

# Fluid Limits for some MCMC samplers

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Joint work with

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## Outline of the talk

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We are interested in

- ▶ the existence + stability of the fluid limits for skip free Markov Chains.
- ▶ their use in the study of (some) MCMC samplers.

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We will discuss

1. *Fluid Limits* for skip-free Markov Chains.
  - ▶ the existence of *fluid limits*
  - ▶ their characterization
  - ▶ their stability and the stability of the Markov Chain.
2. Applications to Metropolis-Hastings Markov Chains
  - ▶ Convergence of the samplers
  - ▶ How to tune the parameters ?

## MCMC samplers / Hastings-Metropolis \_\_\_\_\_

Sample from a (complex, unnormalized) distribution  $\pi$  on  $\mathbb{R}^d$  when exact sampling is not possible :

Define a Markov Chain  $(\Phi_n, n \geq 0)$ ,  
with unique stationary distribution  $\propto \pi$   
and *ergodic*.

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and *ergodic*.

Ex. Hastings-Metropolis algorithm

Given  $\Phi_t$ , define  $\Phi_{t+1}$  by

- $\Phi_{t+1/2} \sim Q(\Phi_t, \cdot)$ .
  - $\Phi_{t+1} = \begin{cases} \Phi_{t+1/2} & \text{with prob. } \alpha(\Phi_t, \Phi_{t+1/2}) \\ \Phi_t & \text{with prob. } 1 - \alpha(\Phi_t, \Phi_{t+1/2}) \end{cases}$ ,
- where  $\alpha(x, z) = 1 \wedge \frac{\pi(z)Q(z, x)}{\pi(x)Q(x, z)}$ .

# MCMC samplers / Hastings-Metropolis

Problems :

- ▶ (★) Convergence ? (ergodicity)

$$\kappa(n) \quad |\mathbb{E}_x [g(\Phi_n)] - \pi(g)| \rightarrow 0 \quad \forall x, \quad g \in ?$$

- ▶ Limit Theorems

$$n^{-1} \sum_{k=1}^n g(\Phi_k) \xrightarrow{\text{a.s.}} \pi(g) \quad \frac{1}{\sqrt{n}} \sum_{k=1}^n \{g(\Phi_k) - \pi(g)\} \xrightarrow{\text{d}} \mathcal{N}(0, \sigma_g^2).$$

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Hereafter, illustrations in the case

- symmetric HM :  $Q(x, y) = q(|x - y|)$
- $q(z) \sim \sigma \mathcal{N}_d(0, \mathbb{I})[z]$

## Existence of fluid limits (a) \_\_\_\_\_

↪ Define a normalized process

(i) in the initial point

$$\eta_r(0; x) = \frac{1}{r} \Phi_0 = x, \quad \Phi_0 = rx.$$

(ii) in time and space

$$\eta_r(t; x) = \frac{1}{r} \Phi_{\lfloor tr \rfloor},$$

$$\eta_r(t; x) = \frac{1}{r} \Phi_k \quad \text{on } \left[ \frac{k}{r}; \frac{(k+1)}{r} \right).$$

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### ► Distributions

- $\mathbb{P}_x$  : distribution of the Markov Chain with initial distribution  $\delta_x$ .
- $\mathbb{Q}_{r;x}$  : image prob. of  $\mathbb{P}_x$  by  $\eta_r(\cdot; x)$       prob. on the space of càd-làg functions  $\mathbb{R}^+ \rightarrow X$ .

## Existence of fluid limits (b) \_\_\_\_\_

► Définition :  $\mathbb{Q}_x$  is a fluid limit if there exists  $\{r_n\}_n \rightarrow +\infty$ ,  $\{x_n\}_n \rightarrow x$  s.t.

