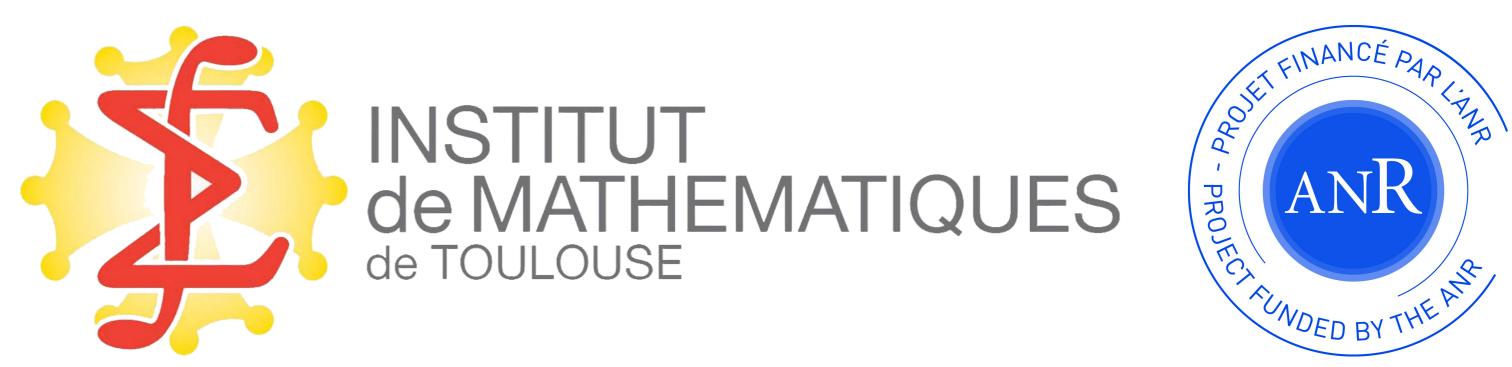
Asymptotically accurate high-order space and time schemes for the Euler system in the low Mach regime

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## Introduction

• **Model under consideration**. We study the compressible isentropic Euler system:

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ho) &= 0. \end{aligned}$ 

- $\rho > 0$  is the density of the fluid
- ▶  $U \in \mathbb{R}$  is the velocity of the fluid
- $p(\rho) = \rho^{\gamma}$  is the pressure
- $\gamma \geq 1$  is the ratio of specific heats
- $\blacktriangleright$   $\varepsilon$  is the squared Mach number
- ► **Incompressible limit**. With well-prepared initial and boundary conditions, the compressible Euler system tends to the following

# **1.2.** A limiting procedure

The implicit part of this IMEX scheme is nothing but an implicit Runge-Kutta discretization. Unfortunately, the following result holds.

**Theorem** ([4]): There are no strong stability preserving implicit Runge-Kutta schemes of order higher than one.

To tackle this problem and still obtain a scheme more than first-order accurate, we introduce a limiting procedure. It consists in lowering the order of the scheme if oscillations are detected; it belongs to the framework of MOOD techniques (see [2]).

We introduce a **convex combination**, of parameter  $\theta$ , between the second-order discretization and the first-order discretization, as follows:

# 2. Application to the Euler system

The strategy developed for the model problem is now applied to the Euler system. For the second-order accuracy, we use:

- ▶ the ARS(2,2,2) time discretization;
- ► a linear reconstruction.
- To control the oscillations, we introduce:
  - the Euler analogue of the  $\theta$ -AP scheme;
- ► a limiter on the reconstruction slopes.

**Remark**: The Euler variables no longer satisfy a maximum principle.

We do not apply the same detection criterion as in the transport case. Instead, we turn to the **Riemann invariants**. Indeed, the Riemann invariants of smooth solutions are transported at the characteristic velocities, and thus they satisfy a maximum principle.

incompressible limit when  $\varepsilon$  tends to 0:

$$\begin{cases} \rho = \rho_0, \\ \nabla \cdot U = 0, \\ \rho_0 \partial_t U + \rho_0 \nabla \cdot (U \otimes U) + \nabla \pi_1 = 0, \end{cases}$$

where  $\pi_1$  is the order one correction of the pressure. The time singularity of this limit is due to the propagation of the acoustic waves at a velocity proportional to  $1/\sqrt{\varepsilon}$ .

