

# I Laplace equation

## 1) The Laplacian of a function

Let  $\Omega \subset \mathbb{R}^N$  be an open set and  $u \in C^2(\Omega)$ .

The Laplacian  $\Delta u$  is defined by

$$\Delta u := \sum_{j=1}^N \frac{\partial^2 u}{\partial x_j^2}$$

Proposition 1 (elementary properties of  $\Delta$ ). Let  $u \in C^2(\Omega)$

1)  $\Delta u = \operatorname{div}(\nabla u)$

2) Polar coordinates:  $\Delta f = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$

3) for radial functions:  $\Delta u = u'' + \frac{N-1}{r} u'$  if  $u(x) = v(|x|)$ .

4)  $\mathbb{R}^2 \simeq \mathbb{C}$   $\partial_z = \frac{1}{2} \left( \frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right)$ ,  $\partial_{\bar{z}} = \frac{1}{2} \left( \frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right)$ . Hence  $\Delta = 4 \partial_z \partial_{\bar{z}}$

Proof: exercise

Exercise: ~~Prove~~ Suppose  $N=3$  and  $(r, \theta, \phi)$  are spherical coordinates.

prove that

$$\Delta f = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

## 2) Some calculus theorems

Let  $\Omega \subset \mathbb{R}^N$  be a bounded open set with  $C^1$  boundary.

We denote the unit outward normal vector at a point  $x \in \partial \Omega$  by  $\nu$ .

and  $\frac{\partial u}{\partial \nu} := \nu \cdot \nabla u$  is the normal derivative of  $u \in C^1(\bar{\Omega})$ .

Theorem: let  $u, v \in C^2(\bar{\Omega})$ . Then

$$1) \int_{\Omega} \operatorname{div}(u) \, dx = \int_{\partial\Omega} u \cdot \nu \, d\sigma \quad (\text{divergence theorem, also called Gauss-Green, Gauss, Ostrogradsky, ...})$$

$$2) \int_{\Omega} \operatorname{div}(u \nu) \, dx = - \int_{\Omega} u \operatorname{div}(\nu) \, dx + \int_{\partial\Omega} u \nu \cdot \nu \, d\sigma$$

$$3) \int_{\Omega} \Delta u \, dx = \int_{\partial\Omega} \frac{\partial u}{\partial \nu} \, d\sigma$$

$$\bullet \int_{\Omega} \nabla_{\nu} \nabla u \, dx = - \int_{\Omega} u \Delta \nu + \int_{\partial\Omega} \frac{\partial \nu}{\partial \mu} u \, d\sigma$$

$$\bullet \int_{\Omega} u \Delta \nu - \nu \Delta u \, dx = \int_{\partial\Omega} u \frac{\partial \nu}{\partial \mu} - \nu \frac{\partial u}{\partial \mu} \, d\sigma$$

Green's formulas

~~Exercise~~

Exercise: Admit 1) and prove 2) and 3).

### 3) Harmonic functions

Def: A function  $u \in C^2(\Omega)$  is said to be harmonic if  $\Delta u = 0$  in  $\Omega$ .

$$\Delta u = 0 \text{ in } \Omega.$$

Rq:  $\mathbb{R}^2 \simeq \mathbb{C}$ . Every holomorphic function is harmonic.

a) The mean value property.

Theorem: let  $u \in C^2(\bar{\Omega})$  be an harmonic function. Then for all ball

$B = B_R(x) \subset \subset \Omega$  we have

$$u(x) = \frac{1}{\omega_N R^{N-1}} \int_{\partial B} u \, d\sigma = \frac{1}{\omega_N R^N} \int_B u \, dx \quad (\text{here, } \omega_N \text{ is the volume of the unit sphere } \omega_N = \frac{2\pi^{N/2}}{N\Gamma(N/2)})$$

Proof: Consider the function

$$\phi(r) := \frac{1}{N\omega_N r^{N-1}} \int_{\partial B_r(x)} u(y) d\sigma$$

1) Remark that  $\frac{1}{N\omega_N r^{N-1}} \int_{\partial B_r(x)} u(y) d\sigma = \frac{1}{\omega_N} \int_{\partial B_1(0)} u(x+r\zeta) d\sigma$

2) Compute the derivative of  $\phi$ :

$$\begin{aligned} \phi'(r) &= \frac{1}{\omega_N} \int_{\partial B_1(0)} \nabla u(x+r\zeta) \cdot \zeta d\sigma \\ &= \frac{1}{\omega_N} \int_{\partial B_1(0)} \frac{\partial u}{\partial r}(x+r\zeta) d\sigma \\ &= \frac{1}{N\omega_N r^{N-1}} \int_{\partial B_r(x)} \frac{\partial u}{\partial r}(y) d\sigma \end{aligned}$$

Apply Green formula, we get

$$\phi'(r) = \frac{1}{N\omega_N r^{N-1}} \int_{B_r(x)} \Delta u(y) dy = 0$$

Hence  $\phi$  is constant.

3) Prove that  $\lim_{r \rightarrow 0} \phi(r) = u(x)$  and conclude for the first equality

4) Using that  $\int_{B(x,r)} u dy = \int_0^r \left( \int_{\partial B(x,\tau)} u d\sigma \right) d\tau$

prove the second equality

Theorem (converse to mean value property)

$$\text{Let } u \in C^2(\Omega) \text{ satisfy } u(x) = \frac{1}{N \omega_N r^{N-1}} \int_{\partial B_r(x)} u(y) dy$$

for each ball  $B(x, r) \subset \Omega$ . Then  $u$  is harmonic

Proof: Choose  $r$  s.t.  $\Delta u > 0$  in  $B(x, r)$  and find a contradiction with  $\phi$  as above.

b) Maximum principles

Theorem (strong maximum principle): Suppose that  $\Omega$  is connected.

Let  $u \in C^2(\Omega)$  <sup>be harmonic</sup> and suppose that there exists  $x \in \Omega$  s.t.

$$u(x) = \max_{y \in \Omega} u(y).$$

Then  $u$  is constant

Proof: Let  $r$  be such that  $B_r(x) \subset \Omega$ .

$$\text{Then } u(x) = \frac{1}{\omega_N r^N} \int_{B_r(x)} u(y) dy \leq u(x).$$

It is possible only if  $u \equiv u(x)$  in  $B_r(x)$ .

Consider the set  $\{y \in \Omega; u(y) = u(x)\}$ .

The above argument show that it is ~~closed~~ open in  $\Omega$ .

On the <sup>other</sup> hand, since  $u$  is  $C^0$ , it is also closed.

Hence it is  $\Omega$ .

Theorem (weak maximum principle)  $\Omega$  ~~connected~~ ~~and~~ bounded

Let  $u \in C^2(\Omega) \cap C^0(\bar{\Omega})$  be an harmonic function.

Then  $\max_{y \in \bar{\Omega}} u(y) = \max_{y \in \partial\Omega} u(y)$ .

Proof: Apply the strong max principle.

Rk: Similar results are available with max replaced by min.

Exercise: Let  $\Omega$  be <sup>and bounded</sup> connected and  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  be a solution of

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

Where  $g \geq 0$  and there exists  $x \in \partial\Omega$  s.t.  $g(x) > 0$ . Prove that  $u > 0$ .

c) Uniqueness

Theorem: Let  $g \in C(\partial\Omega)$ . There exists at most one solution  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  of

$$\begin{cases} -\Delta u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

Proof: Supp that  $u, v$  satisfy the eq and apply the max principle to  $u-v$ .

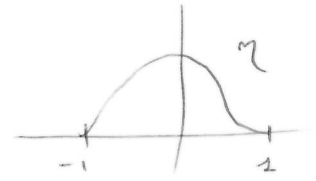
d) Regularity:

Theorem: Let  $u \in C(\Omega)$  satisfy the mean value property in  $\Omega$ .

Then  $u \in C^\infty(\Omega)$ .

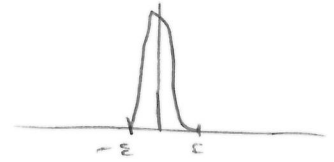
Proof: Consider a standard mollifier: Define  $\eta \in C^\infty(\mathbb{R}^n)$  by

$$\eta(x) := \begin{cases} C \exp\left(\frac{1}{|x|^2-1}\right) & \text{if } |x| < 1 \\ 0 & \text{if } |x| \geq 1 \end{cases}$$



with  $C$  s.t.  $\int_{\mathbb{R}^n} \eta \, dx = 1$

for all  $\varepsilon > 0$ , set  $\eta_\varepsilon(x) := \frac{1}{\varepsilon^n} \eta\left(\frac{x}{\varepsilon}\right)$



Let  $u_\varepsilon = \eta_\varepsilon * u$  in  $\Omega_\varepsilon := \{x \in \Omega \mid \text{dist}(x, \partial\Omega) > \varepsilon\}$ .

Since  $u_\varepsilon$  is a convolution product,  $u_\varepsilon \in C^\infty(\Omega_\varepsilon)$ .

\* Prove that  $u \equiv u_\varepsilon$  on  $\Omega_\varepsilon$

Let  $x \in \Omega_\varepsilon$ .

$$u_\varepsilon(x) = \int_{\Omega} \eta_\varepsilon(x-y) u(y) \, dy = \frac{1}{\varepsilon^n} \int_{B(x, \varepsilon)} \eta\left(\frac{|x-y|}{\varepsilon}\right) u(y) \, dy$$

$$= \frac{1}{\varepsilon^n} \int_0^\varepsilon \eta\left(\frac{r}{\varepsilon}\right) \left( \int_{\partial B(x, r)} u \, d\sigma \right) dr$$

$$= \frac{1}{\varepsilon^n} \int_0^\varepsilon \eta\left(\frac{r}{\varepsilon}\right) N \omega_N r^{n-1} \, dr$$

$$= \frac{u(x)}{\varepsilon^n} \int_{B(0, \varepsilon)} \eta_\varepsilon \, dy = u(x)$$

Rk: Deduce from the last th an improvement of the Th on  $f \in C^0 + \text{mean v.}$   
 $\Rightarrow$  harmonicity

e) estimates on derivatives

Theorem: Assume  $u$  is harmonic in  $\Omega$ . Then

$$|D^\alpha u(x)| \leq \frac{C_k}{r^{N+k}} \|u\|_{L^1(B(x,r))}$$

for each ball  $B(x,r) \subset \Omega$  and each multiindex  $\alpha$  of length  $|\alpha|=k$ .

