Large density flows and congestion phenomena

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Schémas numériques pour les écoulements à faible nombre de Mach

Toulouse, November 20-22, 2017

Applications

partially free surface flows







collective motion



Fluid equations under maximal density constraint

 \bullet two-phase model (free / congested) \rightarrow "hard" congestion model

$$\begin{cases} \partial_t \rho + \operatorname{div} (\rho u) = 0\\ \partial_t (\rho u) + \operatorname{div} (\rho u \otimes u) + \nabla p - \operatorname{div} \mathbb{S} = 0\\ 0 \le \rho \le \rho^*, \ (\rho^* - \rho)p = 0, \ p \ge 0 \end{cases}$$

in the following: $ho^*=1$

- \blacktriangleright pressureles equations in the free domain $\rho < \rho^*$
- div $u \ge 0$ in the congested domain $\rho = \rho^*$
- activation of the pressure $p \ge 0$ in the congested domain
 - \rightarrow Lagrange multiplier associated to the constraint on u

Literature

$$\begin{cases} \partial_t \rho + \operatorname{div} (\rho u) = 0\\ \partial_t (\rho u) + \operatorname{div} (\rho u \otimes u) + \nabla p - \operatorname{div} \mathbb{S} = 0\\ 0 \le \rho \le \rho^*, \ (\rho^* - \rho)p = 0, \ p \ge 0 \end{cases}$$

• theoretical studies

- ► Lions, Masmoudi (1998), Perrin, Zatorska (2015) : $S = 2\mu D(u) + \lambda \operatorname{div} u \operatorname{Id}$
- ▶ Berthelin (2002, 2016), Perrin, Westdickenberg (2017) : S = 0
- Perrin (2016) : $\mathbb{S} = \mathbb{S}(p)$ + effet de non-localité

• numerical studies

- Degond, Hua, Navoret (2011), Bresch, Renardy (2016)
- Maury, Preux (2016)
- other references (similar systems) : Bourdarias, Ersoy, Gerbi (2012), Godlewski, Parisot, Sainte-Marie, Wahl (2016), Lannes (2016)

Approximation by a "soft" congestion model

soft model compressible singular pressure NS

$$\begin{cases} \partial_t \rho_{\varepsilon} + \operatorname{div} \left(\rho_{\varepsilon} u_{\varepsilon} \right) = 0 \\ \partial_t (\rho_{\varepsilon} u_{\varepsilon}) + \operatorname{div} \left(\rho_{\varepsilon} u_{\varepsilon} \otimes u_{\varepsilon} \right) + \nabla p_{\varepsilon} (\rho_{\varepsilon}) \\ - \nabla \left(\lambda \operatorname{div} u_{\varepsilon} \right) - 2 \operatorname{div} \left(\mu \operatorname{D}(u_{\varepsilon}) \right) = 0 \quad \xrightarrow{\varepsilon \to 0} \\ 0 \le \rho < 1 \end{cases}$$

$$\begin{array}{l} \underline{\text{hard model}}\\ \text{compressible/incompressible NS}\\ \left\{ \begin{array}{l} \partial_t \rho + \operatorname{div}\left(\rho u\right) = 0\\ \partial_t(\rho u) + \operatorname{div}\left(\rho u \otimes u\right) + \nabla p\\ - \nabla\left(\lambda \operatorname{div} u\right) - 2 \operatorname{div}\left(\mu \operatorname{D}(u)\right) = 0\\ 0 \leq \rho \leq 1, \ (1 - \rho)p = 0, \ p \geq 0\\ \operatorname{div} u = 0 \quad \text{on} \quad \{\rho = 1\} \end{array} \right. \end{array} \right.$$

$$p_{\varepsilon}(
ho) = \varepsilon \left(rac{
ho}{1-
ho}
ight)^{\gamma}$$

 \rightarrow singular repulsive forces

$$\lambda + \frac{2}{3}\mu \geq 0$$



ref : Perrin, Zatorska (2015)

Some elements of the theoretical proof

 Ω a bounded domain of $\mathbb{R}^3,$ Dirichlet boundary conditions on $\partial\Omega$

• energy estimate + control of the density

$$\sup_{t\in(0,T)}\int_{\Omega}\left[\frac{\rho_{\varepsilon}|u_{\varepsilon}|^{2}}{2}+\phi(\rho_{\varepsilon})\frac{\varepsilon}{(1-\rho_{\varepsilon})^{\gamma-1}}\right]+\int_{0}^{T}\int_{\Omega}\left(2\mu|\operatorname{D}(u_{\varepsilon})|^{2}+\lambda\left(\operatorname{div} u_{\varepsilon}\right)^{2}\right)\leq E_{\varepsilon}^{0}$$

 ${\rm mes}\,\,\{\rho_{\varepsilon}\geq 1\}=0$

• control of the pressure the mom eq. is tested by $\mathcal{B}(
ho_{arepsilon}-M^0)$, $\mathcal{B}\sim\,\mathrm{div}^{-1}$

$$(p_{\varepsilon}(\rho_{\varepsilon}))_{\varepsilon}, \ (\rho_{\varepsilon}p_{\varepsilon}(\rho_{\varepsilon}))_{\varepsilon}$$
 are bounded in $L^{1}((0, T) \times \Omega)$