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$$\Phi_{k+1} = \Phi_k + \mathbb{E} [\Phi_{k+1} | \mathcal{F}_k] - \Phi_k + \Phi_{k+1} - \mathbb{E} [\Phi_{k+1} | \mathcal{F}_k]$$

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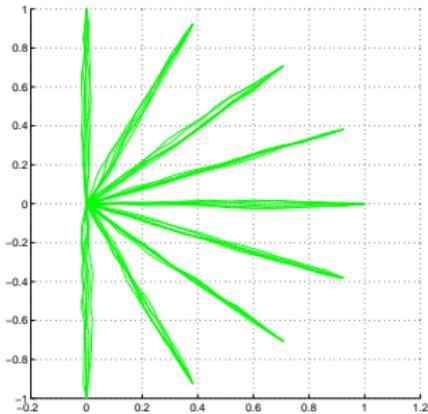
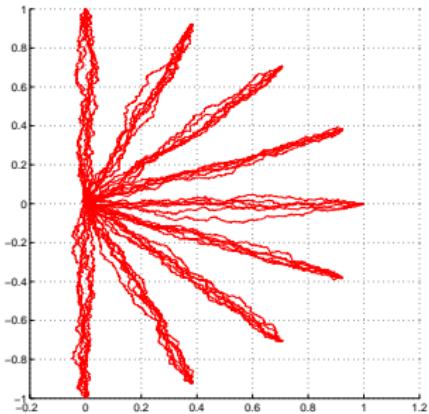
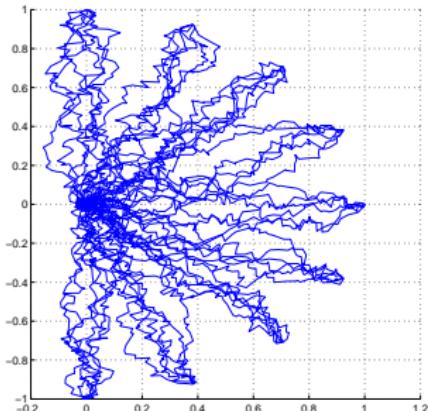
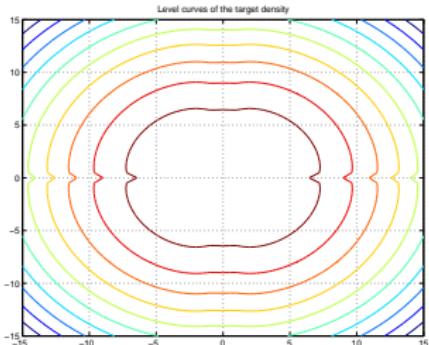
► Result

if

- $\exists p > 1, \quad \lim_{K \rightarrow +\infty} \sup_{x \in \mathbb{X}} \mathbb{E}_x [|\epsilon_1|^p \mathbb{1}_{|\epsilon_1| > K}] \rightarrow 0.$
- $\sup_{x \in \mathbb{X}} |\Delta(x)| < \infty.$

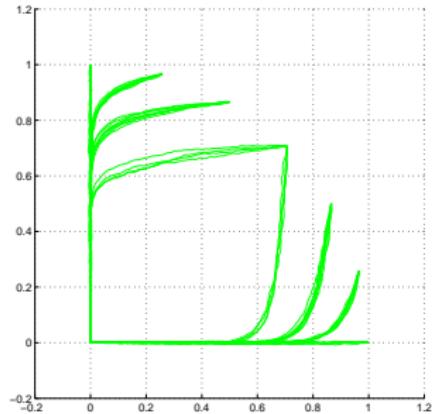
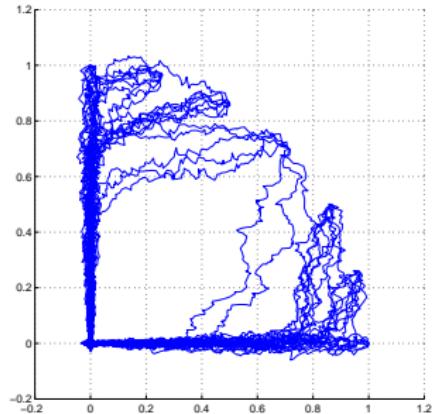
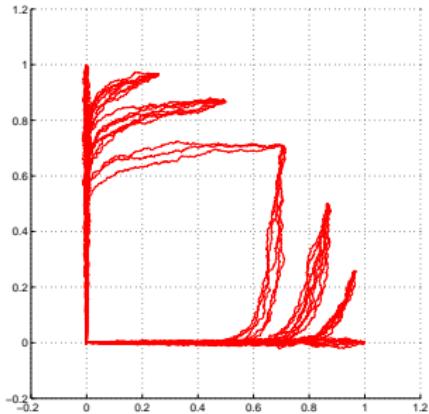
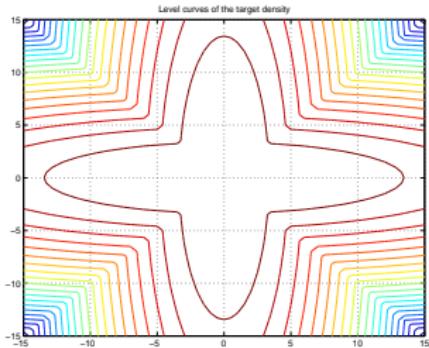
Then fluid limits exist, prob. on the space of continuous functions (whatever the initial point on the unit sphere)