▶ Numerical method. In [3], Dimarco, Loubère and Vignal propose a numerical scheme to preserve this asymptotic behavior. It is written below in semi-discrete form:

$$\frac{\rho^{n+1} - \rho^n}{\Delta t} + \nabla \cdot (\rho U)^{n+1} = 0,$$
  
$$\frac{(\rho U)^{n+1} - (\rho U)^n}{\Delta t} + \nabla \cdot (\rho U \otimes U)^n + \frac{1}{\varepsilon} \nabla (\rho(\rho))^{n+1} = 0.$$

Thanks to the semi-implicitation, this scheme is:

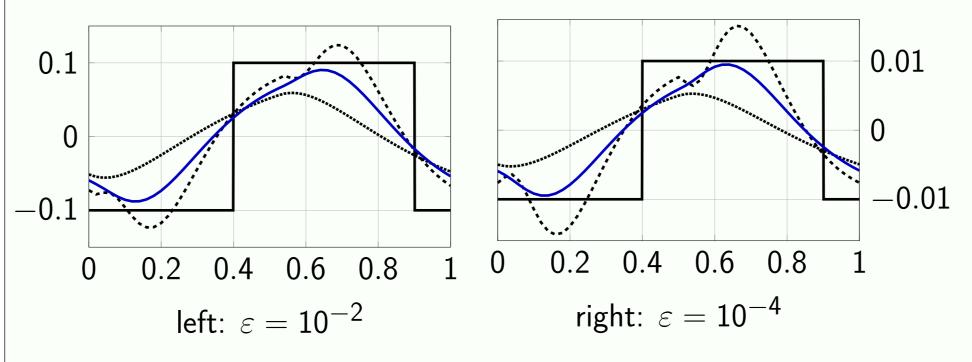
- ► asymptotic preserving (AP), i.e. it discretizes the incompressible Euler system when  $\varepsilon$  tends to 0;
- *uniformly*  $L^{\infty}$ -*stable* providing the space discretization is well-chosen.
- ► **Objective**. Propose an *asymptotically accurate* extension of this numerical scheme. The following properties must be satisfied:
- higher order of accuracy for all values of  $\varepsilon$  (including the asymptotic preserving property when  $\varepsilon \rightarrow 0$ );
- ► ability to *control the oscillations* induced by the use of high accuracy space/time numerical scheme.

## 1. A model problem

 $\left|u_{j}^{n+1}=u_{j}^{n}-\theta(\beta-1)c_{s}\frac{\Delta t}{\Delta x}\left(u_{j}^{n}-u_{j-1}^{n}\right)-\theta(1-\beta)\frac{c_{f}}{\sqrt{\varepsilon}}\frac{\Delta t}{\Delta x}\left(u_{j}^{\star}-u_{j-1}^{\star}\right)\right|$  $\sqrt{\varepsilon} \Delta X \setminus$  $-\theta(2-\beta)c_s\frac{\Delta t}{\Delta x}\left(u_j^{\star}-u_{j-1}^{\star}\right)-\theta\beta\frac{c_f}{\sqrt{\varepsilon}}\frac{\Delta t}{\Delta x}\left(u_j^{n+1}-u_{j-1}^{n+1}\right)$  $-(1-\theta)c_s\frac{\Delta t}{\Delta x}\left(u_j^n-u_{j-1}^n\right)-(1-\theta)\frac{c_f}{\sqrt{\varepsilon}}\frac{\Delta t}{\Delta x}\left(u_j^{n+1}-u_{j-1}^{n+1}\right).$ 

The following procedure is then applied at each time step:

- 1. compute a **candidate solution**  $u^{n+1}$  with the original ARS(2,2,2) discretization, i.e. with  $\theta = 1$ ;
- 2. detect if this candidate solution satisfies the following global maximum principle:  $||u^{n+1}||_{\infty} \leq ||u^n||_{\infty}$ ;
- 3. if this maximum principle is not satisfied, then take  $0 < \theta < 1$  and compute a **new solution**  $u^{n+1}$  with the above  $\theta$ -AP scheme.
- **Remark**: There is a value  $0 < \theta < 1$  such that this  $\theta$ -AP scheme is TVD (Total Variation Diminishing).



