

Les différents modèles utilisés en neutronique: une revue et quelques résultats mathématiques

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Models

Eigenvalue problems to solve: the notion of criticality

Homogeneization results

Homogeneization of the transport equation

Homogeneization of the diffusion equation

Coupling hydrodynamics and neutronics

Systems of equations

Exact 1D solution for the coupled problem

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The basic initial model: Boltzmann's equation

Linear Boltzmann equation with a linear collision kernel

$$\partial_t f(t, x, v) + v \cdot \nabla_x f(t, x, v) = \int K(t, x, v, v') f(t, x, v') dv'. \quad (1)$$

Another vision of this kernel, which decomposes into two nonnegative parts

$$K(t, x, v, v') = \nu K_f(t, x, v, v') - K_a(t, x, v, v') \quad (2)$$

$$\frac{d}{dt} \mathcal{A}(t, x) = A_p(t, x) - A_a(t, x)$$

(\mathcal{A} stands for the number of neutrons in a volume (Lagrangian)),

$A_p(t, x)$ is the number of neutrons produced by unit of time,

$A_a(t, x)$ is the number of neutrons absorbed by unit of time,

$A_p(t, x)$ is produced by fission.

Based on $m'_1 v'_1 + m'_2 v'_2 = m_1 v_1 + m_2 v_2 + \tilde{d}$, where particles 1 and 2 interact, and produce neutrons of impulse \tilde{d} .

Remark: $\frac{1}{2} m'_1 (v'_1)^2 + \frac{1}{2} m'_2 (v'_2)^2 < \frac{1}{2} m_1 (v_1)^2 + \frac{1}{2} m_2 (v_2)^2$.

Multi group neutron diffusion equation

Based on $v = \|v\|\Omega$, where Ω is of norm 1, and selects a direction.

Recall $v = \frac{p}{m\gamma(p)}$, $\gamma(p) = \sqrt{1 + \frac{p^2}{m^2c^2}}$ ($p = \|p\|\Omega$ as well).

$$\begin{aligned} & \left[\frac{1}{\|v\|} \partial_t f + \Omega \cdot \nabla_x f \right] (t, x, \|v\|\Omega) = \int_{\mathbf{R}^3} \frac{K(t, x, \|v\|\Omega, v')}{\|v\|} f(t, x, v') dv' \\ & = \int_0^{+\infty} \frac{\|p'\|^2}{\|v\|} d\|p'\| \int_{S^2} K(t, x, \|v\|\Omega, \|v'\|\Omega') f(t, x, \frac{\|p'\|}{m\gamma(\|p'\|)} \Omega') d\Omega'. \end{aligned}$$

As $p' \in [0, +\infty)$, $v' \in [0, c)$, replace $\int_0^{+\infty}$ by a discrete sum.

$$\int_0^{+\infty} \varphi(p') d\|p'\| = \int_0^c \tilde{\varphi}(v') \rho(\|v'\|) d\|v'\| \rightarrow \sum_{g=1}^K l_g \varphi(v'_g)$$

where v'_g is the 'mean' of $\|v'\|$ in the interval I_g of length l_g .
 g : called a group of energy (K groups).

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where v'_g is the 'mean' of $\|v'\|$ in the interval I_g of length l_g .
 g : called a group of energy (K groups).

After discretization of the integral,

$$\begin{aligned} \frac{1}{\|v\|} \partial_t f + \Omega \cdot \nabla_x f + \sum_{g'} \int_{S^2} k_a(\cdot, \cdot, \|v\| \Omega, v_{g'} \Omega') (v_{g'})^2 l_{g'} f(\cdot, \cdot, v_{g'} \Omega') d\Omega' \\ = \sum_{g'} \int_{S^2} \nu k_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') (v_{g'})^2 l_{g'} d\Omega'. \end{aligned}$$

Same with v : for each v_g in the list $g \in \{1, \dots, K\}$

$$\begin{aligned} \left[\frac{1}{v_g} \partial_t f + \Omega \cdot \nabla_x f \right] + \sum_{g'} \int_{S^2} (v_{g'})^2 l_{g'} k_a(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega' \\ = \sum_{g'} \int_{S^2} (v_{g'})^2 l_{g'} \nu k_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega'. \end{aligned}$$

Called multi-group transport equation for neutrons.