## Example 1 : (regular case) \_\_\_\_\_



$$\pi(x, y) \propto (1 + x^2 + y^2 + x^8 y^2) \exp(-(x^2 + y^2)), \quad q \sim \mathcal{N}(0, 4), \quad r=100, \textcolor{red}{r}=1000, \textcolor{blue}{r}=5000$$

## Example 2 : (irregular case) \_\_\_\_\_

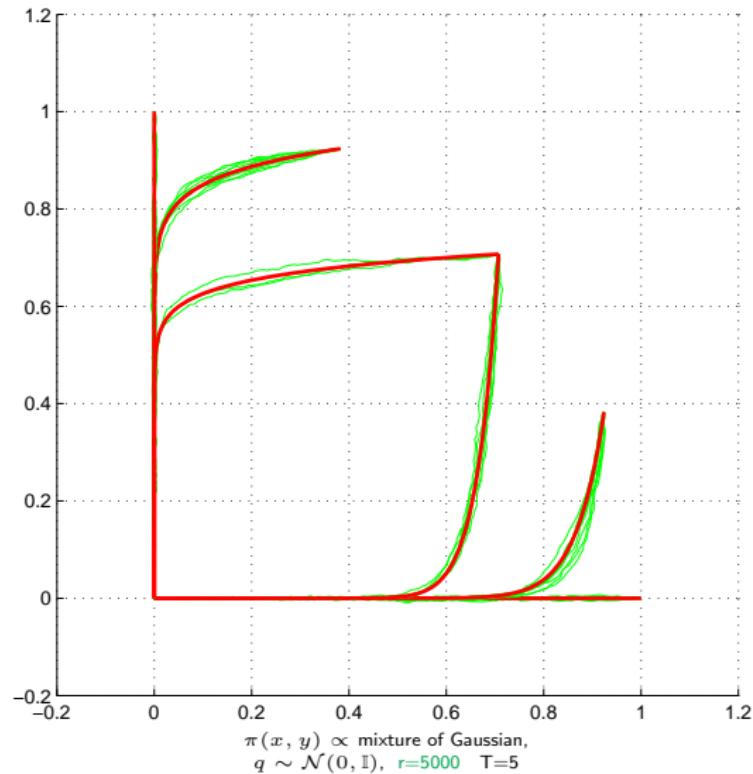


$$\pi(x, y) \propto \mathcal{N}(0, \Gamma_1^{-1}) + \mathcal{N}(0, \Gamma_2^{-1}), \quad q \sim \mathcal{N}(0, 1), \quad r=100, \textcolor{red}{r=1000}, \textcolor{blue}{r=5000}$$

# Characterisation of the fluid limits

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→ Can we describe the distributions  $Q_x$  ?