(Moreover, the constants  $C_k$  are explicitly known:

$$C_0 = \frac{1}{\omega_N}, \quad C_k = \frac{\binom{N+k}{k}}{\omega_N}$$

Proof: By induction.

•  $k=0$  ok by mean value formula

•  $k \geq 1$ . Recall  $u \in C^\infty(\Omega)$ , so we can differentiate  $\Delta u = 0$  to get

$$\Delta \frac{\partial u}{\partial x_j} = 0$$

Hence  $\frac{\partial u}{\partial x_j}$  is harmonic and verifies

$$\left| \frac{\partial u}{\partial x_j} \right|_{\int_{B(x, \frac{r}{2})}} = \frac{1}{\omega_N} \int_{\partial B(x, \frac{r}{2})} \frac{\partial u}{\partial x_j} d\sigma$$

$$= \left| \left( \frac{2}{r} \right)^N \frac{1}{\omega_N} \int_{\partial B(x, \frac{r}{2})} u \nu_i d\sigma \right| \leq \frac{2^N}{r} \int_{\partial B(x, \frac{r}{2})} \|u\|_{L^\infty(\partial B(x, \frac{r}{2}))}$$

for any  $y \in \partial B(x, \frac{r}{2})$ , we have  $B(y, \frac{r}{2}) \subset B(x, r)$  and so

$$|u(y)| \leq \frac{1}{\omega_N} \left( \frac{2}{r} \right)^N \|u\|_{L^1(B(x, r))}$$

• for  $k \geq 1$  exercise

### f) Liebnitz's theorem

Theorem: Suppose  $u: \mathbb{R}^N \rightarrow \mathbb{R}$  is harmonic and bounded. Then  $u$  is constant.

Proof: fix  $x \in \mathbb{R}^N$ ,  $r > 0$ . Then

$$|\nabla u(x)| \leq \frac{C}{r^{N+1}} \|u\|_{L^1(B(x,r))} \leq \frac{C}{r} \|u\|_{L^\infty(\mathbb{R}^N)} \xrightarrow{r \rightarrow \infty} 0$$

Hence  $\nabla u \equiv 0$  and  $u$  is constant.

### g) Analyticity

Theorem: Assume  $u$  is harmonic in  $\Omega$ . Then  $u$  is analytic in  $\Omega$ .

Proof: admitted (see Evans).

### h) Harnack's inequality

Theorem: For each connected open set  $V \subset \subset \Omega$ , there exists  $C$  depending only on  $V$ , such that for all nonnegative harmonic functions  $u$  in  $\Omega$  one has

$$\sup_V u \leq C \inf_V u.$$

Proof: Let  $r := \frac{1}{4} \text{dist}(V, \Omega^c)$ . Let  $x_0 \in V$  and  $x, y \in B(x_0, r)$ . Then

$$u(x) = \frac{1}{\omega_N r^N} \int_{B(x, 2r)} u \, dz \leq \frac{1}{\omega_N r^N} \int_{B(x_0, 2r)} u \, dz = 2^N u(x_0).$$

$$u(y) = \frac{1}{\omega_N (3r)^N} \int_{B(y, 3r)} u \, dz \geq \frac{1}{\omega_N (3r)^N} \int_{B(x_0, 3r)} u \, dz \geq \frac{1}{3^N} u(x_0) \quad \text{and similarly}$$



(9)

$$u(y) = \frac{1}{\omega_N (2r)^N} \int_{B(y, 2r)} u dz \geq \frac{1}{\omega_N (2r)^N} \int_{B(x_0, r)} u dz = 2^N u(x_0).$$

Covering  $V$  with a finite number of balls gives the result.

#### 4) The fundamental solution of the Laplacian

Aim: find an "elementary" explicit solution to the Laplace equation in  $\mathbb{R}^N$

We look for a solution to

$$\Delta u = 0 \quad \text{in } \mathbb{R}^N \setminus \{0\}$$

Idea: we ~~restrict~~ <sup>restrict</sup> ourselves to the search of a radial function, i.e.

to some  $v: \mathbb{R}^+ \rightarrow \mathbb{R}$  s.t.  $u(x) = v(|x|)$ .

Recall: 
$$\Delta u = v'' + \frac{N-1}{r} v'$$

Hence we search  $v$  s.t.

$$v'' + \frac{N-1}{r} v' = 0$$

Multiplying by  $r^{N-1}$ , we get

$$r^{N-1} v'' + (N-1) r^{N-2} v' = 0$$

Therefore,  $(r^{N-1} v')' = 0$

Thus  $r^{N-1} v' = C_1$

i.e.  $v' = \frac{C_1}{r^{N-1}}$  for  $r \neq 0$ .

If  $N \geq 3$ , we obtain  $v(r) = \frac{c_1}{r^{N-2}} + c_2$

If  $N=2$ , we get  $v(r) = c_1 \ln(r) + c_2$

For reasons that will appear later, we fix  $c_2 = 0$  and  $c_1 = -\frac{1}{2\pi}$

if  $N=2$ ,  $\frac{1}{N(N-2)\omega_N}$  if  $N \geq 3$ .

Definition: The function

$$\underline{\Phi} : \mathbb{R}^N \setminus \{0\} \rightarrow \mathbb{R}$$

$$x \mapsto \underline{\Phi}(x) = \begin{cases} -\frac{1}{2\pi} \log |x| & \text{if } N=2 \\ \frac{1}{N(N-2)\omega_N} \frac{1}{|x|^{N-2}} & \text{if } N \geq 3 \end{cases}$$

is called the fundamental solution of the Laplacian.

## II Poisson's equation

### 1) Poisson's equation in $\mathbb{R}^N$

Theorem: Let  $f \in C_c^2(\mathbb{R}^N)$ . Then the function

$$u(x) := (\underline{\Phi} * f)(x) = \int_{\mathbb{R}^N} \underline{\Phi}(y) f(x-y) dy$$

is  $C^2(\mathbb{R}^N)$  and satisfies the Poisson equation

$$-\Delta u = f \text{ in } \mathbb{R}^N$$

Proof: admitted (see the course).

Representation formula for bounded solutions.

Theorem: Let  $N \geq 3$  and  $f \in C_c^2(\mathbb{R}^N)$ . Then if  $u$  is a bounded solution

$$-\Delta u = f \text{ in } \mathbb{R}^N$$

then  $u$  is of the form

$$u = \Phi * f + C$$

for some constant  $C \in \mathbb{R}$ .

Proof: For  $N \geq 3$ ,  $\Phi(x) \rightarrow 0$  as  $|x| \rightarrow +\infty$ , hence  $\Phi * f$  is a bounded solution. Let  $u$  be another bounded solution. Then  $u - \Phi * f$  verifies

$$\Delta u = 0 \text{ in } \mathbb{R}^N$$

and  $u - \Phi * f$  is bounded. From Liouville theorem, we conclude that

$$u - \Phi * f = C.$$

2) Green's functions:

Let  $\Omega \subset \mathbb{R}^N$  be an open, bounded set with a  $C^2$  boundary.

We are looking for solution to the equation

$$(P) \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases} \quad \text{where } f \in C(\Omega) \text{ and } g \in C(\partial\Omega).$$

a) derivation of Green's functions

Let  $u \in C^2(\bar{\Omega})$  be a solution of (P). Fix  $x \in \Omega$ ,  $\varepsilon > 0$  s.t.  $B(x, \varepsilon) \subset \Omega$

and apply Green's formula on the region  $V_\varepsilon := \Omega - B(x, \varepsilon)$  to  $u$  and  $\Phi(\cdot - x)$

$$\int_{V_\varepsilon} u(y) \Delta \bar{\Phi}(y-x) - \bar{\Phi}(y-x) \Delta u(y) dy$$

$$= \int_{\partial V_\varepsilon} u(y) \frac{\partial \bar{\Phi}}{\partial \nu}(y-x) - \bar{\Phi}(y-x) \frac{\partial u}{\partial \nu}(y) d\sigma \quad (*)$$

Observe that:

• since  $\bar{\Phi}$  is harmonic in  $\mathbb{R}^n \setminus \{0\}$ , we have  $\Delta \bar{\Phi}(x-y) = 0$  if  $x \neq y$ .

$$\bullet \int_{\partial B(x, \varepsilon)} u(y) \frac{\partial \bar{\Phi}}{\partial \nu}(y-x) dy = -\bar{\Phi}'(\varepsilon) \int_{\partial B(x, \varepsilon)} u(y) dy$$

$$= \frac{-1}{N\omega_N \varepsilon^{N-1}} \int_{\partial B(x, \varepsilon)} u(y) dy \rightarrow -u(x) \text{ as } \varepsilon \rightarrow 0.$$

$$\bullet \int_{\partial B(x, \varepsilon)} \bar{\Phi}(y-x) \frac{\partial u}{\partial \nu}(y) d\sigma = \bar{\Phi}(\varepsilon) \int_{\partial B(x, \varepsilon)} \frac{\partial u}{\partial \nu}(y) d\sigma$$

$$\leq C \bar{\Phi}(\varepsilon) N\omega_N \varepsilon^{N-1} \|\nabla u\|_{C^\infty(\partial B(x, \varepsilon))} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0.$$

Sending  $\varepsilon \rightarrow 0$  in (\*), we get

$$\int_{\partial \Omega} u(y) \frac{\partial \bar{\Phi}}{\partial \nu}(y-x) - \bar{\Phi}(y-x) \frac{\partial u}{\partial \nu}(y) d\sigma - u(x)$$

$$= - \int_{\Omega} \bar{\Phi}(y-x) \Delta u(y) dy$$

And therefore

$$u(x) = \int_{\Omega} \Phi(y-x) \Delta u(y) dy + \int_{\partial\Omega} u(y) \left( \frac{\partial \Phi}{\partial \nu}(y-x) - \Phi(y-x) \frac{\partial u}{\partial \nu}(y) \right) d\sigma. \quad (**)$$

This would give us a good representation formula for  $u$ , except that we do not know the value of  $\frac{\partial u}{\partial \nu}$  along  $\partial\Omega$ .