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$$\begin{aligned} \left[\frac{1}{v_g} \partial_t f + \Omega \cdot \nabla_x f \right] + \sum_{g'} \int_{S^2} (v_{g'})^2 l_{g'} k_a(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega' \\ = \sum_{g'} \int_{S^2} (v_{g'})^2 l_{g'} \nu k_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega'. \end{aligned}$$

Called multi-group transport equation for neutrons.

More precisely, with $\Phi_g(t, x, \Omega) = \int_{I_g} f(t, x, \|v\|\Omega) \|v\|^2 d\|v\|$
 ($K_{g,g'} = S^2 \times I_g \times I_{g'}$):

$$\begin{aligned} & \left[\frac{1}{v_g} \partial_t \Phi_g + \Omega \cdot \nabla_x \Phi_g \right] \\ & + \sum_{g'} \int_{K_{g,g'}} (v_g)^2 (v_{g'})^2 k_a(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega' \\ & = \sum_{g'} \int_{K_{g,g'}} (v_g)^2 (v_{g'})^2 \nu k_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega'. \end{aligned}$$

Modeled by using $\Phi_{g'}$ as well:

$$\begin{aligned} & \sum_{g'} \int_{K_{g,g'}} (v_g)^2 (v_{g'})^2 \nu k_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') f(\cdot, \cdot, v_{g'} \Omega') d\Omega' \\ & \quad \rightarrow \\ & \sum_{g'} \int_{S^2} \nu K_f(\cdot, \cdot, v_g \Omega, v_{g'} \Omega') \Phi_{g'}(\cdot, \cdot, \Omega') d\Omega'. \end{aligned}$$

Final model

Multi-group ($\Phi_g \geq 0$ on \mathcal{O}):

$$\begin{aligned} \frac{1}{v_g} \partial_t \Phi_g + \Omega \cdot \nabla_x \Phi_g + \sum_{g'} \int_{\Omega'} (\Sigma_a)_{g'}^{g'}(\cdot, \cdot, \Omega, \Omega') \Phi_{g'}(\cdot, \cdot, \Omega') d\Omega' \\ = \\ \sum_{g'} \int_{\Omega'} \nu (\Sigma_f)_{g'}^{g'}(\cdot, \cdot, \Omega, \Omega') \Phi_{g'}(\cdot, \cdot, \Omega, \Omega') d\Omega'. \end{aligned} \quad (3)$$

One group ($\Phi \geq 0$ on K):

$$\begin{aligned} \frac{1}{v} \partial_t \Phi + \Omega \cdot \nabla_x \Phi + \int_{\Omega'} \Sigma_a(\cdot, \cdot, \Omega, \Omega') \Phi(\cdot, \cdot, \Omega') d\Omega' \\ = \\ \int_{\Omega'} \nu \Sigma_f(\cdot, \cdot, \Omega, \Omega') \Phi(\cdot, \cdot, \Omega') d\Omega'. \end{aligned} \quad (4)$$

What is found in neutronics books

Standard representation of the previous equation (other formulation) ($\varphi(t, x, E) = \int_{S^2} \psi(t, x, E, \Omega) d\Omega$, $\chi(E)$: spectrum of energy of fission neutrons):

$$\frac{1}{v(E)} \partial_t \psi(t, x, E, \Omega) + \Omega \cdot \nabla_x \psi(t, x, E, \Omega) + \Sigma_t(t, E, x) \psi(t, x, E, \Omega)$$

=

$$\int_{E_{min}}^{E_{max}} \int_{S^2} (\Sigma_s)_{E', \Omega'}^{E, \Omega}(t, x) \psi(t, x, E, \Omega') d\Omega'$$

$$+ \frac{\chi(E)}{4\pi} \int_{E_{min}}^{E_{max}} \nu \Sigma_f(E') \varphi(t, x, E') dE'$$

+ other terms

other terms: all isotopes and the delayed neutrons.