## Characterization (b) \_\_\_\_\_

$$\Phi_{k+1} = \Phi_k + \underbrace{(\mathbb{E}_x [\Phi_{k+1} | \mathcal{F}_k] - \Phi_k)}_{\Delta(\Phi_k)} + \underbrace{(\Phi_{k+1} - \mathbb{E}_x [\Phi_{k+1} | \mathcal{F}_k])}_{\epsilon_{k+1} \text{ martingale increment}}$$

► For the normalized process

$$\begin{aligned}\eta_r \left[ \frac{k+1}{r}, x \right] &= \frac{1}{r} \Phi_{k+1} \\&= \eta_r \left[ \frac{k}{r}, x \right] + \frac{1}{r} \Delta \left( r \eta_r \left[ \frac{k}{r}, x \right] \right) + \frac{1}{r} \epsilon_{k+1} \\&= \eta_r \left[ \frac{k}{r}, x \right] + \frac{1}{r} h \left( \eta_r \left[ \frac{k}{r}, x \right] \right) + \frac{1}{r} (\xi_k + \epsilon_{k+1})\end{aligned}$$

where

$$h(x) = \lim_{r \rightarrow +\infty} \Delta(r x).$$

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where

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► Thus the dynamic

$$\mu \left( \frac{k+1}{r} \right) = \mu \left( \frac{k}{r} \right) + \frac{1}{r} h \left( \frac{k}{r} \right) \longleftrightarrow \text{ODE : } \dot{\mu}(t) = h(\mu(t))$$

in an additive noise.

## Characterisation (c) \_\_\_\_\_

### ► Theorem

If

- Existence of the fluid limit.
- there exists an open cone  $O$  de  $X \setminus \{0\}$ ,
- $h : O \rightarrow X$  s.t.

$$\sup_{x \in H} |r^\beta \Delta(rx) - |x|^{-\beta} h(x)| \rightarrow 0, \quad r \rightarrow +\infty,$$

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Then for all  $0 \leq s \leq t$ , on  $\{\eta, \eta(u) \in O, s \leq u \leq t\}$ ,

$$\sup_{s \leq u \leq t} \left| \eta(u) - \eta(s) - \int_s^u h \circ \eta(v) \, dv \right| = 0, \quad Q_x^\beta - a.s.$$

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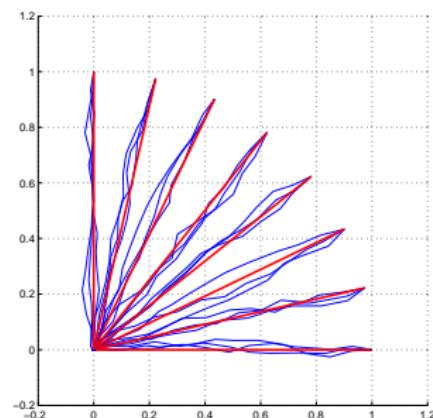
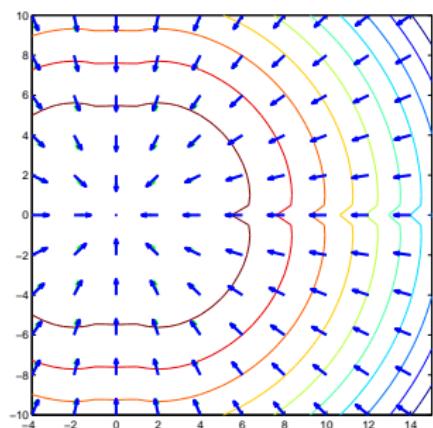
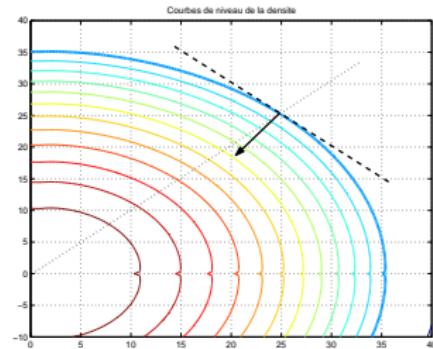
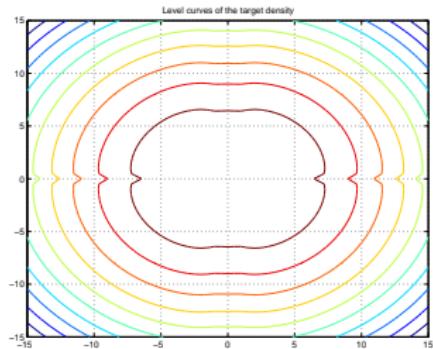
$$\sup_{s \leq u \leq t} \left| \eta(u) - \eta(s) - \int_s^u h \circ \eta(v) \, dv \right| = 0, \quad Q_x^\beta - a.s.$$