The approximation provided by the  $\theta$ -AP scheme, which corresponds to the blue curve when considering the advection of a step function, is in-bounds and more accurate than the first-order discretization.

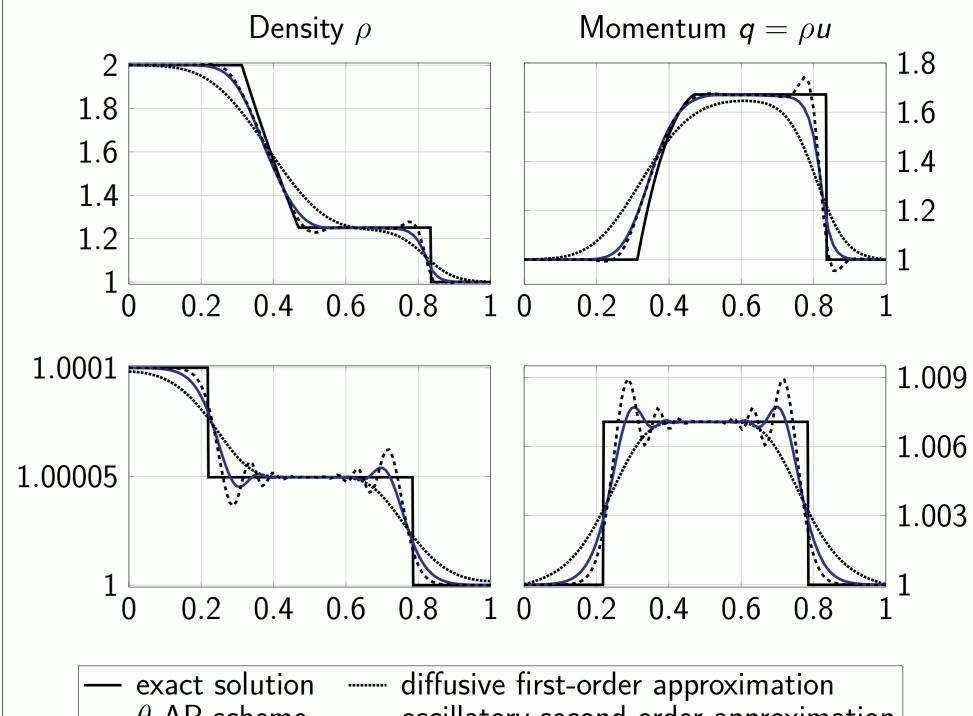
## **1.3. Space accuracy improvement**

First numerical experiment: Riemann problem

We consider a Riemann problem with the following initial data:

$$\begin{cases} \rho_L = 1 + \varepsilon, \\ \rho_R = 1, \end{cases} \quad \begin{cases} q_L = h_L u_L = 1, \\ q_R = h_R u_R = 1, \end{cases}$$

with  $\varepsilon = 1$  (top panels) and  $\varepsilon = 10^{-4}$  (bottom panels). This leads to a left rarefaction wave and a right shock wave, both with characteristic velocities proportional to  $1/\sqrt{\varepsilon}$ . Note that the amplitude of the rarefaction wave fan is also proportional to  $1/\sqrt{\varepsilon}$ .



We consider the following advection equation as a model problem:

$$\partial_t u + c_s \partial_x u + \frac{c_f}{\sqrt{\varepsilon}} \partial_x u = 0,$$

where the slow and fast velocities  $c_s$  and  $c_f/\sqrt{\varepsilon}$  are assumed to be non-negative and of order one.