Critical stationary transport equation

$$\Omega \cdot \nabla_x \psi(t, x, E, \Omega) + \Sigma_t(t, E, x) \psi(x, E, \Omega)$$

=

$$\int_{E_{min}}^{E_{max}} \int_{S^2} (\Sigma_s)_{E', \Omega'}^{E, \Omega}(t, x) \psi(x, E, \Omega') d\Omega' + \frac{\chi(E)}{4\pi k_{eff}} \int_{E_{min}}^{E_{max}} \nu \Sigma_f(E') \varphi(x, E') dE'$$

Classical approximations

Approximation of transport by diffusion (analogous of what financial mathematicians do), $\varphi \geq 0$

$$\frac{1}{v} \partial_t \varphi - \operatorname{div}(d(t, x) \nabla_x \varphi) + \sigma_a(t, x) \varphi(t, x) = \nu \sigma_f(t, x) \varphi(t, x). \quad (5)$$

Boundary conditions: $\Phi_g = \Phi = \varphi = 0$ on $\partial \mathcal{O}$, \mathcal{O} bounded.

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Criticality condition

Start in the case of one group, coefficients independent on t , bounded below by strictly positive constants on K :

$$\frac{1}{v} \partial_t \varphi - \operatorname{div}(d(x) \nabla_x \varphi) + \sigma_a(x) \varphi(t, x) = \nu \sigma_f(x) \varphi(t, x).$$

Subcase: d, σ_a, σ_f independent on x . Solutions of the form $k(t) \varphi(x)$. Separation of variables

$$\frac{1}{v} k'(t) \varphi(x) = k(t) [\operatorname{div}(d(x) \nabla \varphi) - \sigma_a(x) \varphi(x) + \nu \sigma_f(x) \varphi(x)].$$

Obtain $\frac{k'(t)}{k(t)} = \tau^{-1}$ and

$$-\operatorname{div}(d(x) \nabla_x \varphi(x)) + \sigma_a(x) \varphi(x) = \left(\nu \sigma_f(x) - \frac{\tau}{v} \right) \varphi(x).$$

This problem is $A\varphi = B(\tau)\varphi$ on $H_0^1(K)$, where

$$A : \varphi \rightarrow -\operatorname{div}(d(x) \nabla_x \varphi(x)) + \sigma_a(x) \varphi(x), B : \varphi \rightarrow \left(\nu \sigma_f(x) - \frac{\tau}{v} \right) \varphi$$

Mathematical result 1

Proposition

1. For $\frac{\tau}{v} < \min_{\mathcal{O}} \nu \sigma_f(x)$, the problem $A\varphi = B(\tau)\varphi$ on $H_0^1(\mathcal{O})$, $\varphi|_{\partial\mathcal{O}} = 0$ is equivalent to

$$A^{-\frac{1}{2}}B(\tau)A^{-\frac{1}{2}}\psi = \psi, \psi \in H_0^1(\mathcal{O}).$$

2. The operator $A^{-\frac{1}{2}}B(\tau)A^{-\frac{1}{2}}$ is a self-adjoint compact operator, hence admits an infinite countable decreasing sequence $\mu_n(\tau)$ of eigenvalues.
3. The unique nonnegative solution of $A\varphi = B(\tau)\varphi$ in $H_0^1(\mathcal{O})$ is obtained for $\mu_1(\tau) = 1$.

Proof: A is a symmetric self-adjoint coercive operator hence by Lax Milgram lemma, is invertible, and $A^{-\frac{1}{2}}$ is well defined. Denote by ψ such that $A^{-\frac{1}{2}}\psi = \varphi$. Deduce $A\varphi = A^{\frac{1}{2}}\psi = B(\tau)A^{-\frac{1}{2}}\psi$, which is the desired equation. The second item follows (because $B(\tau)$ is an operator on $H_0^1(\mathcal{O})$). The third item is a consequence that the first eigenvector of a positive self-adjoint compact operator is of constant sign, and all others are orthogonal in $L^2(\mathcal{O})$ to this one.

Now, solve $\mu_1(\tau) = 1$.

If $\tau > 0$, unique family of growing in time solution (supercritical).

If $\tau < 0$, unique family of decaying in time solution (subcritical).

If $\tau = 0$, **criticality condition**, solution is stationary in time.