► i.e. the fluid limit  $Q_x^\beta$  is a Dirac mass at the point  $\eta$  satisfying

$$\eta(u) = \eta(s) + \int_s^u h \circ \eta(v) \, dv, \quad s \leq u \leq t,$$

whenever  $\eta([s, t]) \subset O$ .

# Example 3 : Super-exponential case, $O = X \setminus \{0\}$ —



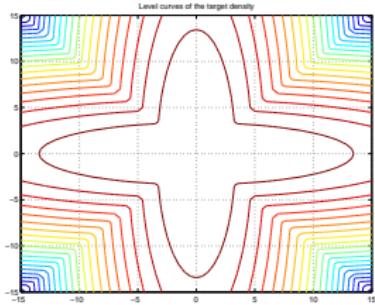
UpperLeft- Level curves of  $\pi$

UpperRight- Rejection area

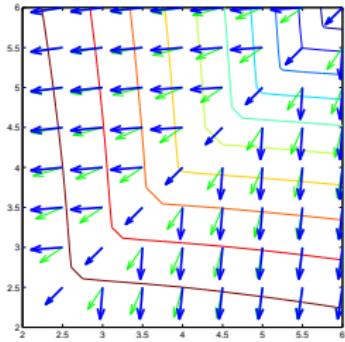
LowerLeft- Level curves,  $\Delta$  and  $h$

LowerRight- Process  $\eta_x^\beta$  and flow of the ODE.

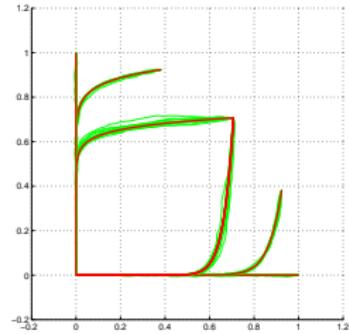
## Example 4 : Super-exponential case, $O \subsetneq X \setminus \{0\}$ —



Level curves of  $\pi$

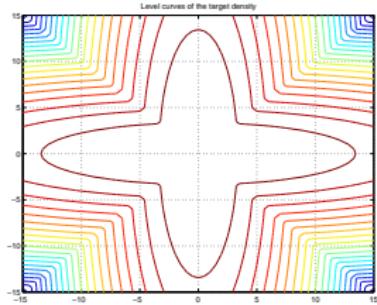


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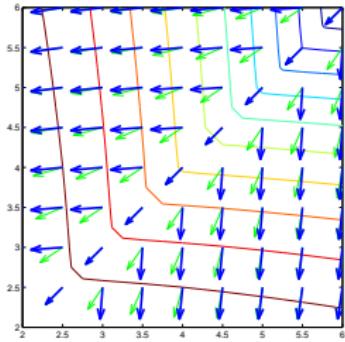


Process  $\eta_x^\beta$  and flow of the ODE.

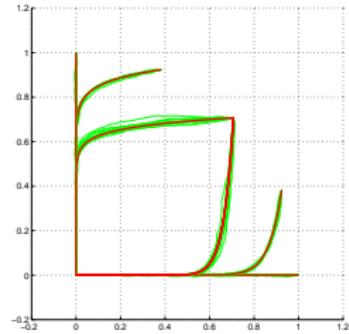
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Level curves of  $\pi$



Level curves,  $\Delta$  and  $h$



Process  $\eta_x^\beta$  and flow of the ODE.