Similarly to the Euler system, the characteristic velocity of the information is proportional to  $1/\sqrt{\varepsilon}$ . As a consequence, we consider the following semi-discrete scheme, mimicking the structure of the one proposed in [3]:

$$\frac{u^{n+1}-u^n}{\Delta t}+c_s\left(\partial_x u\right)^n+\frac{c_f}{\sqrt{\varepsilon}}\left(\partial_x u\right)^{n+1}=0.$$

Since  $c_s \ge 0$  and  $c_f \ge 0$ , we use an upwind discretization in space:

$$\partial_x u \simeq \frac{u_j - u_{j-1}}{\Delta x}.$$

As a consequence, the fully discrete scheme reads:

$$\frac{u_j^{n+1}-u_j^n}{\Delta t}+c_s\frac{u_j^n-u_{j-1}^n}{\Delta x}+\frac{c_f}{\sqrt{\varepsilon}}\frac{u_j^{n+1}-u_{j-1}^{n+1}}{\Delta x}=0.$$

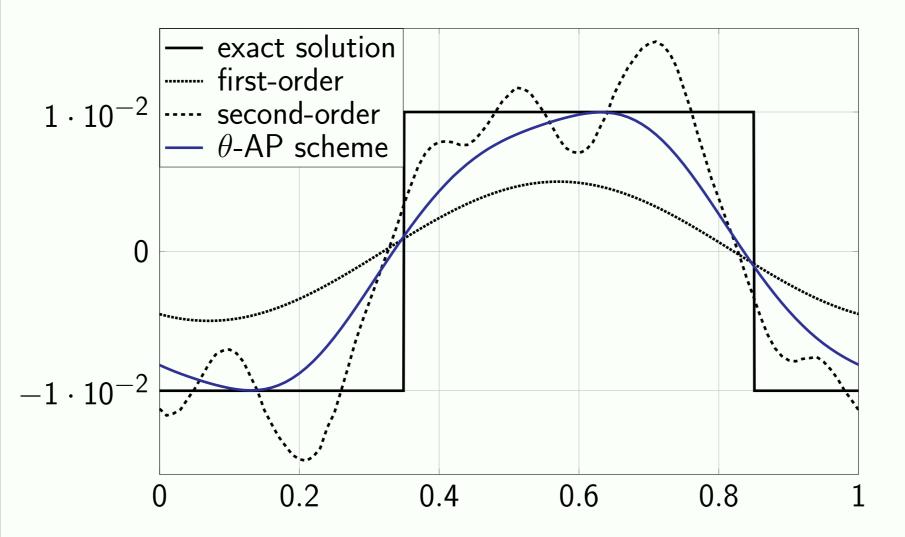
**Goal**: Propose an **asymptotically accurate** extension of this scheme.

## 1.1. A more accurate time discretization

This scheme falls within the framework of the **IMEX** (IMplicit-EXplicit) schemes (see [5] for instance). We turn to the two-step second-order in time **ARS(2,2,2)** discretization (see [1]), as follows:

To address the issue of the second-order space accuracy, we turn to a classical **MUSCL** method. In each cell, we take a **linear approximation**  $u_i^n(x)$  instead of the constant  $u_i^n$ .

In the figure below, we compare the different time discretizations at our disposal, coupled with the MUSCL method to increase space accuracy.



The approximation provided by the  $\theta$ -AP scheme (i.e. the blue curve, here with  $\varepsilon = 10^{-4}$ ) provides the best solution among the three discretizations.