To overcome this difficulty, we introduce the function  $\phi(x,y)$  that for fixed  $x$  solves

$$\begin{cases} \Delta \phi(x, \cdot) = 0 & \text{in } \Omega \\ \phi(x, \cdot) = \Phi(\cdot - x) & \text{on } \partial\Omega \end{cases}$$

Applying again Green's formula, we get

$$\int_{\Omega} \underbrace{u(y) \Delta \phi(x,y)}_0 - \phi(x,y) \Delta u(y) dy = \int_{\partial\Omega} u(y) \frac{\partial \phi(x,y)}{\partial \nu} d\sigma - \int_{\partial\Omega} \phi(x,y) \frac{\partial u}{\partial \nu}(y) d\sigma$$

Hence

$$(***) \quad - \int_{\Omega} \phi(x,y) \Delta u(y) dy = \int_{\partial\Omega} u(y) \frac{\partial \phi(x,y)}{\partial \nu} d\sigma - \int_{\partial\Omega} \Phi(y-x) \frac{\partial u}{\partial \nu}(y) d\sigma$$

Adding (\*\*) and (\*\*\*), we get

$$u(x) = \int_{\Omega} (\Phi(y-x) - \phi(x,y)) \Delta u(y) dy + \int_{\partial\Omega} u(y) \left( \frac{\partial \Phi}{\partial \nu}(y-x) - \frac{\partial \phi(x,y)}{\partial \nu} \right) d\sigma$$

Definition: The Green's function for the domain  $\Omega$  is

$$G(x, y) = \overline{\Phi}(y-x) - \phi(x, y) \quad (x, y \in \Omega, x \neq y).$$

Theorem: If  $u \in C^2(\overline{\Omega})$  solves

$$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

Then

$$u(x) = \int_{\Omega} f(y) G(x, y) dy + \int_{\partial\Omega} g(y) \frac{\partial G}{\partial \nu}(x, y) d\sigma.$$

Rk:  $G$  is the solution of

$$\begin{cases} -\Delta G = \delta_x & \text{in } \Omega \\ G = 0 & \text{on } \partial\Omega \end{cases}$$

Exercise: Prove the symmetry of the Green function:

$$\forall x, y \in \Omega, \quad G(x, y) = G(y, x)$$

b) Green's function for the half-space

$$\mathbb{R}_+^N := \{ (x_1, \dots, x_N) \in \mathbb{R}^N ; x_N > 0 \}$$

Def: for  $x = (x_1, \dots, x_N) \in \mathbb{R}_+^N$ , its reflection according to the plane  $\partial \mathbb{R}_+^N$

is  $\tilde{x} = (x_1, \dots, x_{N-1}, -x_N)$ .

fix  $x \in \mathbb{R}^N$

We look for  $\phi(x, y)$  s.t.

$$(1) \begin{cases} \Delta \phi(x, y) = 0 & \text{in } \mathbb{R}_+^N \\ \phi(x, y) = \underline{\Phi}(y-x) & \text{on } \partial \mathbb{R}_+^N \end{cases}$$

$\underline{\Phi}(y-x)$  would be a good candidate to solve this equation, except that there is a singularity at  $y=x$ . To avoid that, we reflect the singularity outside  $\mathbb{R}_+^N$ :

let  $\phi(x, y) := \underline{\Phi}(y-x) - \underline{\Phi}(y-\tilde{x})$ .

Then  $\phi$  satisfies (1).

Def: The Green function for the half space  $\mathbb{R}_+^N$  is

$$G(x, y) := \underline{\Phi}(y-x) - \underline{\Phi}(y-\tilde{x})$$

Exercise: Compute  $\frac{\partial G}{\partial x_N}(x, y)$ .

$$\frac{\partial G}{\partial y_N}(x, y) = \frac{-1}{N\omega_N} \left[ \frac{y_N - x_N}{|y-x|^N} - \frac{y_N + x_N}{|y-\tilde{x}|^N} \right]$$

$$\Rightarrow \frac{\partial G}{\partial x_N}(x, y) = -\frac{\partial G}{\partial y_N}(x, y) = \frac{-2x_N}{N\omega_N |x-y|^N}$$

We want now to solve the problem

$$\begin{cases} \Delta u = 0 & \text{in } \mathbb{R}_+^N \\ u = g & \text{on } \partial \mathbb{R}_+^N \end{cases}$$

We ~~expect~~ expect that the solution will be

$$(2) \quad u(x) := \frac{2x_N}{N\omega_N} \int_{\partial \mathbb{R}_+^N} \frac{g(y)}{|x-y|^N} dy$$

Vocabulary: The function  $K(x,y) := \frac{2x_N}{N\omega_N} \frac{1}{|x-y|^N}$

is called the Poisson kernel and the above formula the Poisson formula

Thm: Assume  $g \in C(\mathbb{R}^{N-1}) \cap L^\infty(\mathbb{R}^{N-1})$  and let  $u$  be defined by (2). Then

(i)  $u \in C^\infty(\mathbb{R}_+^N) \cap L^\infty(\mathbb{R}_+^N)$

(ii)  $\Delta u = 0$  in  $\mathbb{R}_+^N$

and (iii)  $\lim_{\substack{y \rightarrow x \\ y \in \mathbb{R}_+^N}} u(y) = g(x) \quad \forall x \in \partial \mathbb{R}_+^N$ .

Proof: 1) for fixed  $x$ , the function  $y \mapsto G(x,y)$  is harmonic if  $y \neq x$  and for fixed  $y$ ,  $x \mapsto G(x,y)$  if  $x \neq y$ .

Thus  $x \mapsto -\frac{\partial G}{\partial y_N}(x,y) = K(x,y)$  is harmonic for  $x \in \mathbb{R}_+^N, y \in \partial \mathbb{R}_+^N$



• We have 
$$\int_{\partial \mathbb{R}_+^N} u(x, y) dy = 1 \quad \forall x \in \mathbb{R}_+^N.$$

Since  $g$  is bounded, this implies  $u$  is b.d.

Since  $x \mapsto u(x, y)$  is smooth,  $u$  is smooth

and 
$$\Delta u(x) = \int_{\partial \mathbb{R}_+^N} \Delta_x u(x, y) g(y) dy = 0 \quad \forall x \in \mathbb{R}_+^N$$

• Fix  $x_0 \in \partial \mathbb{R}_+^N$ ,  $\varepsilon > 0$ , let  $\delta > 0$  s.t.

$$|y - x_0| < \delta \Rightarrow |g(y) - g(x_0)| < \varepsilon \quad \forall y \in \partial \mathbb{R}_+^N.$$

If  $|x - x_0| < \frac{\delta}{2}$  ( $x \in \mathbb{R}_+^N$ ).

$$|u(x) - g(x_0)| = \left| \int_{\partial \mathbb{R}_+^N} u(x, y) [g(y) - g(x_0)] dy \right|$$

$$\leq \underbrace{\int_{\partial \mathbb{R}_+^N \cap B(x_0, \delta)} u(x, y) |g(y) - g(x_0)| dy}_{\text{I}} + \underbrace{\int_{\partial \mathbb{R}_+^N \setminus B(x_0, \delta)} u(x, y) |g(y) - g(x_0)| dy}_{\text{J}}$$

Clear that  $\text{I} \leq \varepsilon$ .

For  $\text{J}$ , req that if  $|u - u_0| < \frac{\varepsilon}{2}$  and  $|y - x_0| \geq \delta$  then

$$|y - x_0| \leq |y - x| + \frac{\delta}{2} \leq |y - x| + \frac{1}{2} |y - x_0|$$

$$\Rightarrow |y - x| \geq \frac{1}{2} |y - x_0|$$

Thus

$$\begin{aligned}
 I &\leq 2 \|g\|_{L^\infty} \int_{\mathbb{R}^N \setminus B(x_0, d)} K(x, y) dy \\
 &\leq \frac{2^{N+2} \|g\|_{L^\infty}}{N \omega_N} x_N \int |y - x_0|^{-N} dy \rightarrow 0 \quad \text{as } x_N \rightarrow 0
 \end{aligned}$$

### c) Green's function for a ball

We define Green function on the unit ball  $B(0, 1)$  of  $\mathbb{R}^N$ .

Def: If  $x \in \mathbb{R}^N \setminus \{0\}$ ,  $\tilde{x} = \frac{x}{|x|^2}$  is the dual point of  $x$ .

We look for

$$\begin{cases} \Delta \phi(x, y) = 0 \\ \phi(x, y) = \underline{\Phi}(y, \tilde{x}) \text{ on } \partial B(0, 1) \end{cases}$$

We define  $\phi(x, y) := \underline{\Phi}(|x|(y - \tilde{x}))$ .

Exercise: check that  $\phi$  is the good  $g_{ct}$ .

• Define the Green function  $G$ .

• Check that  $\frac{\partial G}{\partial \nu}(x, y) = \frac{-\underline{\Phi}(1 - |x|^2)}{N \omega_N |x - y|^N}$ .

### 3) Dirichlet's principle

$\Omega$  open, bounded with  $C^1$  boundary.

$$(P) \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

We define the energy functional  $I$  by

$$I(v) := \int_{\Omega} \frac{1}{2} |\nabla v|^2 - f v \, dx$$

for any  $v$  belonging to the admissible set

$$\mathcal{A} := \{ v \in C^2(\bar{\Omega}); v = g \text{ on } \partial\Omega \}$$

Thm: ~~Assume that  $u \in C^2(\bar{\Omega})$  solves (P).~~

Then let  $u \in \mathcal{A}$ . The following assertions are equivalent:

- (i)  $I(u) = \min_{v \in \mathcal{A}} I(v)$ ,
- (ii)  $u$  solves (P).

proof: • (i)  $\Rightarrow$  (ii).

fix any  $v \in C_c^\infty(\Omega)$  and write

$$i(t) := I(u + tv) \text{ for } t \in \mathbb{R}.$$

Let that  $i(t)$  is well defined since  $u + tv \in \mathcal{A}$  for any  $t \in \mathbb{R}$ .

