Maximum de Vraisemblance et Validation Croisée pour l'estimation des hyper-paramètres de covariance pour le Krigeage

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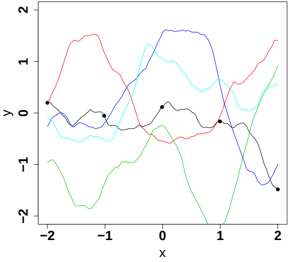
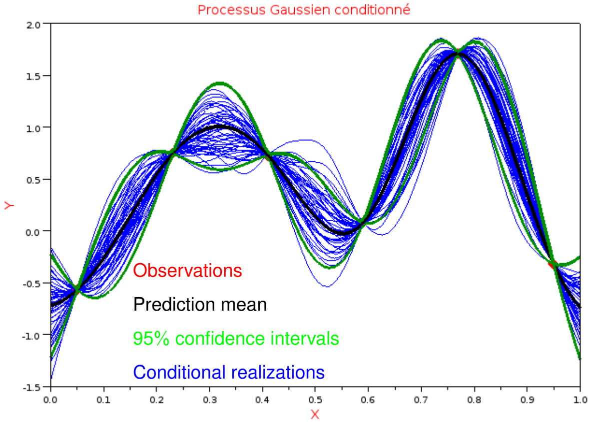
Kriging model with Gaussian process

Basic idea : representing a deterministic and unknown function as the realization of a Gaussian process



Notation
Gaussian process Y defined on the set $\mathcal{X}$.

When the distribution of the Gaussian process is known



All this from explicit matrix vector formula

Covariance function estimation

Parameterization

Covariance function model $\left\{\sigma^2 K_\theta, \sigma^2 \geq 0, \theta \in \Theta\right\}$ for the Gaussian Process Y.

- σ^2 is the variance hyper-parameter
- θ is the multidimensional correlation hyper-parameter. K_θ is a stationary correlation function.

Estimation

Y is observed at $x_1, ..., x_n \in \mathcal{X}$, yielding the Gaussian vector $y = (Y(x_1), ..., Y(x_n))$.
Estimators $\hat{\sigma}^2(y)$ and $\hat{\theta}(y)$

"Plug-in" Kriging prediction

1. Estimate the covariance function
2. Assume that the covariance function is fixed and carry out the explicit Kriging equations

Maximum Likelihood for estimation

Explicit Gaussian likelihood function for the observation vector y

Maximum Likelihood

Define $\mathbf{R}_\theta$ as the correlation matrix of $y = (Y(x_1), ..., Y(x_n))$ under correlation function K_θ.
The Maximum Likelihood estimator of (σ^2, θ) is

$$(\hat{\sigma}^2_{ML}, \hat{\theta}_{ML}) \in \underset{\sigma^2 \geq 0, \theta \in \Theta}{\operatorname{argmin}} \frac{1}{n} \left(\ln\left(|\sigma^2 \mathbf{R}_\theta|\right) + \frac{1}{\sigma^2} y^t \mathbf{R}_\theta^{-1} y \right)$$

Cross Validation for estimation

- $\hat{y}_{\theta,i,-i} = \mathbb{E}_{\sigma^2,\theta}(Y(x_i)|y_1,...,y_{i-1},y_{i+1},...,y_n)$
- $\sigma^2 c^2_{\theta,i,-i} = var_{\sigma^2,\theta}(Y(x_i)|y_1,...,y_{i-1},y_{i+1},...,y_n)$

Leave-One-Out criteria we study

$$\hat{\theta}_{CV} \in \operatorname*{argmin}_{\theta\in\Theta} \sum_{i=1}^{n} (y_i - \hat{y}_{\theta,i,-i})^2$$

and

$$\frac{1}{n}\sum_{i=1}^{n}\frac{(y_i - \hat{y}_{\hat{\theta}_{CV},i,-i})^2}{\hat{\sigma}^2_{CV} c^2_{\hat{\theta}_{CV},i,-i}} = 1 \Leftrightarrow \hat{\sigma}^2_{CV} = \frac{1}{n}\sum_{i=1}^{n}\frac{(y_i - \hat{y}_{\hat{\theta}_{CV},i,-i})^2}{c^2_{\hat{\theta}_{CV},i,-i}}$$