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Simple classical application

Further reducing: constant coefficients, $\mathcal{O} = [0, L]$: Spectrum of

$$A: \tilde{\mu}_n = n^2 \frac{\pi^2}{L^2} d + \sigma_a.$$

Eigenvectors $x \rightarrow \sin \frac{n\pi x}{L}$.

Spectrum of $A^{-\frac{1}{2}} B(\tau) A^{-\frac{1}{2}}$:

$$\mu_n(\tau) = \frac{\nu\sigma_f - \frac{\tau}{v}}{n^2 \frac{\pi^2}{L^2} d + \sigma_a}.$$

Resolution of $\mu_1(\tau) = 1$:

$$\frac{\tau}{v} = \nu\sigma_f - \sigma_a - \frac{\pi^2}{L^2} d.$$

Criticality condition

$$\nu\sigma_f = \sigma_a + \frac{\pi^2}{L^2} d \tag{6}$$

New formulation of the eigenvalue problem

Replace $\nu\sigma_f - \frac{\tau}{v}$ by $\frac{\nu\sigma_f}{k_{eff}}$

$$-\operatorname{div}(d(x)\nabla\varphi(x)) + \sigma_a(x)\varphi(x) = \frac{\nu\sigma_f(x)}{k_{eff}}\varphi, \varphi_{\partial\mathcal{O}} = 0.$$

Means k_{eff} is an eigenvalue of $A^{-\frac{1}{2}}(\nu\sigma_f(.))A^{-\frac{1}{2}}$.

A lot different, except for $\nu\sigma_f$ constant or $k_{eff} = 1$.

In particular: nothing can be said if $k_{eff} \neq 1$ for a value of τ .

Only information: if the spectrum of $A^{-\frac{1}{2}}(\nu\sigma_f(.))A^{-\frac{1}{2}}$ lies in $(0, 1)$, the spectrum of $\nu\sigma_f - A$ lies in $(-\infty, 0)$, always subcritical.

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Multi-group presentation of the eigenvalue problem

$$\frac{1}{v_g} \partial_t \Phi_g - \operatorname{div}(D_g \nabla \Phi_g) + \sum_{g'} \Sigma_a^{g' \rightarrow g} \Phi_{g'} = \sum_{g'} \nu \Sigma_f^{g' \rightarrow g} \Phi_{g'}$$

Critical value equation

$$-\operatorname{div}(D_g \nabla \Phi_g) + \sum_{g'} \Sigma_a^{g' \rightarrow g} \Phi_{g'} = \sum_{g'} \nu \Sigma_f^{g' \rightarrow g} \Phi_{g'} - \frac{\tau}{v_g} \Phi_g, \text{ for all } g$$

MODEL (Allaire-Capdebosc, 1998)

$$-\operatorname{div}\left(\sum_{g'} D_{g' \rightarrow g} \nabla \Phi_{g'}\right) + \sum_{g'} \Sigma_a^{g' \rightarrow g} \Phi_{g'} = \frac{1}{k_{eff}} \sum_{g'} \nu \Sigma_f^{g' \rightarrow g} \Phi_{g'}, \quad (7)$$

with $\Phi_g|_{\partial K} = 0$.

Mathematical result on the multi-group problem

Hypotheses: $D_{g' \rightarrow g} = D_g$ (block-diagonal) and $D_g(x) \cdot \xi \cdot \xi \geq \alpha \xi \cdot \xi$ (coerciveness),

Exists $C > 0$ such that $\Sigma_a^{g' \rightarrow g} \leq 0$ when $g' \neq g$, $\Sigma_a^{g \rightarrow g} \geq C$,

$-\Sigma_a^{g' \rightarrow g} \geq C$ for $0 < |g' - g| \leq 1$,

$\Sigma_f^{g' \rightarrow g} \geq 0$ for all g, g' , $\Sigma_f^{1 \rightarrow K} \geq C$,

$\sum_{g'=1}^K \Sigma_a^{g' \rightarrow g} \geq C \nu \sum_{g'=1}^K \Sigma_f^{g' \rightarrow g}$.

Proposition

Problem (7) has at least one, and at most a countable number of eigenvalues. The first eigenvalue is real and simple, and a corresponding eigenvector can be chosen with all positive components.

Habetler-Martino 1958.

