1017 also plays a significant role at Mars; an increased steady incident pressure indeed  
 1018 compresses the whole induced magnetosphere, and thus pushes the BS closer to  
 1019 the planet, while a variable pressure can also induce more complex phenomena such  
 1020 as transients with Hot Flow Anomalies as observed at Earth (Otto and Zhang (2021))
- 1021 • other variables possibly influence the MAVEN BS location, such as the IMF in-  
 1022 tensity, clock angle, or other IMF orientation angles that could generate asymme-  
 1023 tries of the BS surface; large cone angles may e.g. in principle be related to increased  
 1024  $\vec{V} \times \vec{B}$  electric fields that accelerate pickup ions and increase the mass loading and  
 1025 thus the size of the obstacle to the solar wind; low clock angles can also be asso-  
 1026 ciated to a preferential direction of the electric field depending on the IMF direc-  
 1027 tion, thus inducing asymmetric BS locations ; moreover, equator vs pole asym-  
 1028 metries in the MSE frame as identified at Venus can also be related to mass load-  
 1029 ing effects or to an anisotropic wave velocity ((Alexander et al., 1986), (Jarvinen  
 1030 et al., 2013)); however, the correlations between these possible angular drivers and  
 1031 the Martian BS location are either non significant (e.g. larger shock  $R_{TD}$  values  
 1032 along the convection electric field), or significantly reduced after controlling for  
 1033 the  $1^{st}$  order importance drivers and for the  $\theta_{bn}$  influence with using partial cor-  
 1034 relations.

1035 We showed in the previous sections how direct simple analysis can lead to an un-  
1036 derestimation or an overestimation of the influence of minor drivers when these are cross  
1037 correlated with major drivers. The use of specific methods such as partial correlations,  
1038 AIC or LASSO, allows for an efficient disentangling of the various drivers at play. To  
1039 check the efficiency of these methods, we performed a simple test: we kept for MAVEN  
1040 the real drivers datasets (thus keeping the existing cross correlations), but artificially mod-  
1041 ified the real  $R_{TD}$  dataset with the following procedure : we first perform a regression  
1042 of the  $R_{TD}$  dataset with respect to the various possible drivers and identify the slope value  
1043 associated with a specific driver we want to test (e.g. the "clock angle" of the MSE pole  
1044 vs equator influence) ; then we modified the specific influence of this specific driver, by  
1045 removing (little influence dataset) from the real  $R_{TD}$  dataset, adding ten times (strong  
1046 influence dataset), or adding twice with also noise (noisy moderate influence dataset) the  
1047 slope associated with this specific driver. When applying the partial correlations, AIC  
1048 and LASSO methods to these three artificial  $R_{TD}$  datasets (little influence, strong in-  
1049 fluence, noisy moderate influence), one gets results that are coherent with the expecta-  
1050 tions: all methods show an increased and coherent ranking of the specific driver for an  
1051 increased influence of this driver (i.e. for the strong influence dataset compared to the  
1052 noisy moderate and little influence datasets), while the other drivers influence keeps un-  
1053 changed. This simple test thus confirms these methods are able to identify any signif-  
1054 icant driver that impacts the RTD dataset, i.e. any driver that shows a recurrent pat-  
1055 tern, whatever its nature and its reference coordinate system (in the geographical coor-  
1056 dinate system for crustal fields, in the MSO system, in the IMF related coordinate sys-  
1057 tem etc.). These methods are more powerful than direct analysis regarding the detec-  
1058 tion of minor drivers whose influence may be hidden / underestimated / overestimated  
1059 based on simple direct analysis due to cross correlations with major drivers.

1060 Parametrizing in details the BS location as a function of its physical drivers is be-  
1061 yond the scope of this paper since this needs a detailed theoretical understanding of the  
1062 response of the BS to each driver and to a combination of these drivers that may be inter-  
1063 related as demonstrated above. However, previous authors tried to infer functional forms  
1064 of the influence of the main drivers on the plasma boundaries locations, either from em-  
1065 pirical relations or theoretical developments, and it may thus be interesting to compare  
1066 some of these results with our analysis.

1067 One can in particular compare the LASSO regression results (Table 2) that pro-  
 1068 vide coefficients for each driver to functional forms provided by previous studies. In or-  
 1069 der to compare the LASSO coefficients ( $b_{LASSO_i}$ ) with direct slopes of classic regressions  
 1070 ( $b_i$  in 2.2), one simply needs to divide the LASSO coefficient of a specific variable by the  
 1071 standard deviation  $\sigma_i$  of the variable (or of its logarithm if a power law function is con-  
 1072 sidered) since the variables are standardized in the LASSO approach:  $b_i = b_{LASSO_i}/\sigma_i$ .

1073 Regarding the SW dynamic pressure influence, Spreiter et al. (1966) used a  $P_{SW}^{-1/6}$   
 1074 SW dynamic pressure dependence for the nose distance of the Earth’s magnetopause and  
 1075 BS, later used at different planets including Mars (Verigin et al., 1993). Crider (2004)  
 1076 suggested a SW dynamic pressure influence on the Martian MPB terminator distance  
 1077 with a softer slope than  $-1/6$ :  $P_{SW}^{-0.05}$ . In comparison, the LASSO regularization gives  
 1078 power law index values of  $-0.0596/-0.0268$  for MAVEN/ MEX datasets when using  
 1079 a power law functional form ( $RTD = a \prod_i X_i^{b_i}$ ), which is close to the Crider (2004) value  
 1080 of  $-0.05$  based on MGS data, or to the MEX only values of  $-0.02/-0.03$  by BH16. Re-  
 1081 cently, Nemec et al. (2020) compared the influence of several drivers on the MAVEN BS  
 1082 crossings (EUV, SW dynamic pressure and crustal field intensity). They suggested a non-  
 1083 negligible but small influence of crustal fields, but only local crustal fields were consid-  
 1084 ered, and the magnetosonic mach number or IMF orientation parameters were not in-  
 1085 vestigated, however the power law index suggested  $-0.06$  in their study for the SW dy-  
 1086 namic pressure is also comparable to the LASSO conclusions.

