

The PBW Theorem

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thm (PBW). Given \mathfrak{g} , the map

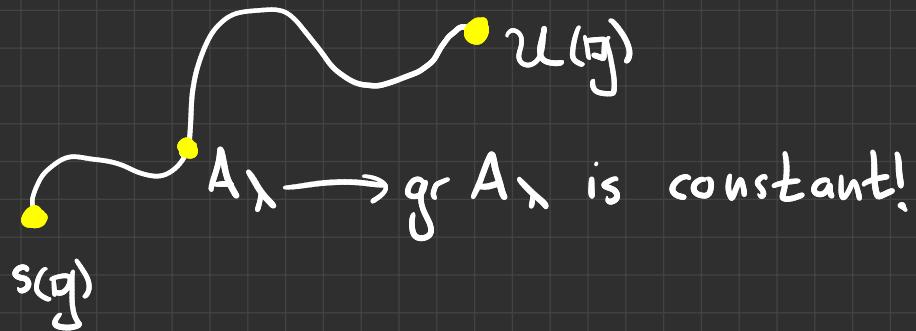
$$\begin{aligned} S(\mathfrak{g}) &\longrightarrow \text{gr } U(\mathfrak{g}) \\ x &\longmapsto x + F^0 U(\mathfrak{g}) \end{aligned}$$

is an isomorphism of graded \mathbb{C} -algebras.

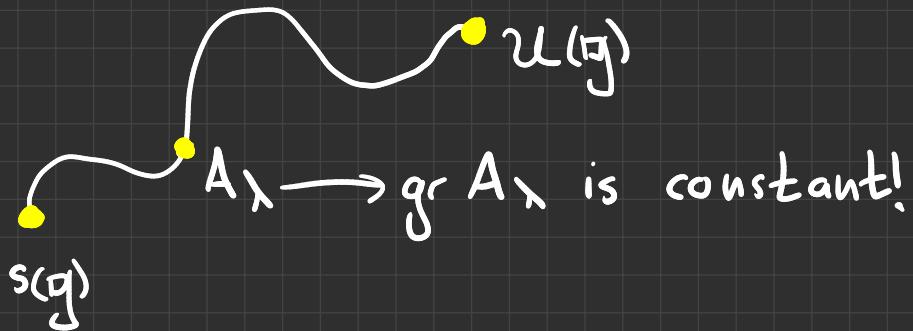
Braverman & Gaitsgory

ingredients: deformations + cohomology

a cartoonish picture



a cartoonish picture



deformations!

$$A_\lambda := Tg / \langle x \otimes y - y \otimes x - \lambda [x, y] : x, y \in g \rangle$$

def. A (flat graded) deformation A_t of a graded associative \mathbb{C} -algebra A is a $\mathbb{C}[t]$ -algebra, which is free as a module, and whose fiber $A_0 = A_t/(t)$ at $t=0$ is isomorphic to A as a filtered \mathbb{C} -algebra.



$$A_\lambda := A_t /_{(t-\lambda)}$$

def. A (flat graded) i -level deformation A_t of a graded associative \mathbb{C} -algebra A is a $\mathbb{C}[t]/(t^m)$ -algebra, which is free as a module, and whose fiber $A_0 = A_t/(t)$ at $t=0$ is isomorphic to A as a filtered \mathbb{C} -algebra.

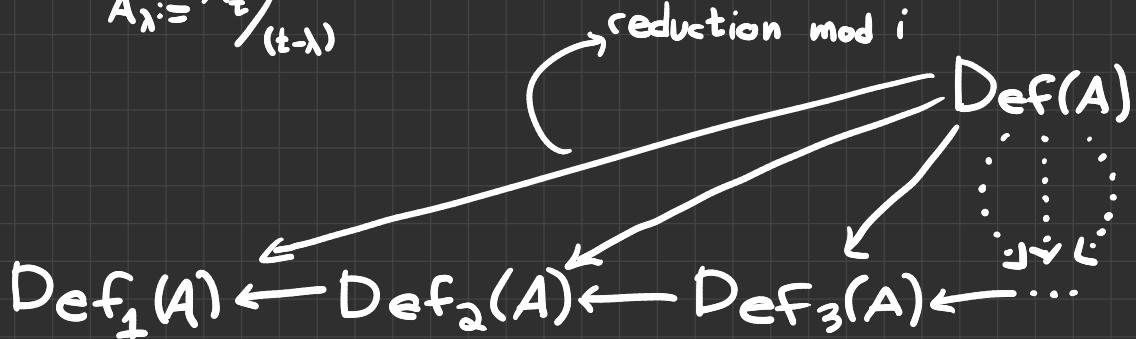


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def. A (flat graded) i -level deformation A_t of a graded associative \mathbb{C} -algebra A is a $\mathbb{C}[t]/(t^m)$ -algebra, which is free as a module, and whose fiber $A_0 = A_t/(t)$ at $t=0$ is isomorphic to A as a filtered \mathbb{C} -algebra.