By (i), the function  $i$  has a minimum at 0, and thus

$$i'(0) = 0.$$

Note that

$$\begin{aligned}
i(t) &= \int_{\Omega} \frac{1}{2} |\nabla u + t \nabla v|^2 + (u + tv)f \, dx \\
&= \int_{\Omega} \frac{1}{2} (|\nabla u|^2 + t \nabla u \nabla v + \frac{t^2}{2} |\nabla v|^2 - uf - tvf) \, dx.
\end{aligned}$$

Thus  $i$  is differentiable and

$$i'(t) = \int_{\Omega} \nabla u \nabla v + t |\nabla v|^2 - vf \, dx$$

In particular

$$0 = i'(0) = \int_{\Omega} \nabla u \nabla v - vf \, dx.$$

Integrating by part, we get

$$\int_{\Omega} (-\Delta u - f)v \, dx = 0.$$

This is valid for any  $v \in C_c^\infty(\Omega)$ , thus  $-\Delta u = f$  in  $\Omega$  and  $u$  verifies (i).

• (ii)  $\Rightarrow$  (i).

Let  $v \in A$ . Since  $u$  verifies (P), we have

$$0 = \int_{\Omega} (-\Delta u - f)(u - v) \, dx$$

by part:

$$0 = \int_{\Omega} \nabla u \nabla(u - v) - f(u - v) \, dx.$$

No boundary term since  $u - v = 0$  on  $\partial\Omega$ .

Hence

$$\begin{aligned} \int_{\Omega} |\nabla u|^2 - uf &= \int_{\Omega} \nabla u \nabla v - vf \, dx \\ &\leq \int_{\Omega} \frac{1}{2} |\nabla u|^2 + \frac{1}{2} |\nabla v|^2 - vf \, dx \end{aligned}$$

Thus  $I(u) \leq I(v)$ .

4) A variational principle for the first eigenvalue of Laplace operator.

Let  $\Omega$  be open and bounded.

We consider the <sup>unbounded</sup> operator  $-\Delta : L^2(\mathbb{R}^N) \rightarrow L^2(\mathbb{R}^N)$  with domain  $H_0^1(\Omega)$ .

Thm: ~~The eigenvalues of  $-\Delta$~~

The spectrum of  $-\Delta$  is a sequence of real, positive eigenvalues  $\{\lambda_k\}$  such that  $\lambda_k \rightarrow +\infty$  (if the eigenvalues are ordered by increasing values), and there exist an orthonormal basis  $\{e_k\}$  of  $L^2(\Omega)$  ~~constituted~~ formed by eigenvectors of  $-\Delta$ . Here  $e_k \in H_0^1(\Omega) \cap C^\infty(\bar{\Omega})$  for each  $k$ .

Def:  $\lambda_1$  is called the principal or first e.v. of  $-\Delta$ .

Thm: (i)  $\lambda_1 = \min \left\{ \int_{\Omega} |\nabla u|^2 \, dx; u \in H_0^1(\Omega), \|u\|_{L^2(\Omega)} = 1 \right\}$ .

(ii)  $\lambda_1$  is simple and  $e_1$  can be chosen to be positive

Proof: Remark first that

$$\int_{\Omega} |\nabla e_k|^2 = - \int_{\Omega} (\Delta e_k) e_k = \lambda_k \|e_k\|_{L^2(\Omega)}^2 = \lambda_k, \quad (1)$$

and

$$\int_{\Omega} \nabla e_k \nabla e_l = \lambda_k \int_{\Omega} e_k e_l = 0 \text{ if } k \neq l, \quad (2)$$

• Take  $u \in H_0^1(\Omega)$  with  $\|u\|_{L^2(\Omega)} = 1$ .

Since  $\{e_k\}$  is an orthonormal basis of  $L^2(\Omega)$ , we have

$$u = \sum_{k=1}^{\infty} \alpha_k e_k \quad \text{for } \alpha_k = (u, e_k)_2$$

$$\text{and } \|u\|_{L^2(\Omega)}^2 = \sum_{k=1}^{\infty} \alpha_k^2 = 1$$

• Let  $w_k := \frac{e_k}{\sqrt{|\lambda_k|}}$ . We claim that  $\{w_k\}$  is an orthonormal basis of  $H_0^1(\Omega)$

for the scalar product  $\int_{\Omega} \nabla \cdot \nabla \cdot$ .

From (1) and (2), it is clearly an orthonormal subset.

Thus, it is enough to prove that if

$$\int_{\Omega} \nabla e_k \nabla u = 0 \quad \forall k, \text{ then } u \equiv 0$$

Since  $\int_{\Omega} \nabla e_k \nabla u = \lambda_k \int_{\Omega} e_k u$ , it is clearly the case.

• We have thus

$$\int_{\Omega} |\nabla u|^2 = \sum_{k=1}^{\infty} \int_{\Omega} \nabla e_k \nabla u = \sum_{k=1}^{\infty} \lambda_k \alpha_k^2 \geq \lambda_1 \sum_{k=1}^{\infty} \alpha_k^2 = \lambda_1$$

since  $\int_{\Omega} |\nabla e_1|^2 = \lambda_1$ , (i) is proved.

• Suppose now that  $\|u\|_L = 1$ ,  $u \in H_0^1(\Omega)$  and  $\int |\nabla u|^2 = \lambda_1$ .

We have

$$\int |\nabla u|^2 = \sum_{k=1}^{\infty} \lambda_k \alpha_k^2 = \lambda_1 = \sum_{k=1}^{\infty} \lambda_k \alpha_k^2$$

$$\text{Thus } \sum_{k=1}^{\infty} (\lambda_k - \lambda_1) \alpha_k^2 = 0$$

which implies  $\alpha_k = 0$  if  $\lambda_k > \lambda_1$ , and ~~then~~ therefore  ~~$(u, e_k)$~~

$$u = \alpha_1 e_1 = \sum_{k=1}^m \alpha_k e_k \quad \text{with } \Delta e_k = \lambda_k e_k \text{ for } k=1, \dots, m$$

which implies  $-\Delta u = \lambda_1 u$ .

• Recall that  $|u| \in H_0^1(\Omega)$ . ~~Moreover~~, and  $\int |\nabla u|^2 \gg \int |\nabla |u||^2$ .

$$\text{Then } \int |\nabla |u||^2 = \lambda_1 \text{ and } \begin{cases} -\Delta |u| = \lambda_1 |u| & \text{in } \Omega \\ |u| = 0 & \text{on } \partial\Omega \end{cases}$$

Thus, by the maximum principle,  $|u| > 0$  in  $\Omega$ .

So  $u > 0$  or  $u < 0$  in  $\Omega$ .

• Finally, given two solutions  $u, v$  of  $\begin{cases} -\Delta u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$

we have, up to a sign change,

$$\int u > 0, \int v > 0 \text{ and there exist } C \text{ s.t.}$$

$$\int_{\Omega} u - Cv = 0$$

$\Rightarrow u = Cv$  in  $\Omega$ , hence  $\lambda_1$  is simple.

### III Wave equation

1) In one space dimension.

$$(w) \begin{cases} u_{tt} - u_{xx} = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ u = g, \quad u_t = h & \text{on } \mathbb{R} \times \{t=0\} \end{cases}$$

We want a representation formula for  $u$  in terms of  $g$  and  $h$ .

Re: factorisation of (w):

$$\left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x}\right) \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x}\right) u = u_{tt} - u_{xx}$$

Write  $v = u_t - u_x$ .

Then  $v_t + v_x = 0$ .

This is a 1-D transport equation, whose solutions are given by

$$v(x, t) = a(x-t) \quad \text{with} \quad a(x) = v(x, 0).$$

Therefore,

$$u_t - u_x = a(x-t).$$

This is a non homogeneous transport eq whose solution is given by

$$\begin{aligned} u(x, t) &= \int_0^t a(x + (t-s) - s) ds + b(x+t) \\ &= \frac{1}{2} \int_{x-t}^{x+t} a(y) dy + b(x+t) \end{aligned}$$

with  $b(x) = u(x, 0)$ .

It remains to compute  $a$  and  $b$ .



first, it is clear that  $b(x) = u(x, 0) = g(x)$ .

Also,  $a(x) = v(x, 0) = u_t(x, 0) - u_x(x, 0) = h(x) - g'(x)$ .

Hence

$$u(x, t) = \frac{1}{2} \int_{x-t}^{x+t} h(y) - g'(y) dy + g(x+t)$$

$$u(x, t) = \frac{1}{2} [g(x+t) + g(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} h(y) dy \quad (d'A)$$

This is d'Alembert formula.

Thm: Assume  $g \in C^2(\mathbb{R})$ ,  $h \in C^1(\mathbb{R})$  and assume  $u$  is given by (d'A). Then  $u \in C^2(\mathbb{R} \times [0, \infty))$  and verifies (w).

Exercise:

(a) Show that the general solution of  $u_{xy} = 0$  is

$$u(x, y) = f(x) + G(y).$$

for any  $f$  and  $G$

(b) Using  $\xi = x+t$ ,  $\eta = x-t$ , show  $u_{\xi\xi} - u_{\eta\eta} = 0 \Leftrightarrow u_{\xi\eta} = 0$

(c) Deduce d'Alembert formula.