Virtual Leave One Out formula

Let $\mathbf{R}_\theta$ be the covariance matrix of $y = (y_1, ..., y_n)$ with correlation function K_θ and $\sigma^2 = 1$

Virtual Leave-One-Out

$$y_i - \hat{y}_{\theta,i,-i} = (diag(\mathbf{R}_\theta^{-1}))^{-1}\mathbf{R}_\theta^{-1} y \quad \text{and} \quad c^2_{i,-i} = \frac{1}{(\mathbf{R}_\theta^{-1})_{i,i}}$$

O. Dubrule, Cross Validation of Kriging in a Unique Neighborhood, *Mathematical Geology*, 1983.

Using the virtual Cross Validation formula :

$$\hat{\theta}_{CV} \in \underset{\theta\in\Theta}{\operatorname{argmin}} \frac{1}{n} y^t \mathbf{R}_\theta^{-1} diag(\mathbf{R}_\theta^{-1})^{-2} \mathbf{R}_\theta^{-1} y$$

and

$$\hat{\sigma}^2_{CV} = \frac{1}{n} y^t \mathbf{R}_{\hat{\theta}_{CV}}^{-1} diag(\mathbf{R}_{\hat{\theta}_{CV}}^{-1})^{-1} \mathbf{R}_{\hat{\theta}_{CV}}^{-1} y$$

Objectives

We want to study the cases of model misspecification, that is to say the cases when the true covariance function K_1 of Y is far from $\mathcal{K} = \left\{\sigma^2 K_\theta, \sigma^2 \geq 0, \theta \in \Theta\right\}$

In this context we want to compare Leave-One-Out and Maximum Likelihood estimators from the point of view of prediction mean square error and point-wise estimation of the prediction mean square error

We proceed in two steps

- When $\mathcal{K} = \left\{\sigma^2 K_2, \sigma^2 \geq 0\right\}$, with K_2 a correlation function, and K_1 the true unit-variance covariance function : theoretical formula and numerical tests
- In the general case : numerical studies

Case of variance hyper-parameter estimation

- $\hat{Y}(x_{new})$: Kriging prediction with fixed misspecified correlation function K_2
- $\mathbb{E}\left[(\hat{Y}(x_{new}) - Y(x_{new}))^2 | y\right]$: conditional mean square error of the non-optimal prediction
- One estimates σ^2 by $\hat{\sigma}^2$.
- Conditional mean square error of $\hat{Y}(x_{new})$ estimated by $\hat{\sigma}^2 c^2_{x_{new}}$ with $c^2_{x_{new}}$ fixed by K_2

The Risk

We study the Risk criterion for an estimator $\hat{\sigma}^2$ of σ^2

$$\mathcal{R}_{\hat{\sigma}^2, x_{new}} = \mathbb{E}\left[\left(\mathbb{E}\left[(\hat{Y}(x_{new}) - Y(x_{new}))^2 | y\right] - \hat{\sigma}^2 c^2_{x_{new}}\right)^2\right]$$

$\longrightarrow$ Explicit formula for estimators of σ^2 that are quadratic forms of the observation vector

Summary of numerical results

For variance hyper-parameter estimation

- We make the distance between K_1 and K_2 vary, starting from 0
- For not too regular design of experiments : CV is more robust than ML to misspecification
  - Larger variance but smaller bias for CV
  - The bias term becomes dominating when $K_1 \neq K_2$
- For regular design of experiments, CV is less robust to model misspecification

For variance and correlation hyper-parameter estimation

- Numerical study on analytical functions
- Confirmation of the results of the variance estimation case

Bachoc F, Cross Validation and Maximum Likelihood estimations of hyper-parameters of Gaussian processes with model misspecification, *Computational Statistics and Data Analysis (2013), http ://dx.doi.org/10.1016/j.csda.2013.03.016*.

Introduction to Kriging and covariance function estimation

Finite sample analysis of ML and CV under model misspecification

Asymptotic analysis of ML and CV in the well-specified case

Conclusion

Framework and objectives

Estimation

We do not make use of the distinction σ^2, θ. Hence we use the set $\{K_\theta, \theta \in \Theta\}$ of stationary covariance functions for the estimation.