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Homogeneization result: Allaire-Bal: transport equation

Equation (4):

$$v \cdot \nabla_x \varphi + \Sigma_a(x, v) \varphi = \frac{1}{k_{eff}} \int_V \nu \Sigma_f(x, v', v) \varphi(x, v') dv' + \int_V f(x, v', v) \varphi(x, v') dv'$$

Σ_a : absorbing, f scattering, Σ_f : fission cross-sections. k_{eff}^{-1} smallest eigenvalue, φ associated eigenvector.

Assumption: K is ϵ -periodic. $\Sigma_{f,a}^\epsilon(x, v) := \Sigma_{f,a}(\frac{x}{\epsilon}, v)$, $f^\epsilon(x, v', v) = f(\frac{x}{\epsilon}, v', v)$.

$$v \cdot \nabla_x \varphi + \Sigma_a^\epsilon(x, v) \varphi = \lambda^\epsilon \int_V \nu \Sigma_f^\epsilon(x, v', v) \varphi(x, v') dv' + \int_V f^\epsilon(x, v', v) \varphi(x, v') dv'$$

Hypotheses and general result (Dautray-Lions)

- Velocity space is compact, K is compact.
 - $\Sigma_f(x, v', v) \geq C$,
 - $\Sigma_a(x, v) - \int_V f(x, v', v) dv' \geq C$,
 - $\Sigma_a(x, v) - \int_V f(x, v, v') dv' \geq C$,
- Introduce $W^2(\mathcal{O} \times V) = \{u \in L^2(\mathcal{O} \times V), v \cdot \nabla_x u \in L^2(\mathcal{O} \times V)\}$.

Proposition

The problem has at most a countable number of eigenvalues. The eigenvalue of smallest modulus is real positive, associated with a positive eigenvector.

The cell problem (notations)

Let λ_∞, ψ the first eigenvalue-eigenvector of the cell problem
(periodicity condition)

$$v \cdot \nabla_x \psi + \Sigma_a(y, v) \psi = \int_V [\lambda_\infty \nu \Sigma_f(y, v', v) + f(y, v', v)] \psi(x, v') dv'$$

Let ψ^* solve (periodicity condition)

$$-v \cdot \nabla_x \psi^* + \Sigma_a(y, v) \psi^* = \int_V [\lambda_\infty \nu \Sigma_f(y, v, v') + f(y, v, v')] \psi^*(x, v') dv'$$

Assume the drift flux is zero

$$\int_{\text{cell} \times V} v \psi(y, v) \cdot \psi^*(y, v) dv = 0.$$

The general problem: theorem (Allaire-Bal)

Let $\bar{\Sigma}$ given by

$$\bar{\Sigma} = \int_{\text{cell} \times V^2} \Sigma_f(y, v', v) \psi^*(y, v') \psi(y, v) dy dv dv'.$$

Let D identified as $D_{ij} = - \int_{\text{cell} \times V} v_j \psi(y, v) \psi^*(y, v) \theta^i(y, v) dy dv.$

Let θ^i solves a cell problem

$$v \cdot \nabla \theta^i + Q(\theta^i) = -v_i,$$

where Q is a scattering operator constructed from the cell problem.

Theorem

Let λ_k^ϵ be the k -th eigenvalue of (4) in the periodic case. Denote by φ_k^ϵ a normalized eigenvector.

1. This eigenvalue satisfies $\lambda_k^\epsilon = \lambda_\infty + \epsilon^2[\nu^k + o(1)]$
2. The associated eigenvector satisfies $\varphi_k^\epsilon(x, v) \simeq \psi(\frac{x}{\epsilon}, v) u^k(x),$
3. The couple (u^k, ν^k) satisfies

$$-\text{div}(D \nabla u^k) = \nu^k \bar{\Sigma} u^k(\Omega), u^k|_{\partial\Omega} = 0.$$

For the model with diffusion (Allaire-Capdeboscq)

- One group: already mentioned,
- multi-group

$$R\partial_t\varphi - \operatorname{div}(A(x)\nabla\varphi) + \Sigma_a\varphi = \nu\Sigma_f\varphi.$$

$\varphi : \mathbf{R}^3 \times \mathbf{R}_+ \rightarrow \mathbf{R}^K$ (K groups of energy),