On the half line

$$\begin{cases} u_{tt} - u_{xx} = 0 & \text{in } \mathbb{R}_+ \times (0, \infty) \\ u = g, \quad u_t = h & \text{on } \mathbb{R}_+ \times \{t=0\} \\ u = 0 & \text{on } \{x=0\} \times (0, \infty) \end{cases}$$

\*  $g(0) = h(0) = 0$

We adapt (d'Alambert) by odd reflection

$$\tilde{u}(x,t) := \begin{cases} u(x,t) & x \geq 0 \\ -u(-x,t) & x \leq 0 \end{cases}$$

$$\tilde{g}(x) := \begin{cases} g(x) & x \geq 0 \\ -g(-x) & x \leq 0 \end{cases}$$

$$\tilde{h}(x) := \begin{cases} h(x) & x \geq 0 \\ -h(-x) & x \leq 0 \end{cases}$$

Then 
$$\begin{cases} \tilde{u}_{tt} - \tilde{u}_{xx} = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ \tilde{u} = \tilde{g}, \quad \tilde{u}_t = \tilde{h} & \text{on } \mathbb{R} \times \{t=0\} \end{cases}$$

Then 
$$\tilde{u}(x,t) = \frac{1}{2} [\tilde{g}(x+t) + \tilde{g}(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} \tilde{h}(y) dy$$

Thus

$$u(x,t) = \begin{cases} \frac{1}{2} [g(x+t) + g(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} h(y) dy & x \geq t \\ \frac{1}{2} [g(x+t) - g(t-x)] + \frac{1}{2} \int_{-x+t}^{x+t} h(y) dy & x \leq t \end{cases}$$

### 2) Spherical means

Let  $N \geq 2, k \geq 2$  and  $u \in C^k(\mathbb{R}^N \times [0, \infty))$  solves

$$\begin{cases} u_{tt} - \Delta u = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ u = g, \quad u_t = h & \text{on } \mathbb{R}^N \times \{t=0\} \end{cases}$$

Def for  $x \in \mathbb{R}^N, t > 0, r > 0$ .

Define 
$$U(x, r, t) := \frac{1}{\text{vol}(\partial B(x, r))} \int_{\partial B(x, r)} u(y, t) \, d\sigma$$

$$G(x, r) := \int_{\partial B(x, r)} g(y) \, d\sigma$$

$$H(x, r) := \int_{\partial B(x, r)} h(y) \, d\sigma$$

Lemma: Fix  $x \in \mathbb{R}^N$ . Then  $U \in C^k(\mathbb{R}_+ \times [0, \infty))$  and

$$\begin{cases} U_{tt} - U_{rr} - \frac{N-1}{r} U_r = 0 & \text{in } \mathbb{R}_+ \times (0, \infty) \\ U = G, \quad U_t = H & \text{on } \mathbb{R}_+ \times \{0\} \end{cases}$$

proof: (Ex).

$$1) \quad U_r(x, r, t) = \frac{r}{N} \int_{\partial B(x, r)} \Delta u(y, t) \, dy.$$

$$U_{rr}(x, r, t) = \int_{\partial B(x, r)} \Delta u \, d\sigma + \left(\frac{1}{N} - 1\right) \int_{\partial B(x, r)} \Delta u \, dy.$$

...  $\Rightarrow u \in C^k$

$$2) \int U_r = \frac{R}{2} \int_{B(x,r)} u_{tt} dy$$

$$= \frac{1}{N\omega_N r^{N-1}} \int_{B(x,r)} u_{tt} dy$$

$$\Rightarrow r^{N-1} U_r = \frac{1}{N\omega_N} \int_{B(x,r)} u_{tt} dy$$

$$\left( r^{N-1} U_r \right)_r = \frac{1}{N\omega_N} \int_{\partial B(x,r)} u_{tt} d\sigma$$

$$= r^{N-1} \int_{\partial B(x,r)} u_{tt} d\sigma = r^{N-1} U_{tt}$$

3) Solution for N=3

Let  $\tilde{U} := rU, \tilde{G} = rG, \tilde{H} := rH$

Then 
$$\begin{cases} \tilde{U}_{tt} - \tilde{U}_{rr} = 0 & \text{on } \mathbb{R}_+ \times (0, \infty) \\ \tilde{U} = \tilde{G}, \tilde{U}_t = \tilde{H} & \text{on } \mathbb{R}_+ \times \{0\} \\ \tilde{U} = 0 & \text{on } \{0\} \times (0, \infty) \end{cases}$$

From the result on the half line, we get

$$\tilde{U}(x,r,t) = \frac{1}{2} \left[ \tilde{G}(r+t) - \tilde{G}(t-r) \right] + \frac{1}{2} \int_{-r+t}^{r+t} \tilde{H}(y) dy \quad \text{for } r \leq t$$

On the other hand, since

$$u(x, t) = \lim_{\epsilon \rightarrow 0} U(x, \epsilon, t), \text{ we get}$$

$$\begin{aligned}
u(x, t) &= \lim_{\epsilon \rightarrow 0} \frac{\tilde{U}}{\epsilon} \\
&= \lim_{\epsilon \rightarrow 0} \frac{\tilde{G}(x+\epsilon) - \tilde{G}(x-\epsilon)}{2\epsilon} + \frac{1}{2\epsilon} \int_{x-\epsilon}^{x+\epsilon} \tilde{H}(y) dy \\
&= \tilde{G}'(x) + \tilde{H}(x)
\end{aligned}$$

thus

$$u(x, t) = \frac{d}{dt} \left( t \int_{\partial B(x, t)} g d\sigma \right) + t \int_{\partial B(x, t)} h d\sigma$$

We have  $\int_{\partial B(x, t)} g(y) d\sigma = \int_{\partial B(0, 1)} g(x+tz) d\sigma$

$$\begin{aligned}
\text{Thus } \frac{d}{dt} \left( \int_{\partial B(x, t)} g(y) d\sigma \right) &= \int_{\partial B(0, 1)} \nabla g(x+tz) \cdot z d\sigma \\
&= \int_{\partial B(x, t)} \nabla g(y) \cdot \frac{y-x}{\epsilon} d\sigma
\end{aligned}$$

Therefore,

$$u(x,t) = \int_{\partial B(x,t)} t h(y) + g(y) + \nabla g(y) \cdot (y-x) d\sigma$$

Kirchoff formula.

2) Solution for  $N=2$

Look for

$$\begin{cases} u_{tt} - \Delta u = 0 & \text{in } \mathbb{R}^2 \times (0, \infty) \\ u = g, u_t = h & \text{on } \mathbb{R}^2 \times \{0\} \end{cases}$$

Idea:

$$\bar{u}(x_1, x_2, x_3, t) = u(x_1, x_2, t)$$

$$\bar{g}, \bar{h} \dots$$

$$\text{Implies } \bar{u}_{tt} - \Delta \bar{u} = 0 \text{ in } \mathbb{R}^3 \times (0, \infty)$$

$$\bar{u} = \bar{g}, \bar{u}_t = \bar{h} \text{ on } \mathbb{R}^3 \times \{0\}$$

$$\text{Then } u(x,t) = \bar{u}(x,0,t) = \frac{\partial}{\partial t} \left( t \int_{\partial B(x,t)} \bar{g} d\sigma \right) + t \int_{\partial B(x,0),t} \bar{h} d\sigma.$$

We remark that

$$\int_{\partial \bar{B}(\bar{x}, t)} \bar{y} \, d\bar{\sigma} = \frac{1}{4\pi t^2} \int_{\partial \bar{B}(\bar{x}, t)} \bar{y} \, d\bar{\sigma}$$

$$= \frac{2}{4\pi t^2} \int_{B(x, t)} g(y) (1 + |Dg(y)|^2)^{\frac{1}{2}} \, dy$$

for  $r(y) = (t^2 - |y - x|^2)^{\frac{1}{2}}$

Note that  $(1 + |Dg|^2)^{\frac{1}{2}} = t (t^2 - |y - x|^2)^{-\frac{1}{2}}$

Thus

$$\int_{\partial \bar{B}(\bar{x}, t)} \bar{y} \, d\bar{\sigma} = \frac{1}{2\pi t} \int_{B(x, t)} \frac{g(y)}{(t^2 - |y - x|^2)^{\frac{1}{2}}} \, dy$$

$$= \frac{t}{2} \int_{B(x, t)} \frac{g(y)}{(t^2 - |y - x|^2)^{\frac{1}{2}}} \, dy$$

Now,

$$t^2 \int_{B(x, t)} \frac{g(y)}{(t^2 - |y - x|^2)^{\frac{1}{2}}} \, dy = t \int_{B(0, 1)} \frac{g(x + rz)}{(1 - |z|^2)^{\frac{1}{2}}} \, dz$$

Thus

$$\frac{\partial}{\partial t} \left( t^2 \int_{B(x, t)} \frac{g(y)}{(t^2 - |y - x|^2)^{\frac{1}{2}}} \, dy \right)$$

$$= \int_{B(0, 1)} \frac{g(x + rz)}{(1 - |z|^2)^{\frac{1}{2}}} \, dz + t \int_{B(0, 1)} \frac{\nabla g(x + rz) \cdot z}{(1 - |z|^2)^{\frac{1}{2}}} \, dz$$

$$= t \int_{B(x,t)} \frac{g(y)}{(t^2 - |y-x|^2)^{\frac{1}{2}}} dy + t \int_{B(x,t)} \frac{\nabla g(y) \cdot (y-x)}{(t^2 - |y-x|^2)^{\frac{1}{2}}} dy$$

Consequently, we can rewrite the formula to get

$$u(x,t) = \frac{1}{2} \int_{B(x,t)} \frac{t g(y) + t^2 h(y) + t \nabla g(y) \cdot (y-x)}{(t^2 - |y-x|^2)^{\frac{1}{2}}} dy$$

5) The nonhomogeneous problem

We look for solutions of

$$(NH) \begin{cases} u_{tt} - \Delta u = f & \text{in } \mathbb{R}^N \times (0, \infty) \\ u = 0, u_t = 0 & \text{in } \mathbb{R}^N \times \{0\} \end{cases}$$

We introduce the auxiliary problem

$$\begin{cases} u_{tt}(\cdot; s) - \Delta u(\cdot; s) = 0 & \text{in } \mathbb{R}^N \times (s, \infty) \\ u(\cdot; s) = 0, u_t(\cdot; s) = f(\cdot; s) & \text{in } \mathbb{R}^N \times \{t=s\} \end{cases}$$

And we define

$$u(x,t) := \int_0^t u(x,t;s) ds \quad x \in \mathbb{R}^N, t \geq 0 \quad (1)$$

Thm: Assume  $n=1,2,3$  and  $f \in C^3(\mathbb{R}^N \times [0, \infty))$ . Define  $u$  by (1)

Then (i)  $u \in C^2(\mathbb{R}^N \times [0, \infty))$

(ii)  $u$  solves (NH).