Well-specified model

The true covariance function K of the Gaussian Process belongs to the set $\{K_\theta, \theta \in \Theta\}$. Hence

$$K = K_{\theta_0}, \theta_0 \in \Theta$$

Objectives

- Study the consistency and asymptotic distribution of the Cross Validation estimator
- Confirm that, asymptotically, Maximum Likelihood is more efficient
- Study the influence of the spatial sampling on the estimation

Spatial sampling for hyper-parameter estimation

- Spatial sampling : Initial design of experiment for Kriging
- It has been shown that irregular spatial sampling is often an advantage for hyper-parameter estimation
  - Stein M, Interpolation of Spatial Data : Some Theory for Kriging, *Springer, New York, 1999. Ch.6.9.*
  - Zhu Z, Zhang H, Spatial sampling design under the infill asymptotics framework, *Environmetrics 17 (2006) 323-337.*
- Our question : Is irregular sampling always better than regular sampling for hyper-parameter estimation ?

Asymptotics for hyper-parameters estimation

Asymptotics (number of observations $n \to +\infty$) is an area of active research (Maximum-Likelihood estimator)

Two main asymptotic frameworks

- fixed-domain asymptotics : The observations are dense in a bounded domain
  From 80'-90' and onwards. Fruitful theory

  Stein, M., Interpolation of Spatial Data Some Theory for Kriging, *Springer, New York, 1999*.

  However, when convergence in distribution is proved, the asymptotic distribution does not depend on the spatial sampling $\longrightarrow$ Impossible to compare sampling techniques for estimation in this context
- increasing-domain asymptotics : A minimum spacing exists between the observation points $\longrightarrow$ infinite observation domain.
  Asymptotic normality proved for Maximum-Likelihood under general conditions

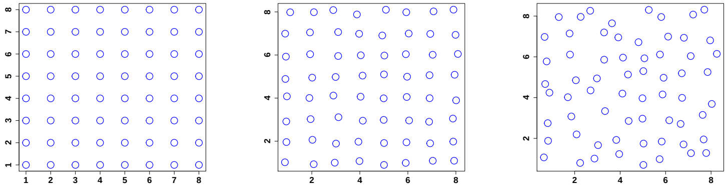
  Sweeting, T., Uniform asymptotic normality of the maximum likelihood estimator, *Annals of Statistics 8 (1980) 1375-1381*.

  Mardia K, Marshall R, Maximum likelihood estimation of models for residual covariance in spatial regression, *Biometrika 71 (1984) 135-146*.

Randomly perturbed regular grid

- Our sampling model : regular square grid of step one in dimension d, $(v_i)_{i \in \mathbb{N}^*}$. The observation points are the $v_i + \epsilon X_i$. The $(X_i)_{i \in \mathbb{N}^*}$ are *iid* and uniform on $[-1, 1]^d$
- $\epsilon \in]-\frac{1}{2}, \frac{1}{2}[$ is the regularity parameter. $\epsilon = 0 \longrightarrow$ regular grid. $|\epsilon|$ close to $\frac{1}{2} \longrightarrow$ irregularity is maximal

Illustration with $\epsilon = 0, \frac{1}{8}, \frac{3}{8}$



Main result

Under general conditions

For ML

- a.s convergence of the random Fisher information : The random trace $\frac{1}{n} Tr \left(\mathbf{R}_{\theta_0}^{-1} \frac{\partial \mathbf{R}_{\theta_0}}{\partial \theta_i} \mathbf{R}_{\theta_0}^{-1} \frac{\partial \mathbf{R}_{\theta_0}}{\partial \theta_j} \right)$ converges a.s to the element $(\mathbf{I}_{ML})_{i,j}$ of a $p \times p$ deterministic matrix $\mathbf{I}_{ML}$ as $n \to +\infty$
- asymptotic normality : With $\Sigma_{ML} = 2\mathbf{I}_{ML}^{-1}$

$$\sqrt{n} \left(\hat{\theta}_{ML} - \theta_0 \right) \to \mathcal{N} \left(0, \Sigma_{ML} \right)$$