1087 The Mach number was also introduced early, with e.g. Verigin et al. (2003) who  
 1088 used complex analytical equations for the mach number dependence based on gas dy-  
 1089 namics approaches. At Mars, Edberg et al. (2010) suggested a linear relation between  
 1090 the terminator distance of the Martian BS with the  $Mms$  (i.e.  $RTD = -0.1Mms + 3.3$   
 1091 in Martian radii) based on a proxy of the IMF at Mars in the absence of direct measure-  
 1092 ment by MEX. The MAVEN LASSO coefficients for a linear model ( $RTD = a + \sum_i X_i \cdot$   
 1093  $b_i$ ) lead to a slope for  $Mms$  of  $-0.06$  that is of the same order as the  $-0.1$  slope by Edberg  
 1094 et al. (2010).

1095 The power law index values derived from the LASSO regularization for the angu-  
 1096 lar distance to the strongest crustal source region are of  $-0.0280/-0.0474$  for MAVEN/MEX,  
 1097 with a steeper slope for MEX, that is even stronger than the slope for the SW dynamic  
 1098 pressure ( $-0.0268$ ) while it is the contrary for MAVEN as discussed in the previous sec-

1099 tions. If we consider a purely local influence of the crustal fields by taking the local crustal  
1100 field pressure instead of the angular distance (or equivalently crustal field pressures av-  
1101 eraged over large angular distance), the power law index associated is reduced by a fac-  
1102 tor of 4 and thus becomes smaller (or much smaller for MAVEN) than the  $P_{SW}$  power  
1103 law index. This is consistent with the Nemeč et al. (2020) results who only considered  
1104 local crustal field pressures with a power law index 3 to 4 times smaller than the value  
1105 for the SW dynamic pressure.

1106 Our results, when compared with a similar approach, are thus consistent with pre-  
1107 vious Martian studies that mostly focused on individual or few main parameters of in-  
1108 fluence at a time and for a specific mission. However, it is clear no simple empirical law  
1109 can account for the whole dynamics of the BS boundary, due to the complex interplay  
1110 of the physical processes at work that can eventually not be represented by combined  
1111 linear or power law functions (in particular the IMF orientation angles such as  $\theta_{bn}$ ), and  
1112 may be strongly cross-correlated as shown above. Each driver also possesses its own timescales,  
1113 with e.g. EUV impacting in general at larger timescales than the solar wind dynamic  
1114 pressure or magnetosonic mach number. Besides, our limited time resolution of the char-  
1115 acteristics of the highly dynamic SW could lead to a slight underestimation of their in-  
1116 fluence on the BS location.

1117 Better understanding the BS dynamics and in particular how internal stimuli prop-  
1118 agate through the Martian induced magnetosphere until the BS would need a full 3-dimensional  
1119 modeling approach (as suggested by the results of Gruesbeck et al. (2018)), with ded-  
1120 icated MHD or hybrid modeling including the complex crustal field topology and tem-  
1121 poral dynamics. Recently Romanelli et al. (2018) investigated the response of the Mar-  
1122 tian BS and of the MPB to variable conditions of the solar wind with the global three-  
1123 dimensional multispecies parallelized hybrid code LatHyS (Modolo et al., 2016). They  
1124 considered three stationary simulations with various conditions of solar wind density, mag-  
1125 netosonic Mach number and velocity, while controlling for constant EUV and IMF ori-  
1126 entation conditions, and analyzed the consecutive BS location variability to compare with  
1127 the extreme conditions encountered during the September 2019 events (see Lee et al. (2018)).  
1128 Li et al. (2020) also developed a three-dimensional four species multi-fluid magnetohy-  
1129 drodynamic (MHD) model to simulate the solar wind global interaction with Mars, where  
1130 they added or removed an ideal dipole-like local crustal field model to study the influ-  
1131 ence of crustal fields on the interaction and on the plasma boundaries. Wang et al. (2020)

1132 also used 3D MHD modeling simulations to investigate the dynamics of the Martian BS,  
1133 and proposed a parametric model including seven parameters, suggesting that the *Mms*  
1134 and SW dynamic pressure were the main drivers of the BS location, but they did not  
1135 include neither EUV nor crustal fields.

1136 It would also be interesting to further compare with a consistent method the dy-  
1137 namics of the BS with the dynamics of the inner plasma boundaries (Magnetic Pile-Up  
1138 Boundary or Induced Magnetosphere Boundary, Ion Composition Boundary, PhotoElec-  
1139 tron Boundary...) since the dynamics of a boundary may impact another boundary, such  
1140 as at Earth between the magnetopause and the BS (Wang et al., 2016) or at Mars be-  
1141 tween the Induced Magnetosphere Boundary and the BS (Ramstad et al., 2017).

1142 In parallel to modeling approaches, we plan to use in the future machine learning  
1143 and artificial intelligence techniques to provide automatic catalogs of BS crossings for  
1144 the MAVEN and MEX missions and thus increase our dataset to reduce the influence  
1145 of cross-correlations, and eventually identify complex nonlinear relationships between the  
1146 BS location (or other plasma boundaries) and external/internal drivers. These techniques  
1147 are indeed mature and proved efficient in space physics to detect plasma phenomena (see  
1148 e.g. Karimabadi et al. (2009), Nguyen et al. (2019)) or to identify parameters of influ-  
1149 ence (see e.g. Al-Ghraibah, A. et al. (2015) or Benvenuto et al. (2018)).

## 1150 5 Conclusions

1151 The recent studies of the Martian environment, thanks in particular to the Mars  
1152 Express and Mars Atmosphere Volatile EvolutionN missions, underline the complexity of  
1153 the Martian interaction with the incident solar wind, that shapes the plasma boundaries.  
1154 The bow shock of the planet is known to depend on extreme ultraviolet fluxes and mag-  
1155 netosonic mach number, while the influence of other possible drivers is less constrained  
1156 or unknown such as crustal magnetic fields or the Interplanetary Magnetic Field inten-  
1157 sity and orientation.