R diagonal matrix of all v_g^{-1} ,

A is a $3 \times 3 \times K$ matrix (block-diagonal), symmetric in 3×3 ,

Σ_a, Σ_f are $K \times K$ matrices,

Separation of variables:

$$-\operatorname{div}(A(x)\nabla\varphi) + \Sigma_a\varphi = (\nu\Sigma_f - \tau R)\varphi,$$

Replaced by

$$-\operatorname{div}(A(x)\nabla\varphi) + \Sigma_a\varphi = \frac{\nu\Sigma_f}{k_{eff}}\varphi,$$

with same solution if $k_{eff} = 1$ or $\tau = 0$ equivalently.

Rescaled problem and theorem (Allaire-Capdebosc)

$$-\epsilon^2 \operatorname{div}\left(A\left(\frac{x}{\epsilon}\right) \nabla \varphi^\epsilon\right) + \Sigma_a\left(\frac{x}{\epsilon}\right) \varphi^\epsilon = \mu^\epsilon \nu \Sigma_f\left(\frac{x}{\epsilon}\right) \varphi^\epsilon, \quad (8)$$

A, Σ_a, Σ_f are periodic functions on $[0, 1]^3$, system with K equations (number of groups), Σ_a and Σ_f are $K \times K$ matrices, and φ^ϵ is a vector of K components.

Hyp: A is a block-diagonal tensor (coupling only with 0th order terms).

Theorem

Let μ^∞, ψ the smallest eigenvalue of the cell problem, and ψ an associated eigenvector. Let $\mu^{\epsilon, m}$ the m -th eigenvalue of (8), and $\varphi^{\epsilon, m}$ associated eigenvector. Then one has

$$\varphi^{\epsilon, m}(x) = u^m(x) \psi\left(\frac{x}{\epsilon}\right), \mu^{\epsilon, m} = \mu^\infty + \epsilon^2 \nu^m + o(\epsilon^2),$$

where ν^m is the m -th eigenvalue and u^m an associated scalar eigenvector for the problem with Dirichlet boundary conditions in Ω

$$-\operatorname{div}(\bar{D} \nabla u) = \nu \bar{\Sigma} u.$$

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Systems of equations (I)

Neutronics hypothesis: One group. Transport \rightarrow diffusion:

$$\begin{cases} \frac{1}{V} \partial_t \varphi - \operatorname{div}[D(H) \nabla \varphi] + [\Sigma_a(H) - \nu \Sigma_f(H)(1 - \beta)] \varphi - \lambda c = 0, \\ \partial_t c + \lambda c - \nu \Sigma_f(H) \beta \varphi = 0. \end{cases} \quad (9)$$

Thanks to E. Jamelot and F. Madiot, c converges rapidly to its equilibrium ($\frac{\lambda V}{L} \simeq 10^{-2}$), hence $\lambda c = \nu \Sigma_f(H) \beta \varphi$ and

$$\frac{1}{V} \partial_t \varphi - \operatorname{div}[D(H) \nabla \varphi] + [\Sigma_a(H) - \frac{\nu \Sigma_f(H)}{k_{eff}}] \varphi = 0. \quad (10)$$

Seek k_{eff} : multiplication factor. Ideal: $k_{eff} = 1$.

Boundary conditions are needed for φ .

Natural ones: $\varphi \geq 0$ on the domain and $\varphi|_{\partial\Omega} = 0$.

Systèmes (III): hydrodynamics equations

$(\rho, \vec{u}, E$ usual unknowns of density, velocity, energy (that is enthalpy or temperature), p given by an equation of state

$$\left\{ \begin{array}{l} \partial_t \rho + \operatorname{div}(\rho \vec{u}) = 0, \quad (\text{a}) \\ \partial_t(\rho \vec{u}) + \operatorname{div}(\rho \vec{u} \otimes \vec{u}) + \nabla[p(\rho, H)] = \rho \vec{g}, \quad (\text{b}) \\ \partial_t(\rho E) + \operatorname{div}(\rho \vec{u} E) = \mathcal{S}_{H,\varphi}(t, x) + \rho \vec{g} \cdot \vec{u} \quad (\text{c}) \end{array} \right. \quad (11)$$