$$A_\lambda := \frac{A_t}{(t-\lambda)}$$



$$\text{Def}(A) \cong \varprojlim_i \text{Def}_i(A)$$

def. Given a graded algebra A and a graded A -bimodule M , we define the bar complex

$$0 \longrightarrow C^0(M) \xrightarrow{d} C^1(M) \xrightarrow{d} C^2(M) \xrightarrow{d} \dots,$$

where

$$C^i(M)_n = \left\{ f \in \text{Hom}_A(A^{\otimes i}, M) : \begin{array}{l} \deg f(a_1, \dots, a_i) \\ = \deg a_1 + \dots + \deg a_i + n \end{array} \right\}$$

and

$$\begin{aligned} df(a_1, \dots, a_{i+1}) &= a_1 f(a_2, \dots, a_{i+1}) + (-1)^i f(a_1, \dots, a_i) a_{i+1} \\ &\quad + \sum_{k=1}^i (-1)^k f(a_1, \dots, a_k a_{k+1}, \dots, a_{i+1}). \end{aligned}$$

$$HH^i(A, M) = H^i(C^*(M)) = \frac{\ker(C^i(M) \longrightarrow C^{i+1}(M))}{\text{im}(C^{i-1}(M) \longrightarrow C^i(M))}$$

Prop.

(i) The set of iso. classes of 1st level deformations of A is canonically identified with $\mathrm{HH}^2(A, A)_{-1}$.

$$\{\text{1}^{\text{st}} \text{ level } A\text{-defs}\} / \underset{\cong}{\sim} \mathrm{HH}^2(A, A)_{-1}$$

(ii) If $A_t^{(i)}$ is an i-level deformation of A, the obstruction to its continuation to the $(i+1)^{\text{st}}$ level lies in $\mathrm{HH}^3(A, A)_{-i-1}$.

(iii) The set of iso. classes of continuations of $A_t^{(i)}$ has the natural structure of a $\mathrm{HH}^2(A, A)_{-i-1}$ -homogeneous space.

$$\{\text{continuations of } A_t^{(i)}\} / \underset{\cong}{\sim} \mathrm{HH}^2(A, A)_{-i-1}$$

big thm. Let $A = S(g)$. There is a quasi-iso.

$$0 \longrightarrow C^0(M) \xrightarrow{d} C^1(M) \xrightarrow{d} C^2(M) \xrightarrow{d} \dots$$
$$\downarrow \quad \downarrow \quad \downarrow$$
$$0 \rightarrow \text{Hom}_C(\Lambda^0 g, M) \rightarrow \text{Hom}_C(\Lambda^1 g, M) \rightarrow \text{Hom}_C(\Lambda^2 g, M) \rightarrow \dots$$

where $\downarrow f(a_1, \dots, a_i) = \sum_{\sigma \in S^i} (-1)^{|\sigma|} f(a_{\sigma(1)}, \dots, a_{\sigma(n)}).$

big thm. Let $A = S(g)$. There is a quasi-iso.

$$\begin{array}{ccccccc}
 0 & \longrightarrow & C^0(M) & \xrightarrow{d} & C^1(M) & \xrightarrow{d} & C^2(M) \xrightarrow{d} \dots \\
 & & \downarrow \circ & & \downarrow \circ & & \downarrow \circ \\
 0 & \longrightarrow & \text{Hom}_C(\Lambda^0 g, M) & \xrightarrow{\circ} & \text{Hom}_C(\Lambda^1 g, M) & \xrightarrow{\circ} & \text{Hom}_C(\Lambda^2 g, M) \xrightarrow{\circ} \dots
 \end{array}$$

where $\circ f(a_1, \dots, a_i) = \sum_{\sigma \in S^i} (-1)^{|\sigma|} f(a_{\sigma(1)}, \dots, a_{\sigma(n)})$.

$$\Omega(a, b, c) = \sum_{k=1}^i f_k(f_{i-k+1}(a, b), c) - f_k(a, f_{i-k+1}(b, c))$$

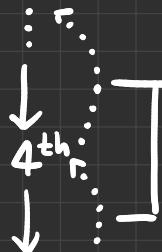
$\underbrace{\phantom{f_k(f_{i-k+1}(a, b), c) - f_k(a, f_{i-k+1}(b, c))}}$

$$\circ \Omega(x, y, z) = \circ f_i(\circ f_i(x, y), z) + \circ f_i(\circ f_i(y, z), x) + \circ f_i(\circ f_i(z, x), y)$$