1158 In this paper we analyzed the influence of a number of possible internal and ex-  
1159 ternal drivers of the shock location, based on the first time on two missions (MAVEN  
1160 and MEX). We used consistent methods that allow to compare both missions datasets,  
1161 as well as to take into account the cross correlations between the drivers that can mod-  
1162 ify the interpretation of the data.

1163 We first analyzed the direct influence of the possible drivers of the shock based on  
1164 linear correlation coefficients or absolute variations of the shock location. Then, we showed  
1165 that many of the possible drivers are correlated to each other due to their nature and/or  
1166 to the trajectory of spacecraft. We used a partial correlation approach to investigate in  
1167 details the impact of these cross-correlations on the interpretation of the MAVEN and  
1168 MEX shock crossings datasets. This approach appears crucial to investigate the influ-  
1169 ence of second order drivers of the shock that may be linked to each other or to stronger  
1170 drivers. Finally, we used two known different model selection methods, called Akaike In-  
1171 formation Criterion (AIC, see Appendix A) and Least Absolute Shrinkage Selection Op-  
1172 erator (LASSO, see Appendix B) to compare the relative importance of the shock drivers.  
1173 These methods - partial correlations, AIC, LASSO - are able to identify any significant  
1174 driver that impacts the extrapolated terminator distance of the shock, i.e. any driver that  
1175 shows a recurrent pattern, whatever its nature and its reference coordinate system (in  
1176 the geographical coordinate system for crustal fields, in the MSO system, in the IMF re-  
1177 lated coordinate system etc.). These methods are more powerful than direct analysis re-  
1178 garding the detection of minor drivers whose influence may be hidden / underestimated  
1179 / overestimated based on simple direct analysis due to cross correlations with major drivers.

1180 Based on our analysis, we showed that the major drivers of the Martian shock lo-  
1181 cation are extreme ultraviolet fluxes and solar wind magnetosonic Mach number, while  
1182 crustal fields (through various parameters) and solar wind dynamic pressure are signif-  
1183 icant but play a secondary role of similar importance. The results for the magnetosonic  
1184 mach number and for the IMF related parameters are based only on the MAVEN dataset,  
1185 due to the absence of magnetic field for MEX. The analysis of the MAVEN data also shows  
1186 perpendicular shocks are located at significantly higher distances than parallel shocks,  
1187 but no conclusive explanation was reached despite a number of possible reasons stud-  
1188 ied, including an anisotropy fast magnetosonic wave velocity depending on the  $\theta_{bn}$  an-  
1189 gles that is mentioned in the Earth's and Venusian bow shock literature (Russell et al.  
1190 (1988), Peredo et al. (1995), Chai et al. (2015)). Other variables possibly influence the  
1191 shock location, such as the IMF intensity, clock angle, or other IMF orientation angles  
1192 (cone angle  $\theta_{vb}$ ,  $\theta_{vn}$ ) that could generate asymmetries of the shock surface, with e.g. a  
1193 possible close to equator vs pole asymmetry in the Mars Sun Electric field frame as iden-  
1194 tified at Venus and probably related to mass loading effects ((Alexander et al., 1986),  
1195 (Jarvinen et al., 2013)). However, the correlations between these last possible drivers and

1196 the Martian shock location are significantly reduced after controlling for cross correla-  
 1197 tions with the main drivers of the shock including the  $\theta_{bn}$  angle influence. Moreover, no  
 1198 further shocks were observed along the direction of the convective electric field, contrary  
 1199 to suggestions by previous authors based on smaller datasets or proxy methods.

1200 Providing an analytical proxy of the shock location that accounts precisely for the  
 1201 combined influence of its drivers appears unrealistic given the complex interplay of the  
 1202 internal and external physical processes at work, each of them possessing its own timescales.  
 1203 Better understanding the plasma boundaries dynamics and in particular how internal  
 1204 stimuli propagate through the Martian induced magnetosphere until the bow shock will  
 1205 need a modeling approach including the complex crustal field topology and temporal dy-  
 1206 namics, as well as a comparison of the dynamics of the various boundaries.

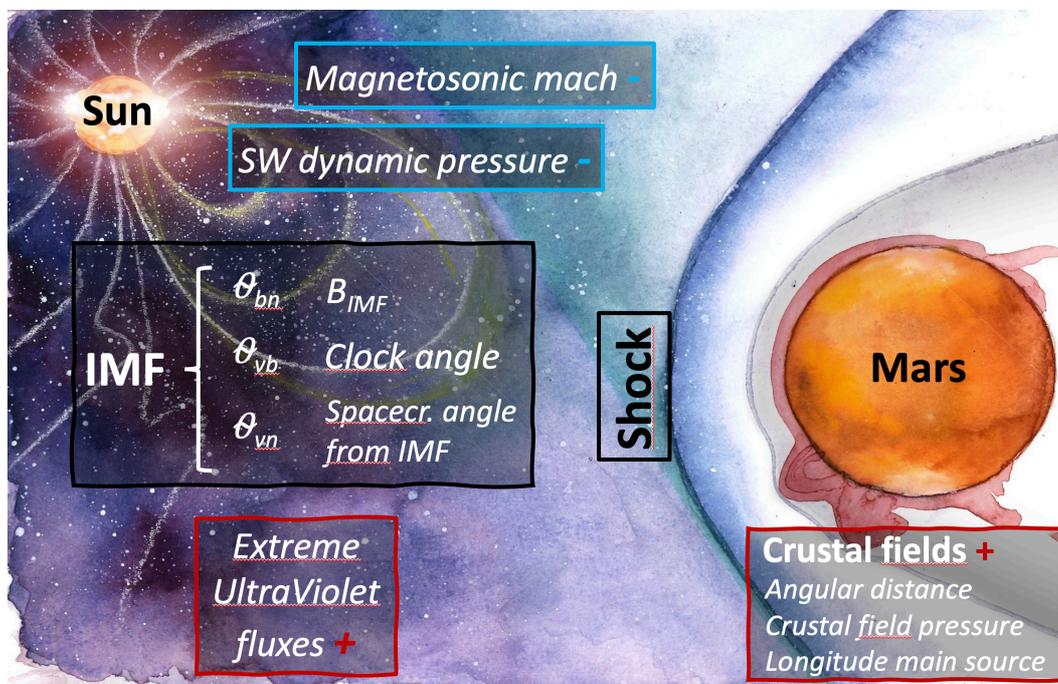
1207 In a future work we plan to investigate the use of machine learning and artificial  
 1208 intelligence techniques that are efficient to provide automatic catalogs of events (e.g. plasma  
 1209 boundaries) and eventually identify complex nonlinear relationships between the bound-  
 1210 aries location and external/internal drivers. These techniques are indeed mature and proved  
 1211 efficient in space physics to detect plasma phenomena or to identify parameters of in-  
 1212 fluence.