Proof: (i) Clear

$$(ii) u_t(x, t) = u(x, t; t) + \int_0^t u_t(x, t; s) ds = \int_0^t u_t(x, t; s) ds$$

$$\begin{aligned} u_{tt} &= u_t(x, t; t) + \int_0^t u_{tt}(x, t; s) ds \\ &= f(x, t) + \int_0^t u_{tt}(x, t; s) ds \end{aligned}$$

Moreover,

$$\Delta u(x, t) = \int_0^t \Delta u(x, t; s) ds = \int_0^t u_{tt}(x, t; s) ds$$

$$\text{Thus } u_{tt}(x, t) - \Delta u(x, t) = f(x, t).$$

Exercise: Write ~~d'Alembert~~ Duhamel formula for  $N=1$  and  $N=3$

$$\bullet N=1: u(x, t) = \frac{1}{2} \int_0^t \int_{x-s}^{x+s} f(y, t-s) dy ds \quad (x \in \mathbb{R}, t \geq 0)$$

$$\begin{aligned} \bullet N=3: u(x, t) &= \int_0^t (t-s) \int_{\partial B(x, t-s)} f(y, s) d\sigma ds \\ &= \frac{1}{4\pi} \int_0^t \int_{\partial B(x, t-s)} \frac{f(y, s)}{(t-s)} d\sigma ds \\ &= \frac{1}{4\pi} \int_0^t \int_{\partial B(x, r)} \frac{f(y, t-s)}{r} d\sigma dr \\ &= \frac{1}{4\pi} \int_{B(x, t)} \frac{f(y, t-(y-x))}{|y-x|} dy. \end{aligned}$$

6) Uniqueness

For  $\Omega \subset \mathbb{R}^N$ , bounded open with smooth boundary  $\partial\Omega$ , we set

$$\Omega_T = \Omega \times (0, T), \quad \Gamma_T = \overline{\Omega_T} - \Omega_T \quad \text{for } T > 0$$

We are interested in

$$(2) \begin{cases} u_t - \Delta u = f & \text{in } \Omega_T \\ u = g & \text{on } \Gamma_T \\ u_t = h & \text{on } \Omega \times \{t=0\} \end{cases}$$

Thm: There exists at most one function  $u \in C^2(\overline{\Omega_T})$  solving (2).

Proof: Let  $u$  and  $\tilde{u}$  be two solutions of (2) and set  $v = u - \tilde{u}$ .

Then  $v$  solves

$$\begin{cases} v_t - \Delta v = 0 & \text{in } \Omega_T \\ v = 0 & \text{on } \Gamma_T \\ v_t = 0 & \text{on } \Omega \times \{t=0\} \end{cases}$$

We define the energy by

$$E(v(t)) = \frac{1}{2} \int_{\Omega} v_t^2 + |\nabla v|^2 dx$$

Then

$$\begin{aligned} \frac{d}{dt} E(v(t)) &= \int_{\Omega} v_t v_{tt} + \nabla v \cdot \nabla v_t dx \\ &= \int_{\Omega} v_t (v_{tt} - \Delta v_t) dx = 0. \end{aligned}$$

Thus  $E(v(t)) = E(v(0)) = 0$  for all  $t$ .

This gives  $v_t = \nabla v = 0$  in  $\Omega_T$  and thus  $v = 0$  in  $\Omega_T$ .

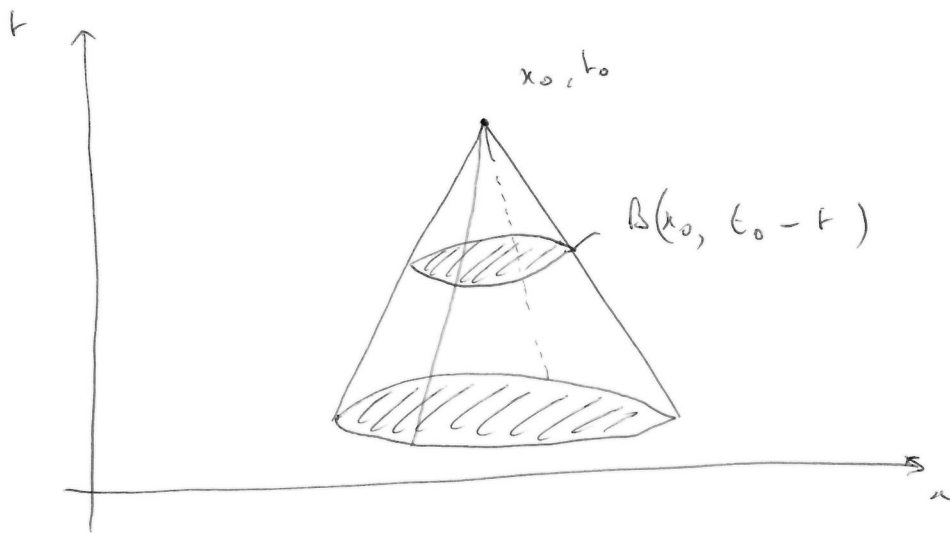
7) Domain of dependence, finite propagation of speed, causality principle

suppose  $u \in C^2$  solves

$$u_{tt} - \Delta u = 0 \quad \text{in } \mathbb{R}^N \times (0, \infty)$$

fix  $x_0 \in \mathbb{R}^N, t_0 > 0$ , and consider the cone

$$C = \{ (x, t) \mid 0 \leq t \leq t_0, |x - x_0| \leq t_0 - t \}$$



Thm: If  $u \equiv u_t \equiv 0$  on  $B(x_0, t_0) \times \{t=0\}$ , then  $u \equiv 0$  within the cone  $C$ .

Proof: Define

$$E(t) := \frac{1}{2} \int_{B(x_0, t_0 - t)} u_t^2(x, t) + |\nabla u(x, t)|^2 dx \quad 0 \leq t \leq t_0.$$

Then

$$\frac{d}{dt} E(t) = \int_{B(x_0, t_0 - t)} u_t u_{tt} + \nabla u \nabla u_t dx = \frac{1}{2} \int_{\partial B(x_0, t_0 - t)} u_t^2 + |\nabla u|^2 d\sigma$$

$$\begin{aligned}
 &= \int_{B(x_0, t_0-t)} u_t (u_{tt} - \Delta u) dx + \int_{\partial B(x_0, t_0-t)} \frac{\partial u}{\partial \nu} u_t d\sigma - \frac{1}{2} \int_{\partial B(x_0, t_0-t)} u_t^2 + |\nabla u|^2 d\sigma \\
 &= \int_{\partial B(x_0, t_0-t)} \frac{\partial u}{\partial \nu} u_t - \frac{1}{2} u_t^2 - \frac{1}{2} |\nabla u|^2 d\sigma
 \end{aligned}$$

Now,  $\left| \frac{\partial u}{\partial \nu} u_t \right| \leq |u_t| |\nabla u| \leq \frac{1}{2} u_t^2 + \frac{1}{2} |\nabla u|^2$ , which implies

$$\frac{d}{dt} E(t) \leq 0 \text{ and thus } E(t) \leq E(0) = 0. \quad \forall 0 \leq t \leq t_0.$$

Therefore,  $u_t = \nabla u = 0$  and  $u \equiv 0$  in  $C$ .

• Exercises: Klein-Gordon equation.

$$u_{tt} - \Delta u + m^2 u = 0, \quad m > 0.$$

1) What is the energy? Show it is constant.

2) Prove the causality principle.

• Huygen's principle

• Exercise: Let  $g, h$  be smooth with compact support and  $u$  solves

$$\begin{cases} u_{tt} - \Delta u = 0 & \text{in } \mathbb{R}^3 \times (0, \infty) \\ u|_g, u_t|_h & \text{on } \mathbb{R}^3 \times \{t=0\} \end{cases}$$

Prove ~~that~~ there exists  $C > 0$  s.t.

$$|u(x, t)| \leq \frac{C}{t} \quad \forall x \in \mathbb{R}^3, \quad \forall t > 0. \quad \left( \int_{\partial B} = \frac{1}{N(x, t)^{2s-1}} \int_{\partial B} \right)$$

Exercise: Same hypothesis, but in dimension 2.

1) Fix  $x \in \mathbb{R}^2$ . Show

$$|u(x,t)| \leq \frac{C}{t} \quad \forall t > 0$$

2) Show that ~~for all~~  $x \in \mathbb{R}^2$

$$|u(x,t)| \leq \frac{C}{t^{1/2}} \quad \forall x \in \mathbb{R}^2 \quad \forall t > 0. \quad \left( \int_B f = \frac{1}{\omega_N r^N} \int_B \right)$$

Exercise: Solve  $u_{xx} - 3u_{xt} - 4u_{tt} = 0$ ,  $u(x,0) = g$ ,  $u_t(x,0) = h$ .

Exercise: For a sol of  $u_{tt} = u_{xx}$ , we define the energy density  $e = \frac{1}{2}(u_t^2 + u_x^2)$  and the momentum density  $p = u_t u_x$

1) Show  $\frac{de}{dt} = \frac{dp}{dx}$  and  $\frac{dp}{dt} = \frac{de}{dx}$

2) Show  $e(x,t)$ ,  $p(x,t)$  solve the wave eq.

Exercise: Show that the wave equation has the following invariance properties.

- 1) Any translate  $u(x-y, t)$  for fixed  $y$  is also a solution
- 2)  $u_x$  is also a solution
- 3) The dilated function  $u(ax, at)$  is also a solution

IV Heat equation

$$u_t - \Delta u = 0$$

1) Fundamental solution.

Def: The function

$$\Phi(x, t) := \begin{cases} \frac{1}{(4\pi t)^{N/2}} e^{-\frac{|x|^2}{4t}} & x \in \mathbb{R}^N \quad t > 0 \\ 0 & x \in \mathbb{R}^N \quad t < 0 \end{cases}$$

is called the fundamental solution of the heat equation.

Exercise: Show that for  $t > 0$ ,  $\int_{\mathbb{R}^N} \Phi(x, t) dx = 1$ .