the proof

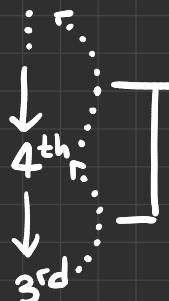
⋮
↓ 4th
↓ 3rd
↓ 2nd
↓ 1st ←

the proof



→ always extends because
 $HH^3(S(g), S(g))_{-i} = 0$ for $i > 3$

the proof



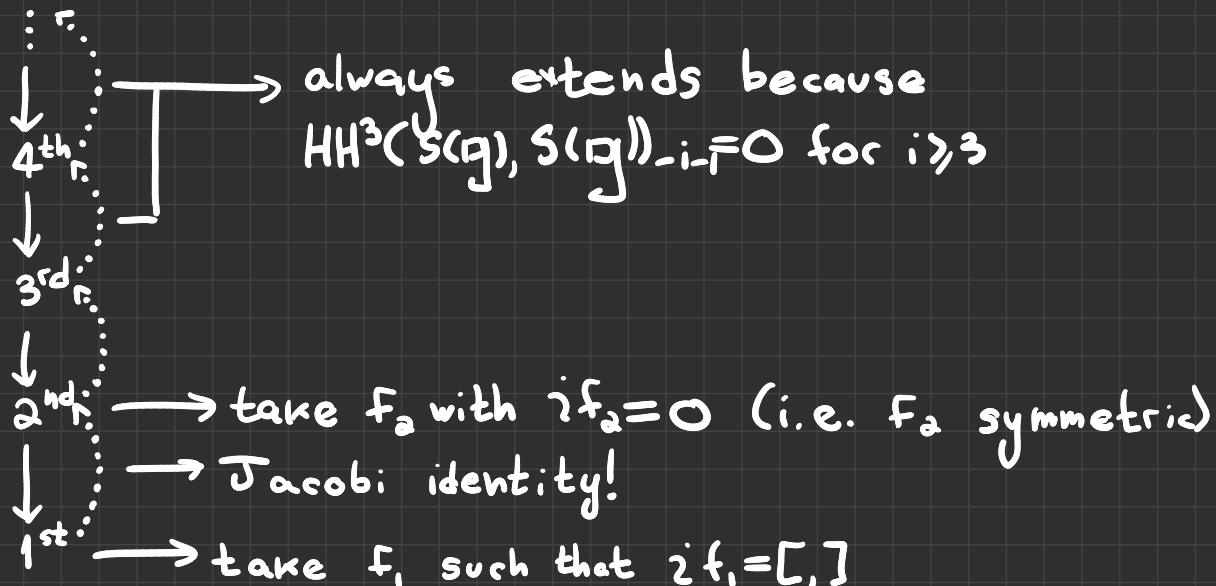
always extends because
 $HH^3(S(g), S(g))_{-i} = 0$ for $i > 3$



→ Jacobi identity!

→ take f_i such that $[f_i] = [,]$

the proof



the proof

- take f_i symmetric for $i > 3$
- ↓ always extends because
 $HH^3(S(g), S(g))_{-i} = 0$ for $i > 3$
- 4th ↓
F → take f_3 symmetric
- 3rd ↓
F → take f_2 with $\bar{f}_2 = 0$ (i.e. f_2 symmetric)
↓ → Jacobi identity!
- 2nd ↓
F → take f_1 such that $\bar{f}_1 = [,]$
- 1st ↓

the proof

- take f_i symmetric for $i > 3$
- ↓ always extends because
 $HH^3(S(g), S(g))_{-i} = 0$ for $i > 3$
- 4th r. ↓
- 3rd r. → take f_3 symmetric
- 2nd r. ↓ → take f_2 with $\sum f_2 = 0$ (i.e. f_2 symmetric)
→ Jacobi identity!
- 1st r. → take f_1 such that $\sum f_1 = [,]$

We get a deformation $A_t = A \oplus At \oplus \dots \oplus At^i \oplus \dots$ with
 $a * b = ab + f_1(a, b)t + \dots + f_i(a, b)t^i + \dots$

$$\begin{array}{ccc}
 x & \longmapsto & x + 0t + \cdots + (t-1) \\
 g & \longrightarrow & A_1 \\
 \downarrow & \ddots & \uparrow \\
 \downarrow f & \ddots & \\
 u(g) & &
 \end{array}
 \quad
 \begin{array}{ccc}
 s(g) & \xrightarrow{g} & \text{gr } A_1 \\
 x & \longmapsto & (x + 0t + \cdots + (t-1)) + F^0 A_1
 \end{array}$$

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$$\begin{array}{ccccc}
 s(g) & \longrightarrow & gr u(g) & \xrightarrow{gr f} & gr A_1 & \xrightarrow{g^{-1}} & s(g) \\
 x & \longmapsto & x + F^0 u(g) & \longmapsto & (x + 0t + \cdots + (t-1)) + F^0 A_1 & \longmapsto & x
 \end{array}$$

$$\begin{array}{ccc}
 x & \xrightarrow{\quad} & x + 0t + \cdots + (t-1) \\
 g & \xrightarrow{\quad} & A_1 \\
 \downarrow & \ddots & \downarrow \\
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 u(g) & &
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 x & \xrightarrow{\quad} & (x + 0t + \cdots + (t-1)) + F^0 A_1
 \end{array}$$

$$\begin{array}{ccccc}
 & & id & & \\
 & \swarrow & & \searrow & \\
 s(g) & \xrightarrow{\quad} & gr u(g) & \xrightarrow{gr f} & gr A_1 & \xrightarrow{g^{-1}} & s(g)
 \end{array}$$

$$x \xrightarrow{\quad} x + F^0 u(g) \xrightarrow{\quad} (x + 0t + \cdots + (t-1)) + F^0 A_1 \xrightarrow{\quad} x$$

□

Thanks!

<https://linux.ime.usp.br/~pablo>