## 1213 **Appendix A Akaike Information Criterion**

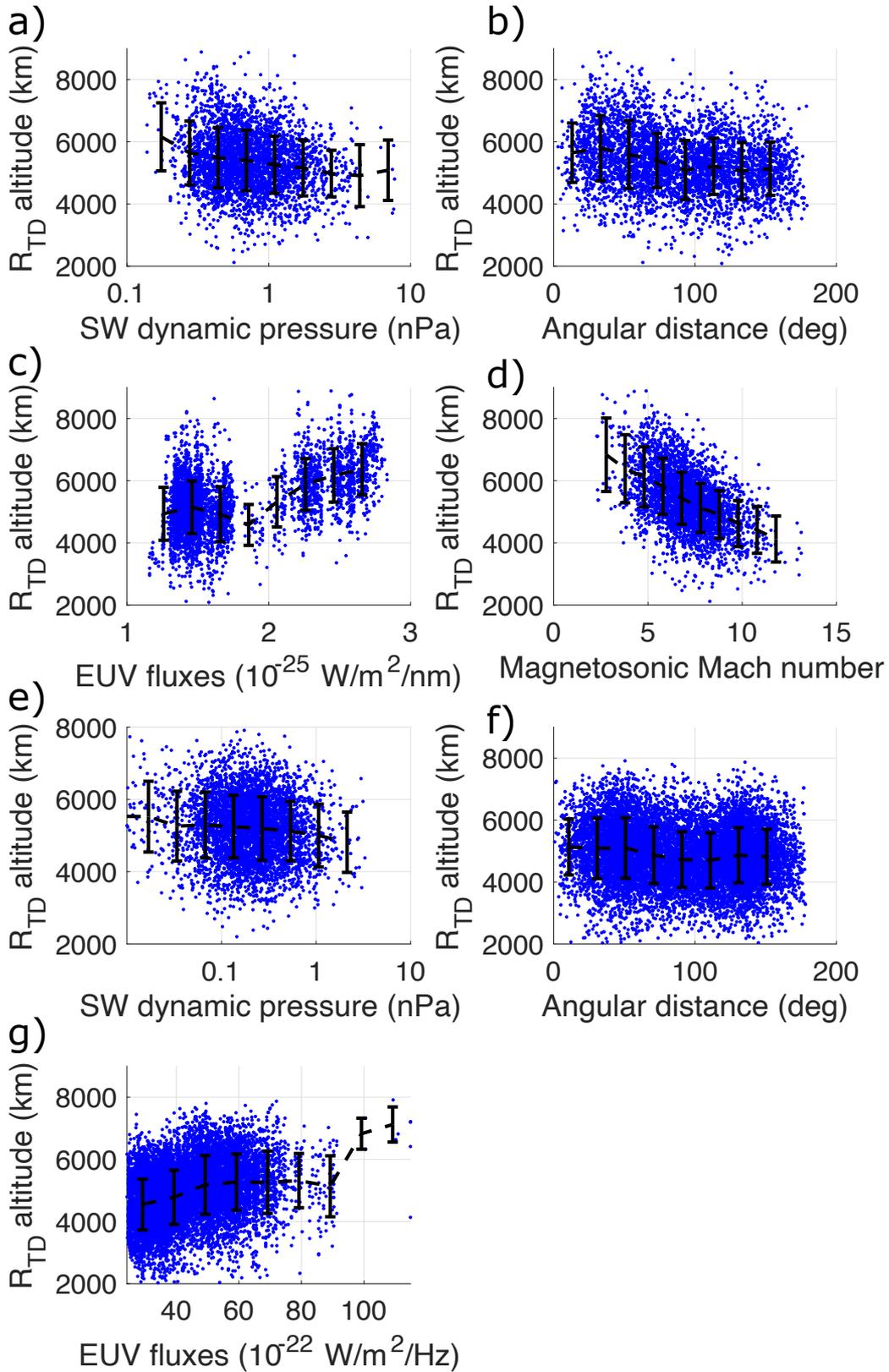
1214 The Akaike information criterion (AIC) is a criterion based on information theory  
 1215 widely used to perform model selection (Burnham & Anderson, 2002), by estimating the  
 1216 relative quality of several models for a given dataset. When a model is considered to rep-  
 1217 resent a process generating a dataset, some information is lost by using the model. AIC  
 1218 estimates the relative amount of information lost among several models. This method  
 1219 can be used to compare linear or non-linear models, as long as the models are being fit  
 1220 to the same data. Moreover, AIC takes into account both the goodness of fit of the model  
 1221 and the complexity of the model, with a penalty that increases with the number of es-  
 1222 timated parameters to prevent from overfitting.