For CV

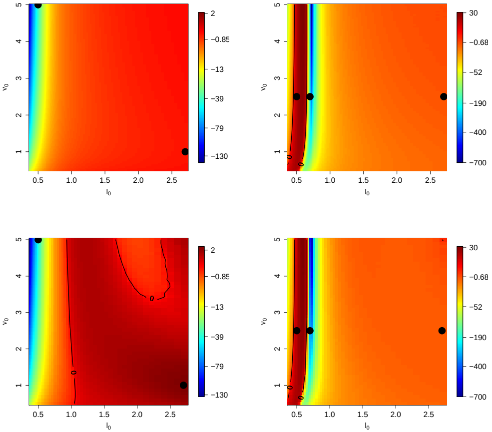
Same result with more complex random traces for asymptotic covariance matrix Σ_{CV}

$\Sigma_{ML,CV}$ depends only on the regularity parameter ϵ.
$\boxed{\longrightarrow}$ in the sequel, we study the functions $\epsilon \to \Sigma_{ML,CV}$

Small random perturbations of the regular grid

Matèrn model. Dimension one. One estimated hyper-parameter.
Levels plot of $(\partial_\epsilon^2 \Sigma_{ML,CV})/\Sigma_{ML,CV}$ in $\ell_0 \times \nu_0$

Top : ML
Bot : CV
Left : $\hat{\ell}$ (ν_0 known)
Right : $\hat{\nu}$ (ℓ_0 known)

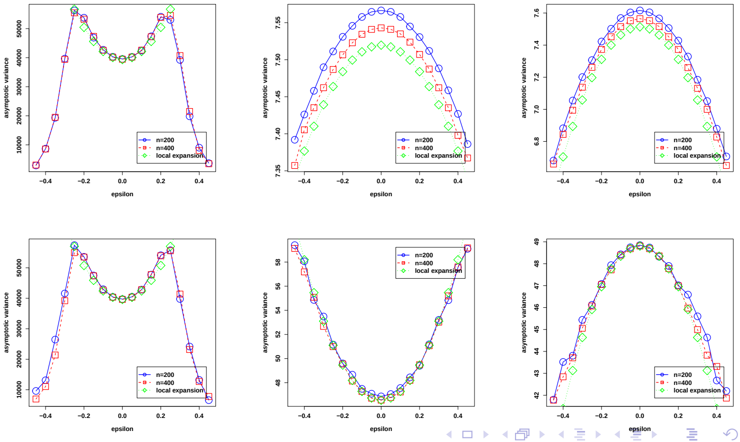


There exist cases of degradation of the estimation for small perturbation for ML and CV. Not easy to interpret

Large random perturbations of the regular grid

Plot of $\Sigma_{ML,CV}$. Top : ML. Bot : CV.

From left to right : $(\hat{\nu}, \ell_0 = 0.5, \nu_0 = 2.5)$, $(\hat{\ell}, \ell_0 = 2.7, \nu_0 = 1)$, $(\hat{\nu}, \ell_0 = 2.7, \nu_0 = 2.5)$



Conclusion on the well-specified case

- CV is consistent and has the same rate of convergence than ML
- We confirm that ML is more efficient
- Irregularity in the sampling is generally an advantage for the estimation, but not necessarily
  - With ML, irregular sampling is more often an advantage than with CV
  - Large perturbations of the regular grid are often better than small ones for estimation
  - Keep in mind that hyper-parameter estimation and Kriging prediction are strongly different criteria for a spatial sampling

For further details :

Bachoc F, Asymptotic analysis of the role of spatial sampling for hyper-parameter estimation of Gaussian processes, *Submitted, available at http ://arxiv.org/abs/1301.4321*.

Conclusion

General conclusion

- ML preferable to CV in the well-specified case
- In the misspecified-case, with not too regular design of experiments : CV preferable because of its smaller bias
- In both misspecified and well-specified cases : the estimation benefits from an irregular sampling
- The variance of CV is larger than that of ML in all the cases studied.

Perspectives

- Designing other CV procedures (LOO error ponderation, decorrelation and penalty term) to reduce the variance

Thank you for your attention !