Source term of energy: $\mathcal{S}_{H,\varphi}(t, x) := \mathbb{E} \Sigma_f(H) \varphi(t, x)$, associated with the power of energy produced $\mathcal{P}(t) = \int_{\Omega} \mathcal{S}_{H,\varphi}(t, x) dx$. The last equation rewrites

$$\partial_t(\rho E) + \nabla \cdot (\rho \vec{u} E) = \mathcal{P}(t) \times \frac{\mathbb{E} \Sigma_f(H) \varphi(t, x)}{\int_{\Omega} \mathbb{E} \Sigma_f(H) \varphi(t, x) dx} + \rho \vec{g} \cdot \vec{u}. \quad (12)$$

Note that we assume no diffusion in the heat equation.

Systèmes (IV): the main assumption on the problem: low Mach number (Dellacherie 2011)

The model studied fits into a category called the **quasi-isobaric models**.

Indeed, in a **low Mach number approximation**, in (11)(b), the pressure (given by the e.o.s) is replaced by what S. D et al call a 'dynamic pressure' π , and in the last equation p is considered as **approximately constant**:

$$p(\rho, H) \rightarrow p + M^2\pi(t, x)$$

Equation of state $p = P_0 := p(\rho, H) \leftrightarrow \rho := \rho(H)$ thanks to $\partial_\rho p < 0$. The equation (11)(c) is replaced by the equation for the enthalpy $\rho(\partial_t H + \vec{u} \cdot \nabla H) = \partial_t p + \vec{u} \cdot \nabla p + \mathbb{E}\Sigma_f(H)\varphi(t, x)$, hence

$$\rho(H)(\partial_t H + \vec{u} \cdot \nabla H) = \mathbb{E}\Sigma_f(H)\varphi(t, x). \quad (13)$$

1d set-up

Coefficients $D(h), \Sigma_a(h), \nu\Sigma_f(h)$ are given functions of h (h replaces H and is linked with T through $h = c_p\rho(h)T$).

Result: exact computation of **the unique solution** on $[0, L]$ of the coupled problem.

Finding k_{eff} such that the system has a stationary solution.

Boundary conditions $\varphi(0) = \varphi(L) = 0$, $h(0) = h_e$ and $h(L) = h_s$ given, $D_e = \rho(h(0))u(0)$ (incoming flux):

One too many conditions if we impose $k_{eff} = 1!!!$

Historical remark: the equation on φ only is a generalized eigenvalue problem, and has been solved, with success.

Coupled 1D model

System:

$$\begin{cases} -\frac{d}{dz}(D(h)\frac{d\varphi}{dz}) + \Sigma_a(h)\varphi = \frac{\nu\Sigma_f(h)}{k_{eff}}\varphi \\ \frac{d}{dz}(\rho(h(z))u(z)h(z)) = \mathbb{E}\nu\Sigma_f(h)\varphi(z) \\ \frac{d}{dz}(\rho(h(z))u(z)) = 0 \end{cases} \quad (14)$$

Non linear system of ODEs of order three with one parameter and four boundary conditions.

Auxiliary functions

Define X et Y the two C^2 vanishing at h_e and h_s functions such that

$$(D(h)\nu\Sigma_f(h)X'(h))' = \frac{\Sigma_a(h)}{\nu\Sigma_f(h)}, (D(h)\nu\Sigma_f(h)Y'(h))' = 1. \quad (15)$$

Remark: if $\frac{\Sigma_a(h)}{\nu\Sigma_f(h)}$ and $D(h)\nu\Sigma_f(h)$ are interpolation polynomials, X and Y are known explicitly.

Remark: with a change of unknown $x(h)$, reduce to solve

$$\frac{d^2}{dx^2}(X(h(x))) = (D\Sigma_a)(h(x)), \frac{d^2}{dx^2}(Y(h(x))) = (D\nu\Sigma_f)(h(x)).$$

Main theoretical result

Theorem

Assume $\Sigma_a(h) \geq \Sigma_a > 0$, $\nu\Sigma_f(h) \geq \Sigma_* > 0$, $D(h) \geq D_0 > 0$, continuous functions.