1223 We assume we have a statistical model of observed data, where  $k$  is the number of  
 1224 estimated parameters in the model and  $\hat{L}$  is the maximum value of the likelihood func-  
 1225 tion for the model. Then the AIC value of the model is (Akaike, 1974) :

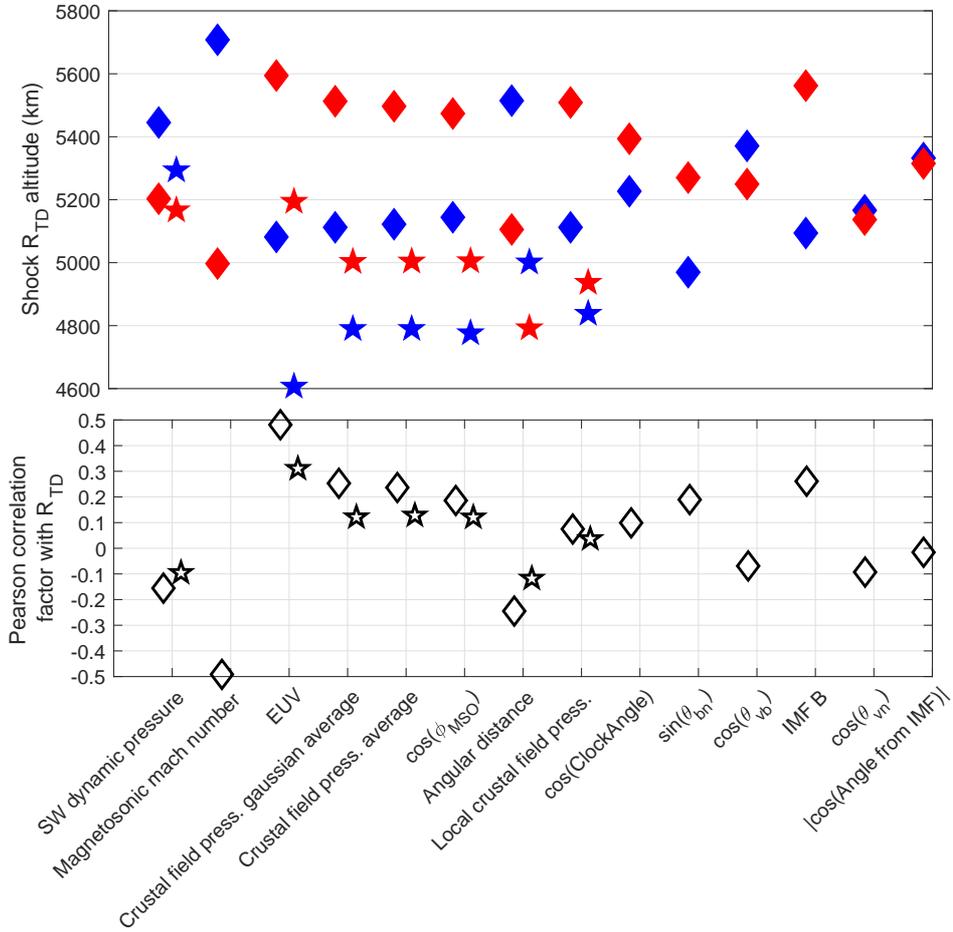
$$AIC = 2k - 2\ln(\hat{L}) \quad (A1)$$



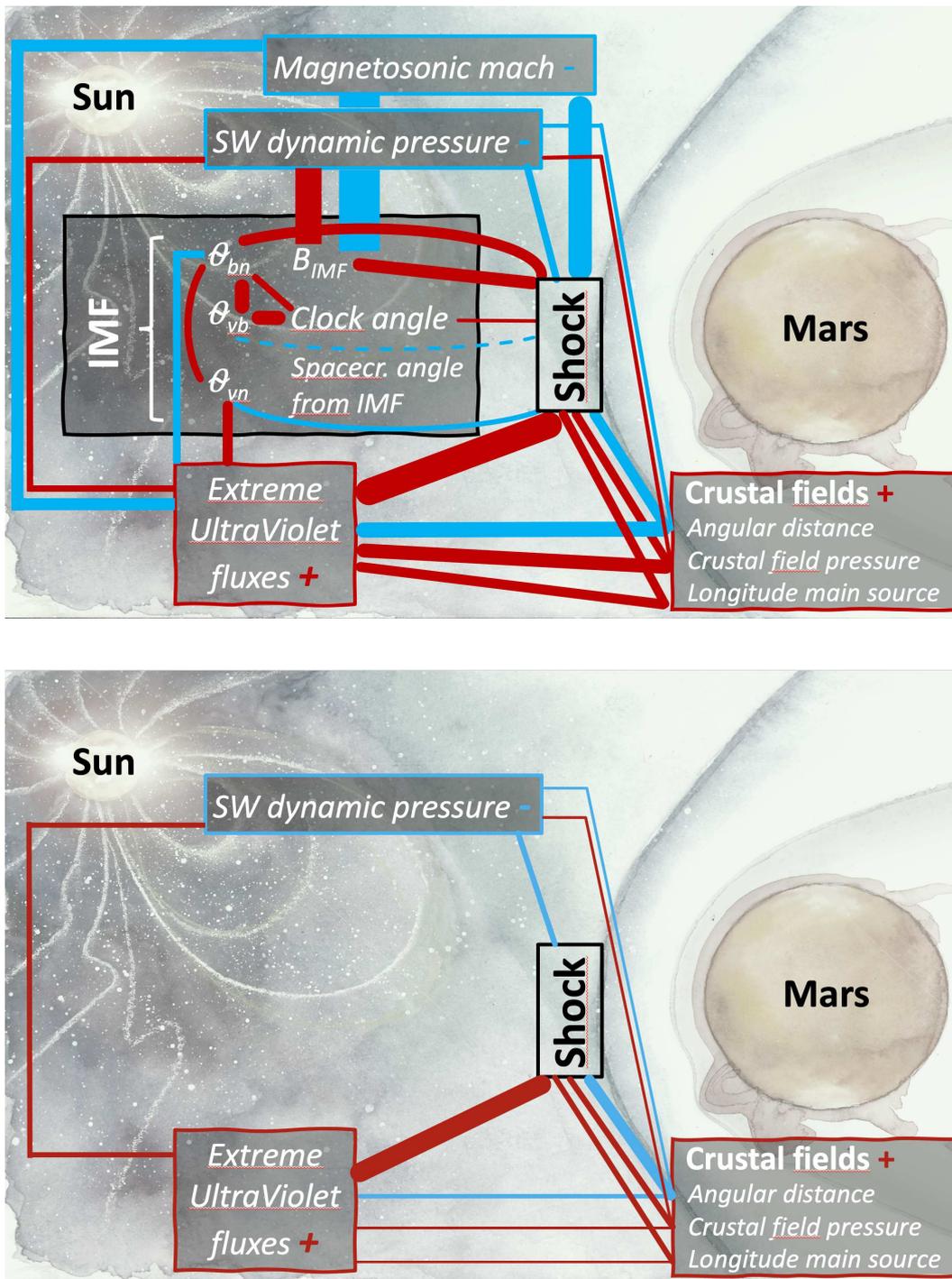
**Figure 1.** Schematics of the possible drivers of the Martian shock location considered in the paper (see text for explanations).  $B_{IMF}$  refers to the IMF intensity,  $\theta_{bn}$  to the angle between the normal of the BS and the IMF vector,  $\theta_{vm}$  between the normal of the BS and the SW velocity vector,  $\theta_{bv}$  between the SW velocity vector and the IMF vector. The signs + (with red color) and - (blue color) refer to the known or expected impact of the driver, with increased crustal fields and Extreme UltraViolet fluxes pushing the BS further from the planet, while increased SW dynamic pressure and magnetosonic mach number push it closer to the planet. The background figure is a drawing by Anastasia Grigoryeva.