↪ There exists  $T_0 < \infty$  s.t. for all  $x \in X$ ,  $|x| = 1$ , and any fluid limit  $\mathbb{Q}_x$ ,

$$\mathbb{Q}_x(\eta, \eta([0, T_0]) \cap O \neq \emptyset) = 1.$$

## [Appl 1] Stability : fluid limit → Markov Chain \_\_\_\_\_

- A fluid limit is **stable** if  $\exists T > 0$  and  $0 < \rho < 1$ , s.t.

$$\forall x, |x| = 1, \quad \mathbb{Q}_x \left( \eta, \inf_{[0,T]} |\eta(\cdot)| \leq \rho \right) = 1.$$

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- If

- irreducible, aperiodic, compact sets are petite.
- Existence of the fluid limits.
- Stability of the fluid limits.

Then polynomial ergodicity,

$$(n+1)^{q-1} \sup_{\{f, |f| \leq 1 + |x|^{p-q}\}} |\mathbb{E}_x[f(\Phi_n)] - \pi(f)| \rightarrow 0, \quad 1 \leq q \leq p.$$

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- Stability ODE / Stability fluid limit

- (i) Case 1 :  $O = X \setminus \{0\}$

$$\exists T, \rho \quad \forall x, |x| = 1, \quad \inf_{[0,T]} |\mu(\cdot; x)| \leq \rho < 1.$$

- (ii) Case 2 :  $O \neq X \setminus \{0\}$  and  $\mathbb{Q}_x(\eta, \eta([0, T_0]) \cap O \neq \emptyset) = 1$ .

$$\forall K > 0, \exists T_K, \rho_K \quad \forall x \in O, |x| \leq K, \quad \inf_{[0, T_K \wedge T_x]} |\mu(\cdot; x)| \leq \rho_K < 1.$$

## [Appl 2] How to choose the parameters of the algorithms ?

- ▶ Hybrid Hastings-Metropolis :

$$P(x, dy) = \sum_{k=1}^d \omega_k P_k(x, dy) \quad \sum_{k=1}^d \omega_k = 1.$$

- choose a direction  $i \in \{1, \dots, d\}$  with prob.  $\omega_i$ .
- update the component  $i$ -th with a  $\mathbb{R}$ -valued HM (proposal  $\mathcal{N}(0, \sigma_i^2)$ ).

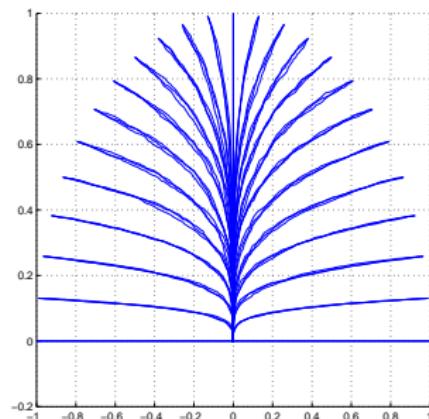
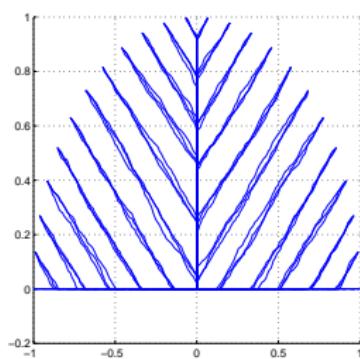
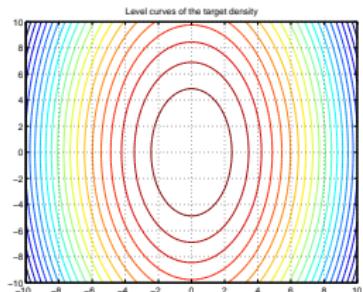
- ▶ Under conditions ...

$$h_i(x) = \frac{1}{\sqrt{2\pi}} \omega_i \sigma_i \operatorname{sign} \left( \lim_{r \rightarrow \infty} \frac{\nabla_i \ln \pi(rx)}{|\nabla \ln \pi(rx)|} \right).$$

- ▶ “Parameters” :  $(\omega_k, \sigma_k)_{1 \leq k \leq d}$ , for ex.