1. For any L , the equation

$$\int_{h_e}^{h_s} \frac{dh}{\nu\Sigma_f(h)\sqrt{2(X(h) - \frac{1}{k}Y(h))}} = L \quad (16)$$

has a unique solution, denoted by k_{eff} .

2. Let h be the solution of the implicit equality

$$\int_{h_e}^h \frac{dh}{\nu\Sigma_f(h)\sqrt{2(X(h) - \frac{1}{k_{eff}}Y(h))}} = z, \quad \varphi = h', \quad \rho(h(z))u(z) = D_e.$$

The set (φ, h, ρ, u) is the unique solution of (14) satisfying the boundary conditions $\varphi(0) = \varphi(L) = 0$, $h(0) = h_e$ and $h(L) = h_s$.

Calculus

Le débit D_e est donc constant, et après manipulations

$$-\frac{\mathbb{E}}{D_e} \frac{d}{dz} \left(D(h) \frac{d\varphi}{dh} \right) + \frac{\Sigma_a(h)}{\nu \Sigma_f(h)} \frac{dh}{dz} = \frac{1}{k_{eff}} \frac{dh}{dz},$$

que l'on intègre exactement ($S'(h) = \frac{\Sigma_a(h)}{\nu \Sigma_f(h)}$):

$$-\frac{\mathbb{E}}{D_e} D(h) \frac{d\varphi}{dz} + S(h(z)) = \frac{1}{k_{eff}} h + C_0.$$

En multipliant par $\frac{\varphi(z)}{D(h)} = \frac{D_e}{\mathbb{E}} \frac{h'(z)}{\nu \Sigma_f(h) D(h)}$ on obtient

$$X(h) - \frac{1}{k_{eff}} Y(h) = \frac{1}{2} \left(\frac{\mathbb{E}}{D_e} \right)^2 \varphi^2 = \frac{1}{2} \frac{(h')^2}{(\nu \Sigma_f(h))^2}.$$

Proof of item (i): Finding k_{eff}

As $\varphi \geq 0$, $h'(z) = \nu \Sigma_f(h) \sqrt{2(X(h) - \frac{1}{k_{eff}}Y(h))}$, with k_{eff} such that, for all $h \in [h_e, h_s]$, $X(h) - \frac{1}{k_{eff}}Y(h) \geq 0$. Necessarily, $k_{eff} \in (0, \min_{[h_e, h_s]} \frac{Y}{X})$. Equation for k_{eff} :

$$L = \int_{h_e}^{h_s} \frac{dh}{\nu \Sigma_f(h) \sqrt{2(X(h) - \frac{1}{k_{eff}}Y(h))}}.$$

The function $L(k_{eff})$ is strictly increasing, the limit of

$\int_{h_e}^{h_s} \frac{dh}{\nu \Sigma_f(h) \sqrt{2(X(h) - \frac{1}{k_{eff}}Y(h))}}$ when k_{eff} converges to 0 is 0, the

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is $+\infty$, hence a unique solution to this equation.

This problem is nonlinear.

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Numerical integration

$\lambda := \frac{1}{k}$. $\psi_\lambda(h) = X(h) - \lambda Y(h)$. Equation (16) to solve:

$$\int_0^L \frac{h'}{\sqrt{2\psi_\lambda(h)}} = 1.$$

$L = 1$ for the sequel. Integration of the system:

Meshing $0 = z_0 < z_1 < \dots < z_{N-1} < z_N = 1$,

Numerical integration of h (Crank-Nicolson):

$$\frac{h_{j+1} - h_j}{\Delta z_{j+\frac{1}{2}}} = \frac{\varphi_j + \varphi_{j+1}}{2} \quad \Delta z_{j+\frac{1}{2}} = z_{j+1} - z_j \quad (17)$$

$$\varphi_j = \sqrt{\psi_\lambda(h_j)}, \varphi_{j+1} = \sqrt{\psi_\lambda(h_{j+1})},$$

Equation

$$1 = \sum \Delta z_{j+\frac{1}{2}} \Leftrightarrow 2 \sum_{j=0}^{N-1} \frac{h_{j+1} - h_j}{\sqrt{\psi_\lambda(h_j)} + \sqrt{\psi_\lambda(h_{j+1})}} = 1. \quad (18)$$

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