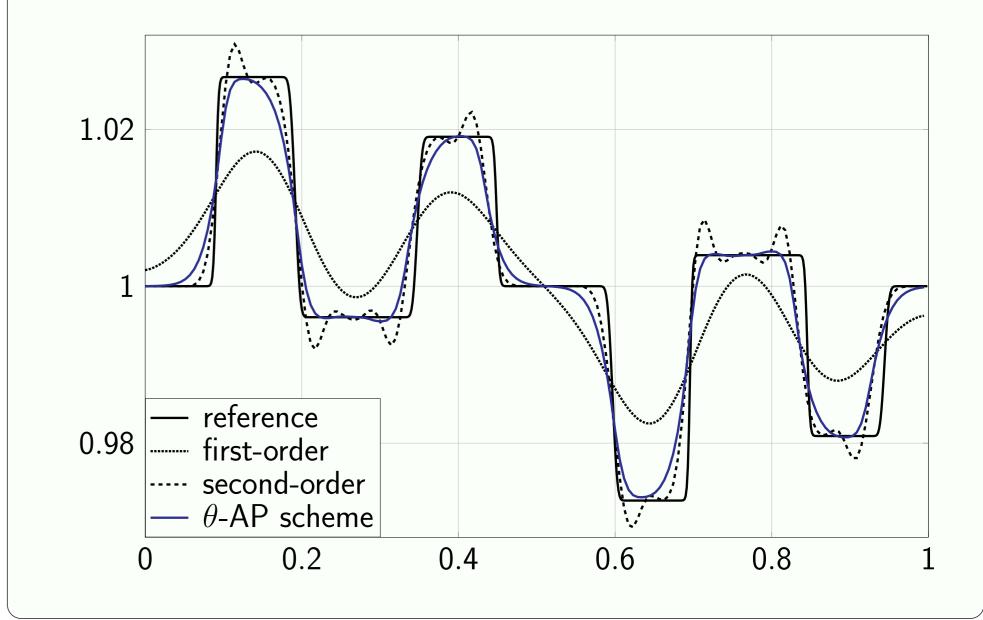
What about the numerical **order of accuracy**?

**Definition**: A numerical method is of space (resp. time) order *p* if its error is proportional to  $\Delta x^{p}$  (resp.  $\Delta t^{p}$ ) when considering the approximation of a smooth solution.

We thus display the error with respect to the number of points for a smooth solution and  $\varepsilon \in \{1, 10^{-1}, 10^{-2}, 10^{-4}\}$  (from left to right and

For both values of  $\varepsilon$ , the  $\theta$ -AP scheme yields a better approximation than both other schemes: it is less diffusive than the first-order one and less oscillatory than the second-order one.