2) Initial value problem.

$$(IVP) \begin{cases} u_t - \Delta u = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ u = g & \text{on } \mathbb{R}^N \times \{t=0\} \end{cases}$$

$$\text{Set } u(x, t) := \int_{\mathbb{R}^N} \Phi(x-y, t) g(y) dy$$

Thm: Assume  $g \in C(\mathbb{R}^N) \cap L^\infty(\mathbb{R}^N)$  and let  $u$  be defined as above. Then

(i)  $u \in C^\infty(\mathbb{R}^N \times (0, \infty))$

(ii)  ~~$u_t - \Delta u = 0$~~   $u$  satisfies (IVP).

Rk: Infinite propagation of speed.

We remark if  $g \in C(\mathbb{R}^N) \cap C^\infty(\mathbb{R}^N)$  satisfies  $g \equiv 0, g \geq 0$ , then

$u(x,t) > 0$  for all  $x \in \mathbb{R}^N$  and  $t > 0$ .

3) Nonhomogeneous problem.

$$(NH) \begin{cases} u_t - \Delta u = f & \text{in } \mathbb{R}^N \times (0, \infty) \\ u = 0 & \text{on } \mathbb{R}^N \times \{t=0\} \end{cases}$$

As for the wave equation, we introduce an auxiliary problem

$$\begin{cases} v_t(x,t;s) - \Delta v(x,t;s) = 0 & \mathbb{R}^N \times (s, \infty) \\ v(x,t;s) = f(x,s) & \mathbb{R}^N \times \{t=s\} \end{cases}$$

The solution is

$$v(x,t;s) = \int_{\mathbb{R}^N} \Phi(x-y, t-s) f(y,s) dy$$

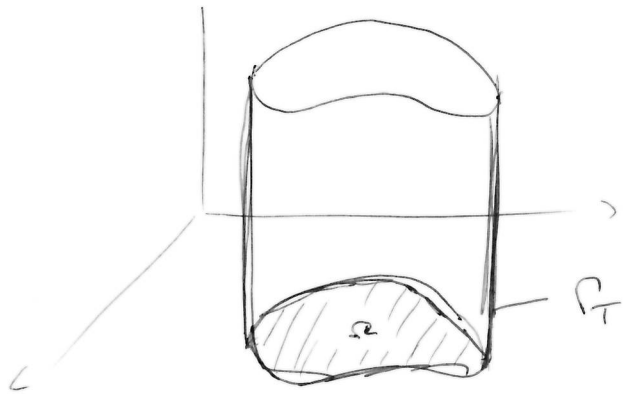
Thm: let  $f \in C^2(\mathbb{R}^N \times [0, \infty))$  with compact support.

$$\begin{aligned} \text{Define } u(x,t) &:= \int_0^t v(x,t;s) ds \\ &= \int_0^t \frac{1}{(4\pi(t-s))^{\frac{N}{2}}} \int_{\mathbb{R}^N} e^{-\frac{|x-y|^2}{4(t-s)}} f(y,s) dy ds. \end{aligned}$$

Then  $u \in C^2(\mathbb{R}^N \times (0, \infty))$  and verifies (NH).

#### 4) Poisson-value formula

for  $\Omega \subset \mathbb{R}^N$  open and bounded,  $T > 0$ , we define  $\Omega_T = \Omega \times [0, T]$  and  $\Gamma_T = \overline{\Omega_T} \setminus \Omega_T$ .



Def: Fix  $x \in \mathbb{R}^N$ ,  $t \in \mathbb{R}$ ,  $r > 0$  and define the Heat ball

$$E(x, t, r) := \left\{ (y, s) \in \mathbb{R}^{N+1} \mid s \leq t, \Phi(x-y, t-s) \geq \frac{1}{r^N} \right\}.$$

Thm: Let  $u \in C^2(\Omega_T)$  solve the heat equation. Then

$$u(x, t) = \frac{1}{4 r^N} \iint_{E(x, t, r)} u(y, s) \frac{|x-y|^2}{(t-s)^2} dy ds$$

for each  $E(x, t, r) \subset \Omega_T$ .



Proof: Assume that  $x=0, t=0$  and  $u$  is smooth (it is reasonable, as we shall see in the sequel).

We write  $E(0,0;r) = E(r)$  and

$$\begin{aligned} \phi(r) &:= \frac{1}{r^N} \int_{E(r)} u(y,r) \frac{|y|^2}{s^2} dy ds \\ &= \int_{E(1)} u(y, r^2 s) \frac{|y|^2}{s^2} dy ds \end{aligned}$$

We compute

$$\begin{aligned} \phi'(r) &= \int_{E(1)} \sum_{j=1}^N u_{y_j} \cdot y_j \frac{|y|^2}{s^2} + 2r u_s \frac{|y|^2}{s^2} dy ds \\ &= \frac{1}{r^{N+1}} \int_{E(r)} \left( \nabla_y u \cdot y + 2u_s \right) \frac{|y|^2}{s} dy ds. \end{aligned}$$

To do the computations, it is easier to introduce

$$\psi := -\frac{N}{2} \log(-4\pi s) + \frac{|y|^2}{4s} + N \log(r).$$

kk:  $\psi = 0$  on  $\partial E(r)$  (why?).

We have

$$\begin{aligned} \frac{1}{r^{N+1}} \int_{E(r)} 2r u_s \frac{|y|^2}{s} dy ds &= \frac{1}{r^{N+1}} \int_{E(r)} 4u_s \sum_{i=1}^N y_i \psi_{y_i} dy ds \\ &= -\frac{1}{r^{N+1}} \int_{E(r)} 4m u_s \psi + 4 \sum_{i=1}^N u_{s y_i} y_i \psi dy ds \end{aligned}$$

$$= \frac{1}{u^{N+1}} \int_{E(r)} -4N u_s \psi + 4 \sum_{i=1}^N u_{y_i} y_i \psi_s \, dy \, ds.$$

$$= \frac{1}{u^{N+1}} \int_{E(r)} -4N u_s \psi + 4 \sum_{i=1}^N u_{y_i} y_i \left( -\frac{N}{2s} - \frac{|y|^2}{4s^2} \right) \, dy \, ds$$

$$= \frac{1}{u^{N+1}} \int_{E(r)} -4N u_s \psi - \frac{2N}{s} \sum_{i=1}^N u_{y_i} y_i \, dy \, ds - A.$$

Since  $u$  solves the heat equation.

$$\phi'(r) = \frac{1}{u^{N+1}} \int_{E(r)} -4N \Delta u \psi - \frac{2N}{s} \sum_{i=1}^N u_{y_i} y_i \, dy \, ds$$

$$= \sum_{i=1}^N \frac{1}{u^{N+1}} \int_{E(r)} 4N u_{y_i} \psi_{y_i} - \frac{2N}{s} u_{y_i} y_i \, dy \, ds.$$

$$= 0.$$

$\Rightarrow \phi$  const.

$$\begin{aligned} \phi(r) &= \lim_{t \rightarrow 0} \phi(t) = u(0,0) \left( \lim_{t \rightarrow 0} \iint_{E(t)} \frac{|y|^2}{s^2} \, dy \, ds \right) \\ &= 4 u(0,0) \text{ (obvious)}. \end{aligned}$$

5) Maximum principle.

Thm: Assume  $u \in C^2(\Omega_T) \cap C(\bar{\Omega}_T)$  solves the heat eq in  $\Omega_T$ . Then

(i)  $\max_{\bar{\Omega}_T} u = \max_{\Gamma_T} u$

(ii) if  $\Omega$  is connected, and there exists  $(x_0, t_0) \in \Omega_T$  s.t.

$u(x_0, t_0) = \max_{\bar{\Omega}_T} u$  then  $u$  is constant in  $\bar{\Omega}_{t_0}$ .

Proof: 1) Supp  $\exists (x_0, t_0) \in \Omega_T$  with  $u(x_0, t_0) = \Pi := \max_{\bar{\Omega}_T} u$ .

for  $r$  small,  $E(x_0, t_0, r) \subset \Omega_T$  and

$$\Pi = u(x_0, t_0) = \frac{1}{4r^{2N}} \iint_{E(x_0, t_0, r)} u(y, s) \frac{|x_0 - y|^2}{(t_0 - s)^2} dy ds \leq \Pi.$$

(because  $\iint_{E(x_0, t_0, r)} \frac{|x_0 - y|^2}{(t_0 - s)^2} dy ds$

It is possible only if  $u = \Pi$  in  $E(x_0, t_0, r)$ .

Consider a line segment connecting  $(x_0, t_0)$  to some  $(y_0, t_0) \in \Omega_T, s_0 < t_0$ .

Let  $s_0 := \min \{s \geq s_0 \mid u(x, t) = \Pi \ \forall (x, t) \in L, s_0 \leq t \leq t_0\}$ .

Since  $u$  is continuous, the min is attained. Assume  $s_0 > s_0$ . Then

$u(y_0, s_0) = \Pi$  for some  $(y_0, s_0)$  on  $L \cap \Omega_T$ , and so  $u = \Pi$  in  $E(y_0, s_0, r)$

for  $r$  small. Since  $E(y_0, s_0, r)$  contains  $L \cap \{s_0 - r \leq t \leq s_0\}$  for  $r$  small,

we reach a contradiction. Thus  $s_0 = s_0$  and  $u = \Pi$  on  $L$ .

2) by connectedness

Thm:  $g \in C(\mathbb{R}^N), f \in C(\mathbb{R}^N \times [0, T])$ . There exists at most one sol  $u \in C^2(\mathbb{R}^N \times (0, T]) \cap C(\mathbb{R}^N \times [0, T])$  of  $\begin{cases} u_t - \Delta u = f & \text{in } \mathbb{R}^N \times (0, T) \\ u = g & \text{on } \mathbb{R}^N \times \{t=0\} \end{cases}$

satisfying  $|u(x, t)| \leq A e^{a|x|^2} \ \forall x \in \mathbb{R}^N, \forall 0 < t \leq T$  for  $a, A > 0$ .

6) Regularity:

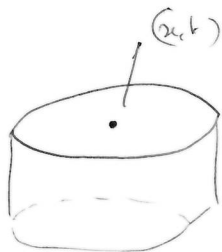
Thm: Assume  $u: \Omega_T \rightarrow \mathbb{R}$  satisfies

- $u, D_x u, D_x^2 u, u_t \in C(\bar{\Omega}_T)$
- $u$  satisfies the heat equation.