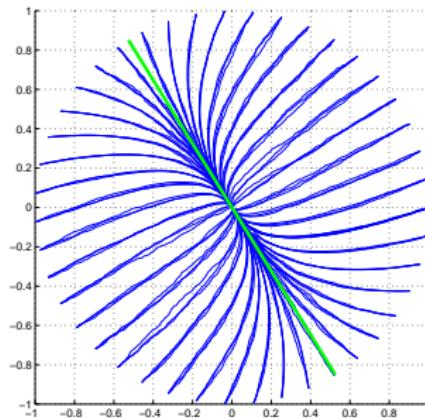
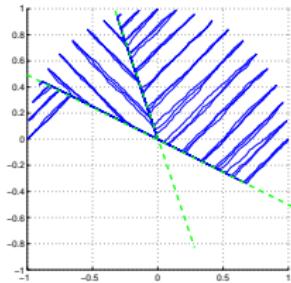
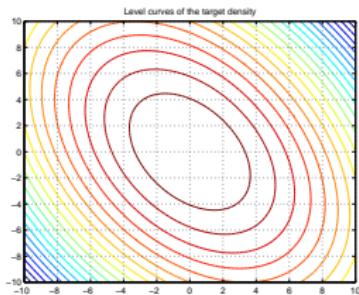
$$\omega_i = \frac{1}{d} \quad \sigma_i = c_i \text{ or } \sigma_i = \ell \lim_{r \rightarrow \infty} \frac{|\nabla_i \ln \pi(rx)|}{|\nabla \ln \pi(rx)|}.$$

## Example 5 : Gaussian $\mathbb{R}^2$ , diagonal dispersion matrix \_\_\_\_\_



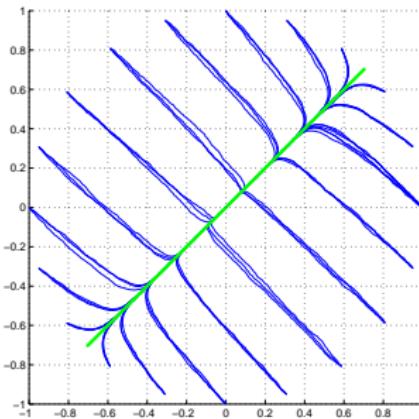
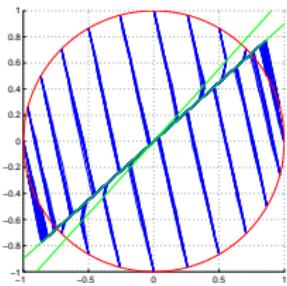
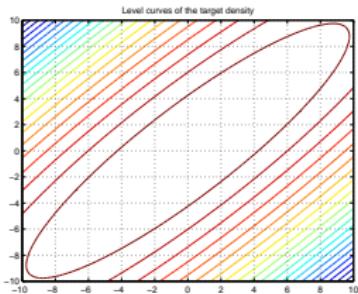
$$\Gamma = \text{diag}(1, 4)$$

## Example 6 : Gaussian $\mathbb{R}^2$ , non-diagonal dispersion matrix \_



$$\Gamma^{-1} = \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix}$$

## Example 7 : Gaussian $\mathbb{R}^2$ , non-diagonal dispersion matrix \_



$$\Gamma^{-1} \propto \begin{bmatrix} 1 & -0.9 \\ -0.9 & 1 \end{bmatrix}$$

$$\sigma_1^2 = 0.5 \quad \sigma_2^2 = 2/0.9$$

## Conclusion

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- ▶ Existence of fluid limits for skip free Markov Chains.
- ▶ [Not Detailed] Case when for some  $0 < \beta < 1$ ,

$$\eta_r(t; x) = \frac{1}{r} \Phi_{\lfloor tr^{1+\beta} \rfloor},$$

→ ergodicity at a lower rate.

- ▶ Characterization of the limit fluid
- ▶ Stable fluid limits → Ergodic Markov Chains, but ...
- ▶ more information on the Markov Chain ... other normalization (diffusion) ?