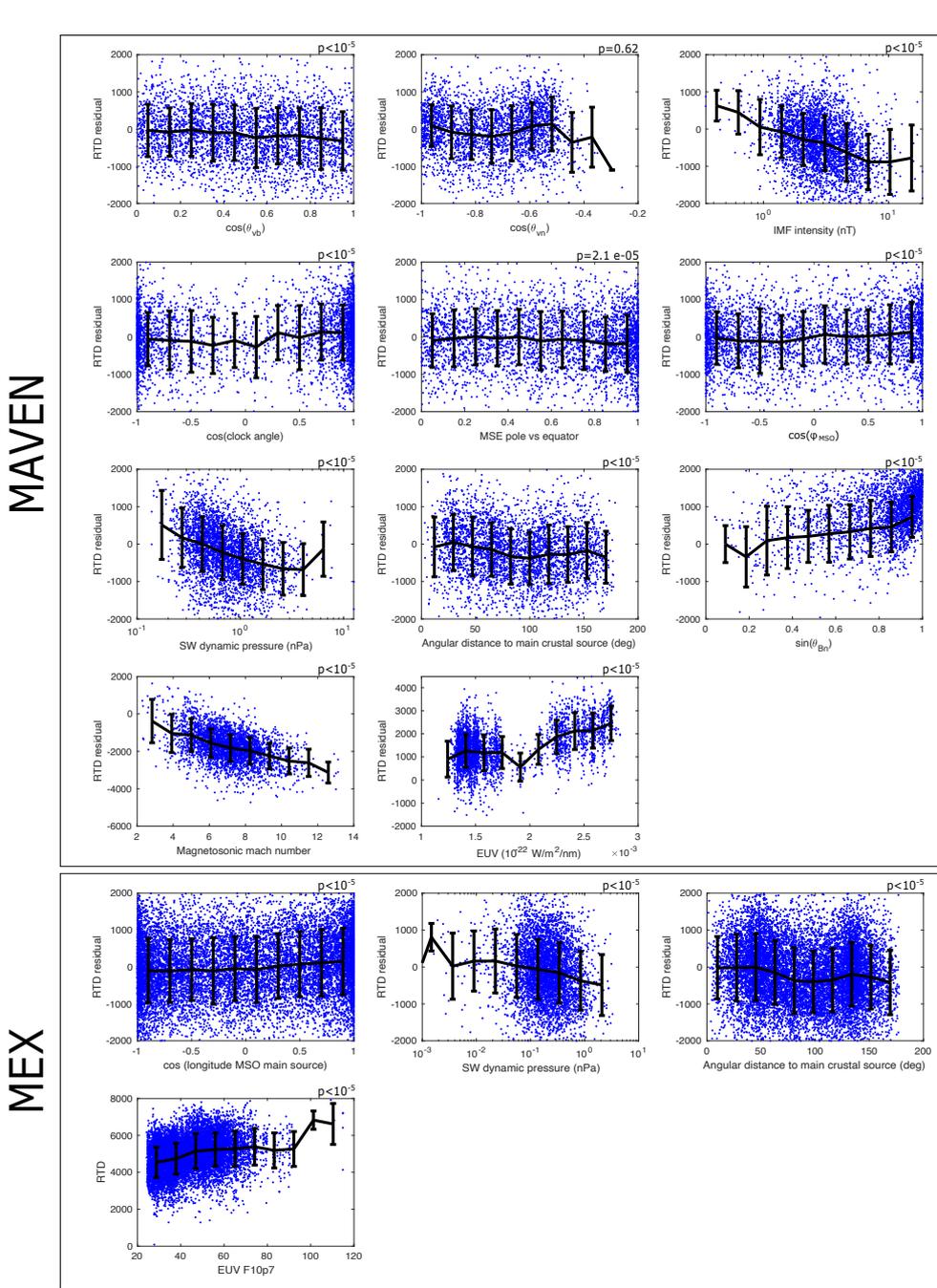
**Figure 2.**  $R_{TD}$  terminator altitude of the MAVEN (panels a to d) and MEX (panels e to g) shock crossings as a function of: the solar wind dynamic pressure (panels a and e), angular distance of the spacecraft from the strongest crustal source region (panels b and f), Extreme UltraViolet fluxes (panels c and g), magnetosonic Mach number (for MAVEN only, panel d).