## A more complex numerical experiment

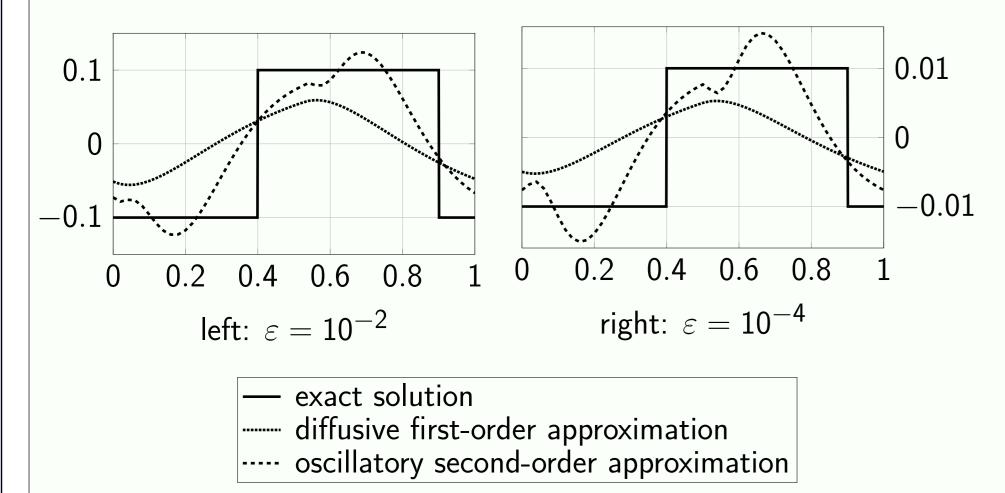


# **Ongoing works**

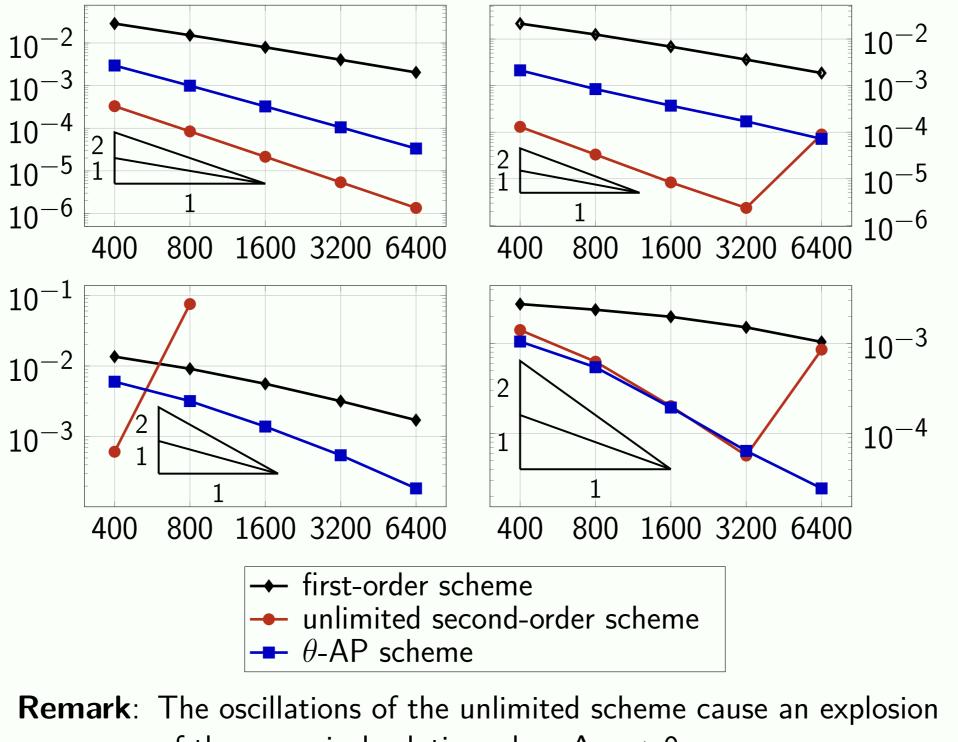
- develop a relevant criterion to determine a local  $\theta$ ;
- implement the extension of the  $\theta$ -AP scheme to two space dimensions;
- validate and verify its behavior on the full Euler system.

 $u_{j}^{\star} = u_{j}^{n} - \beta c_{s} \frac{\Delta t}{\Delta x} \left( u_{j}^{n} - u_{j-1}^{n} \right) - \beta \frac{c_{f}}{\sqrt{\varepsilon}} \frac{\Delta t}{\Delta x} \left( u_{j}^{\star} - u_{j-1}^{\star} \right),$  $u_{j}^{n+1} = u_{j}^{n} - (\beta - 1)c_{s}\frac{\Delta t}{\Delta x}\left(u_{j}^{n} - u_{j-1}^{n}\right) - (1 - \beta)\frac{c_{f}}{\sqrt{\varepsilon}}\frac{\Delta t}{\Delta x}\left(u_{j}^{\star} - u_{j-1}^{\star}\right)$  $-(2-\beta)c_s\frac{\Delta t}{\Delta x}\left(u_j^{\star}-u_{j-1}^{\star}\right)-\beta\frac{c_f}{\sqrt{\varepsilon}}\frac{\Delta t}{\Delta x}\left(u_j^{n+1}-u_{j-1}^{n+1}\right).$ 

This discretization preserves the AP property of the scheme. However, it is oscillatory, as displayed below with the advection of a step function.



top to bottom); the slopes correspond to the order of accuracy.



of the numerical solution when  $\Delta x \rightarrow 0$ .

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