Then  $u \in C^\infty(\Omega_T)$ .

Proof 1) We write

$$C(x, t; r) = \{ (y, s) \mid |x-y| \leq r, t-r^2 \leq s \leq t \}$$



Fix  $(x_0, t_0) \in \Omega_T$  and choose  $r > 0$  s.t.  $C = C(x_0, t_0, r) \subset \Omega_T$ .

Let also  $C' = C(x_0, t_0; \frac{3}{4}r)$ ,  $C'' = C(x_0, t_0; \frac{1}{2}r)$ .

Let  $\zeta = \zeta(x, t)$  s.t.

$$\begin{cases} 0 \leq \zeta \leq 1, \zeta = 1 \text{ on } C' \\ \zeta = 0 \text{ on } \partial C \end{cases}$$

Extend  $\zeta \equiv 0$  in  $(\mathbb{R}^n \times [0, t_0]) \setminus C$ .

2) Assume temporarily that  $u \in C^\infty(\Omega_T)$  and set

$$v(x, t) = \zeta(x, t) u(x, t) \quad (x \in \mathbb{R}^n, 0 \leq t \leq t_0)$$

$$\text{Then } v_t = \zeta_t u + \zeta u_t, \quad \Delta v = \zeta \Delta u + 2 \nabla \zeta \nabla u + u \Delta \zeta$$

Consequently,  $v = 0$  on  $\mathbb{R}^n \times \{t = 0\}$

$$\text{and } v_t - \Delta v = \zeta_t u - 2 \nabla \zeta \cdot \nabla u - \Delta \zeta u =: \tilde{f} \text{ in } \mathbb{R}^n \times (0, t_0)$$

Now set

$$\tilde{v}(x,t) := \int_0^t \int_{\mathbb{R}^n} \Phi(x-y, t-s) \tilde{f}(y,s) dy ds.$$

By unicity,  $v \equiv \tilde{v}$

Now, suppose  $(x,t) \in C'$ . Since  $\int \equiv 0$  on  $C$ , we have

$$u(x,t) = \iint_C \Phi(x-y, t-s) \left[ (\zeta_s(y,s) - \Delta \zeta(y,s)) u(y,s) - 2 \nabla \zeta(y,s) \cdot \nabla u(y,s) \right] dy ds$$

$$= \iint_C \left[ \Phi(x-y, t-s) (\zeta_s(y,s) + \Delta \zeta(y,s)) + 2 \nabla_y \Phi(x-y, t-s) \cdot \nabla \zeta(y,s) \right] u(y,s) dy ds$$

If  $u$  is not smooth, this result can be obtained by mollifying  $u$ .

3) The formula has the form

$$u(x,t) = \iint_C K(x,t, y,s) u(y,s) dy ds.$$

with  $K(x,t, y,s) \equiv 0$  in  $C'$

and  $K$  smooth on  $C \setminus C'$ . This implies  $u \in C^\infty$ .

7) Uniqueness.

$$\begin{cases} u_t - \Delta u = f & \text{in } \Omega_T \\ u = g & \text{on } \Gamma_T \end{cases}$$

$\Omega$  open, bdd,  $\partial \Omega \in C^1$ .

Thm: There exists at most one solution  $u \in C_T^1(\Omega_T) \cap C_T^2(\Omega_T)$ .

Proof: Let  $u, \tilde{u}$  be two solutions, and set  $w := u - \tilde{u}$ . Then

$$\begin{cases} w_t - \Delta w = 0 & \text{in } U_T \\ w = 0 & \text{on } \Omega_T \end{cases}$$

Set  $e(t) := \int_{\Omega} w^2(x, t) dx \quad (0 \leq t \leq T)$

$$\begin{aligned} \text{Then } \frac{d}{dt} e(t) &= 2 \int_{\Omega} w w_t dx \\ &= 2 \int_{\Omega} w \Delta w dx \\ &= -2 \int_{\Omega} |\nabla w|^2 dx \leq 0 \end{aligned}$$

Therefore,  $e(t) \leq e(0) = 0 \quad (0 \leq t \leq T)$

and  $w \equiv 0$  in  $\Omega_T$ .

### 8) Backward uniqueness

Suppose  $(BU) \begin{cases} u_t - \Delta u = 0 & \text{in } \Omega_T \\ u = g & \text{on } \partial\Omega \times [0, T] \end{cases}$

and  $\tilde{u}$  also a sol.

Thm: Suppose  $u, \tilde{u} \in C^2(\overline{\Omega_T})$  solve (BU). If

$$u(x, T) = \tilde{u}(x, T) \quad (x \in \Omega),$$

then  $u \equiv \tilde{u}$  in  $\Omega_T$ .

Proof:  $w = u - \tilde{u}$ ,  $e(t) := \int_{\Omega} w^2 dx \quad (0 \leq t \leq T)$

$$\frac{de}{dt} = -2 \int_{\Omega} |\nabla w|^2 dx$$

Moreover,  $\frac{d^2}{dt^2} e(t) = -4 \int_{\Omega} \nabla w \nabla w_t dx$

$$= 4 \int_{\Omega} \Delta w w_t dx$$

$$= 4 \int_{\Omega} (\Delta w)^2 dx$$

Now, since  $w = 0$  on  $\partial\Omega$

$$\int_{\Omega} |\nabla w|^2 = - \int_{\Omega} w \Delta w dx \leq \left( \int_{\Omega} w^2 dx \right)^{1/2} \left( \int_{\Omega} (\Delta w)^2 dx \right)^{1/2}$$

Thus  $(\dot{e}(t))^2 \leq e(t) \ddot{e}(t)$

2) if  $e(t) = 0 \forall t \in T$ , we are done.

otherwise, there exists  $(t_1, t_2) \subset [0, T]$  s.t.

$$e(t) > 0 \text{ for } t_1 \leq t < t_2, \quad e(t_2) = 0.$$

3) with  $f(t) := \log e(t) \quad (t_1 \leq t < t_2)$

$$\frac{d^2}{dt^2} f(t) = \frac{\ddot{e}(t)}{e(t)} - \frac{\dot{e}(t)^2}{e(t)^2} \geq 0$$

$\Rightarrow f$  convex on  $t_1, t_2$ : for  $0 < z < 1, t_1 < t < t_2$ ,

$$f((1-z)t_1 + zt_2) \leq (1-z)f(t_1) + zf(t_2)$$

thus  $e((1-z)t_1 + zt_2) \leq e(t_1)^{1-z} e(t_2)^z$

So  $0 \leq e((1-z)t_1 + zt_2) \leq e(t_1)^{1-z} \underbrace{e(t_2)^z}_{=0}$

$\Rightarrow e(t) = 0 \quad t_1 \leq t \leq t_2 \quad \checkmark$

Exercise:  $u$  smooth,  $u_t - \Delta u = 0$  in  $\mathbb{R}^N \times (0, \infty)$ .

(i)  $u_t(x, t) := u(x, d^2 t)$  solve heat for  $d \in \mathbb{R}$

(ii) Prove  $v(x, t) := x \nabla u(x, t) + 2t u_t(x, t)$  solves heat.

Exercise:  $N=1$ ,  $u(x, t) = v\left(\frac{x^2}{t}\right)$

1) Show  $u_t = u_{xx} \Leftrightarrow 4z v''(z) + (2+z)v'(z) = 0$  ( $z > 0$ ) (\*)

2) Show gen sol of (\*) is  $v(z) = c \int_0^z e^{-s/4} s^{-1/2} ds + d$

3) Differentiate  $v\left(\frac{x^2}{t}\right)$  in  $x$  and  $t$  and select  $c$  to obtain the fundamental sol  $\Phi$  for  $N=1$ .



Exercise 3 (Evans):

Let  $u$  satisfy

$$\begin{cases} -\Delta u = f & \text{in } B(0, r) \\ u = g & \text{on } \partial B(0, r) \end{cases}$$

Prove that for  $N \geq 3$  we have

$$u(0) = \int_{\partial B(0, r)} g \, d\sigma + \frac{1}{N(N-2)\omega_N} \int_{B(0, r)} \left( \frac{1}{|x|^{N-2}} - \frac{1}{r^{N-2}} \right) f \, dx$$

Hint: modify the proof of the mean value formula.

Exercise: V.G.

$$\Delta u - \Delta u + m^2 u = 0, \quad m > 0$$

- 1) What is the energy? Show it is constant.
- 2) Prove the causality principle.

Exercise 11 Evans Equipartition of energy

Let  $u \in C^2(\mathbb{R} \times (0, \infty))$  solve the IVP for the wave eq in 1D

$$\begin{cases} u_{tt} - u_{xx} = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ u = g, u_t = h & \text{on } \mathbb{R} \times \{t=0\} \end{cases}$$

Supp  $g, h$  have compact supports. The kinetic energy is

$$k(t) := \frac{1}{2} \int_{-\infty}^{\infty} u_t^2(x, t) dx \text{ and the potential energy is}$$

$$p(t) := \frac{1}{2} \int_{-\infty}^{\infty} u_x^2(x, t) dx .$$

(i)  $k(t) + p(t)$  is constant in  $t$

(ii)  $k(t) = p(t)$  for all large enough times  $t$ .

## Exercise 6 (Strauss)

Prove that, among all possible dimensions, only in three dimensions can one have distortionless spherical wave propagation with attenuation.

This means the following.

A spherical wave in  $N$ -D space satisfies

$$\Delta u = \frac{1}{r^{N-1}} \frac{d}{dr} \left( r^{N-1} \frac{du}{dr} \right) = 0$$

Consider such a wave of the form  $u(r, t) = \alpha(r) f(t - \beta(r))$

$\alpha(r)$  = attenuation

$\beta(r)$  = delay

Does such solution exist for arbitrary  $f$

- Plug into the PDE to get an ODE for  $f$
- Set the coeff of  $f''$ ,  $f'$  and  $f$  eq to 0
- Solve the ODEs to see  $N=1$  or  $N=3$
- If  $N=1$ , show  $\alpha(r)$  is constant

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