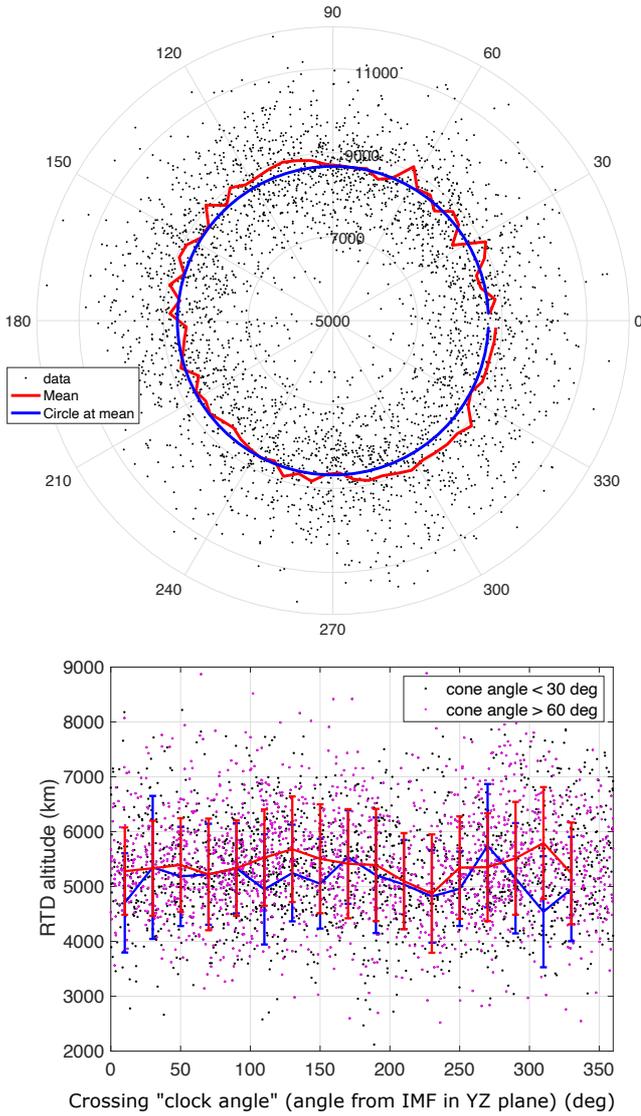
**Figure 3.** Comparison of the influence of a number of physical parameters on the shock  $R_{TD}$  terminator altitude as measured by MAVEN (diamonds; dataset published by Gruesbeck et al. (2018) and Fang et al. (2017)) and Mars Express (stars; dataset published by Hall et al. (2016)). See text for details.



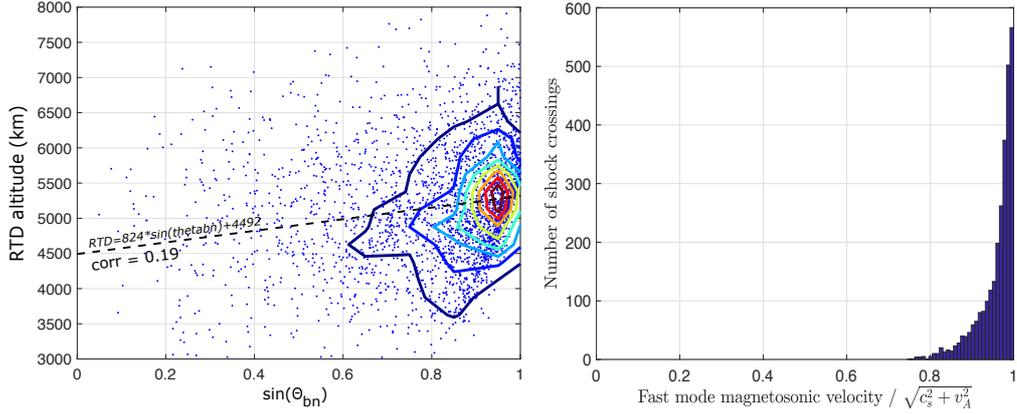
**Figure 4.** Schematic showing the complex inter-correlations of a number of possible parameters of influence for the MAVEN (upper panel) and MEX (lower panel) shock terminator altitude. Blue and red lines correspond respectively to negative and positive Pearson linear correlation factors. The thickness of the lines is proportional to the Pearson correlation factor. Dashed lines represent non-significant (p-value above 5%) correlations. The background figure was adapted from a drawing by Anastasia Grigoryeva.



**Figure 5.** Residuals of the  $R_{TD}$  terminator altitude (in  $km$ ) of the MAVEN (upper panels) and Mars Express (lower panels) shock crossings vs the possible drivers of the shock location, after removing the linear dependence vs the main drivers. The main drivers considered to calculate the residuals are the magnetosonic mach number (only available for MAVEN) and the Extreme Ultraviolet fluxes. Numbers above the panels correspond to p-values associated with the linear partial correlations (where  $< 10^{-5}$  refers to negligible p-values).



**Figure 6.**  $R_{TD}$  terminator altitude (in  $km$ ) of the MAVEN shock crossings in the Mars Sun Electric field coordinate system, as a function of the angle between the projection in the terminator plane of the crossing and of the IMF vector ( $90^\circ$  points toward the convection electric field). Individual crossings are given by black dots. (Upper panel) The averaged binned profile (red line) is compared with a constant profile at the overall mean value (blue circle). The radial axis starts from  $5000\ km$  altitude to focus on the variability around the mean. (Lower panel) Averaged mean profiles are superimposed for only large ( $> 60^\circ$ , red line) or low ( $< 30^\circ$ ) cone angle values of the Interplanetary Magnetic Field. Both panels correspond to direct analysis as performed by previous authors, but can be biased due to cross correlations.

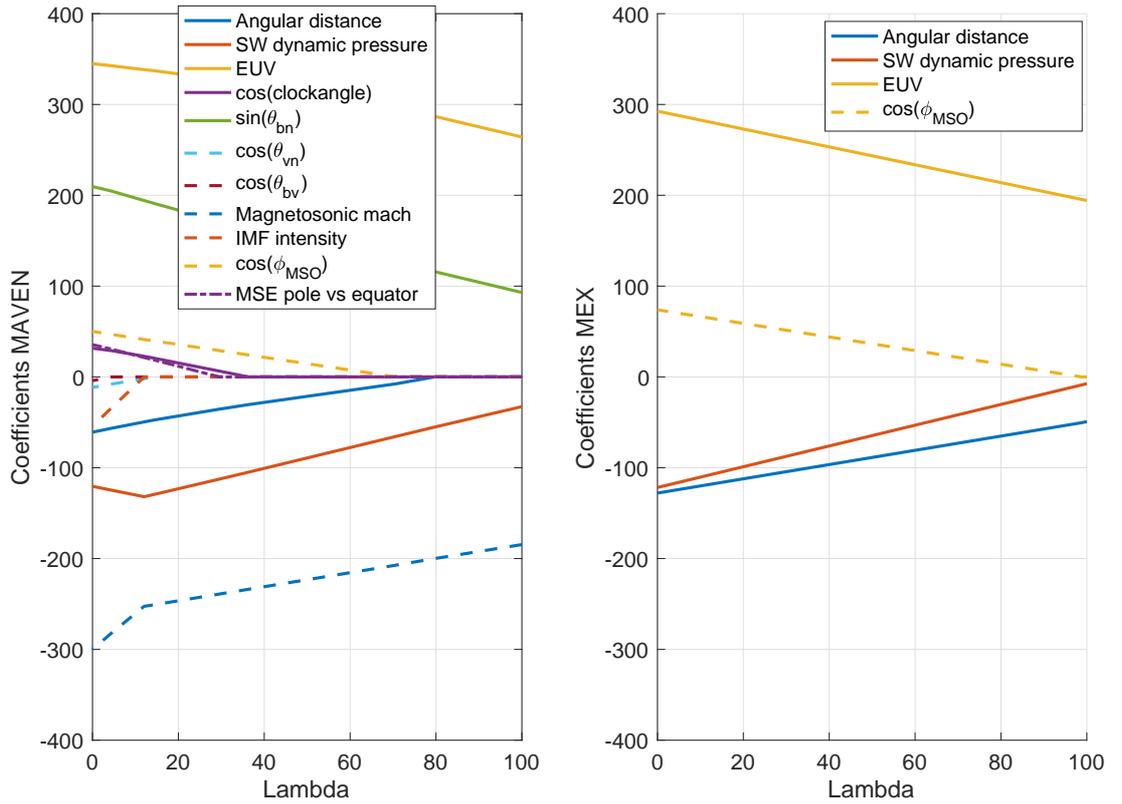


**Figure 7.** (left)  $R_{TD}$  terminator altitude (in  $km$ ) of the MAVEN shock crossings vs the sine of  $\theta_{bn}$  the angle between the IMF direction and the shock normal; contour (thick red) lines of the occurrence frequency and a linear regression (dashed line) are added, as well as the Pearson correlation coefficient between both parameters. (right) Histogram of the number of crossings as a function of the ratio between the fast mode magnetosonic wave velocity and  $\sqrt{c_s^2 + v_A^2}$ .

1226 Among several candidate models fitting the data, the preferred model is the one  
 1227 with the minimum AIC value. Only the relative AIC difference among several candidate  
 1228 models is significant - with differences larger than 2 being significant, and larger than  
 1229 4 very significant -, and there is no significance in the absolute value of AIC. The rel-  
 1230 ative likelihood of a model  $i$  compared to the best model (with minimum AIC) is given  
 1231 by  $exp(AIC_{min} - AIC_{model_i})$ .

## 1232 Appendix B LASSO

1233 The Least Absolute Shrinkage Selection Operator (LASSO) is a commonly used  
 1234 supervised regularization method for regression developed by Tibshirani (1996). LASSO  
 1235 is an efficient technique for shrinkage and selection method, where a penalty term allows  
 1236 the identification of the significance of predictors in a regression model. Compared to  
 1237 classical regression, the coefficients of the regression are constrained by the sum of the  
 1238 modulus or absolute values of the coefficients being as small as possible. These coeffi-  
 1239 cients can even be set to zero, allowing for selecting the most significant variables de-  
 1240 pending on the regularization parameter. LASSO is in particular efficient with a large  
 1241 number of predictors included a priori in the model.



**Figure 8.** Coefficients of the Lasso regression of the MAVEN (left) and MEX (right) drivers of the Martian shock extrapolated terminator altitude, as a function of the regularization parameter Lambda.

We assume our parameter of interest  $y$  depends at first order on a linear combination of variables  $x_i$  with an error term:

$$y = \sum_i \beta_i x_i + e \quad (\text{B1})$$

LASSO gives as a result the regression coefficients  $\beta_i$  as a function of the regularization parameter  $\lambda$ , by minimizing the following term with the glmnet R package:

$$J(\beta_i) = 1/N \sum_{j=1}^N (y_j - \sum_i \beta_i x_{i,j})^2 + \lambda \sum_i |\beta_i| \quad (\text{B2})$$

When increasing  $\lambda$  from zero (i.e. for LASSO switched off or for the classical solution) to larger values, the regularization term sets more coefficients to zero, thus removing them from the selected model. The LASSO technique needs the definition of a training set to learn from and a test set in order to tune the parameter  $\lambda$ . A good  $\lambda$  value can be obtained by a cross-validation procedure, e.g. 10-folds in our study to avoid overfitting.

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