● weak cvg of the weak solutions → compactness arguments of Lions

- ▶ study the oscillation of $\rho_{\varepsilon} \rightarrow \text{evolution of } \lim_{\varepsilon \rightarrow 0} \rho_{\varepsilon} \ln \rho_{\varepsilon} \rho \ln \rho$
- weak compactness property of the effective flux $(2\mu + \lambda) \operatorname{div} u_{\varepsilon} p_{\varepsilon}(\rho_{\varepsilon})$

Theorem (Perrin, Zatorska 2015)

Let $\gamma >$ 3, assume that initially 0 $\leq
ho_{arepsilon}^{0} <$ 1 a.e. and

$$M^0_arepsilon = \int_\Omega
ho^0_arepsilon \, \mathrm{d} x \leq C, \qquad \int_\Omega E_arepsilon(
ho^0_arepsilon, m^0_arepsilon) \leq C.$$

Then, for $\varepsilon \to 0$, there exists a subsequence $(\rho_{\varepsilon}, u_{\varepsilon}, p_{\varepsilon})$ converging to (ρ, u, p) a weak solution of the hard congestion system with

$$\begin{split} \rho_{\varepsilon} &\to \rho \quad \text{strongly in} \quad L^{q}\big((0,T) \times \Omega\big) \\ u_{\varepsilon} &\to u \quad \text{weakly in} \quad L^{2}\big(0,T; (W_{0}^{1,2}(\Omega))^{d}\big) \\ p_{\varepsilon}(\rho_{\varepsilon}) &\to p \quad \text{weakly in} \quad \mathcal{M}^{+}\big((0,T) \times \Omega\big) \end{split}$$

- low regularity of the limit pressure
 - definition of the product ρp in the constraint $(1 \rho)p = 0$
- no result about the existence of local strong solutions
- no theoretical result about the singular limit in the inviscid case

Numerical approach

$$\begin{cases} \partial_t \rho_{\varepsilon} + \operatorname{div} \left(\rho_{\varepsilon} u_{\varepsilon} \right) = 0\\ \partial_t (\rho_{\varepsilon} u_{\varepsilon}) + \operatorname{div} \left(\rho_{\varepsilon} u_{\varepsilon} \otimes u_{\varepsilon} \right) + \nabla p_{\varepsilon} (\rho_{\varepsilon}) \left(- \operatorname{div} \mathbb{S} \right) = 0 \end{cases}$$

• <u>singular pressure</u> $p_{\varepsilon}(\rho) = \varepsilon \left(\frac{\rho}{1-\rho}\right)^{\gamma}$



- $p_{arepsilon}$ ensures the constraint $ho_{arepsilon} < 1$
- p_{ε} becomes stiffer and stiffer as $\varepsilon \to 0$
- explicit treatment ⇒ conditional stability

$$\Delta t \leq \frac{\sigma \Delta x}{\max\{|u_{\varepsilon}| + \sqrt{p_{\varepsilon}'(\rho_{\varepsilon})}\}} \; \underset{\rho_{\varepsilon} \to 1}{\xrightarrow{\varepsilon \to 0}} \; 0$$

ightarrow implicit treatment of some terms

Implicit treatment of the pressure

$$\begin{cases} \frac{\rho^{n+1}-\rho^n}{\Delta t} + \operatorname{div}(\rho u)^{n+1} = 0\\ \frac{(\rho u)^{n+1}-(\rho u)^n}{\Delta t} + \operatorname{div}(\rho u \otimes u)^n + \nabla p_{\varepsilon}(\rho^{n+1}) = 0 \end{cases}$$

• reformulation: div (Mom eq) and insert the result into Mass eq.

$$\begin{cases} \frac{\rho^{n+1}-\rho^n}{\Delta t} + \operatorname{div}(\rho u)^n - \Delta t \Delta p_{\varepsilon}(\rho^{n+1}) - \Delta t \nabla^2 : (\rho u \otimes u)^n = 0\\ \frac{(\rho u)^{n+1} - (\rho u)^n}{\Delta t} + \operatorname{div}(\rho u \otimes u)^n + \nabla p_{\varepsilon}(\rho^{n+1}) = 0 \end{cases}$$

 \rightarrow uniform stability condition

•
$$ho^{n+1} =
ho(p_{arepsilon}^{n+1}) o$$
 nonlinear elliptic equation on $p_{arepsilon}^{n+1}$

- 1) compute p_{ε}^{n+1}
- 2) deduce the new density $\rho^{n+1} \rightarrow \rho^{n+1}$ satisfies automatically the constraint
- 3) compute the new momentum $(\rho u)^{n+1}$

Degond, Hua & Navoret (2011): Implicit/explicit splitting of the pressure

Computation of the momentum, Gauge Method

- Gauge Decomposition $\rho u = a \nabla \varphi$, div a = 0
- time discretization

$$\begin{split} \Delta \varphi^{n+1} &= \frac{1}{\Delta t} (\rho^{n+1} - \rho^n) \qquad \varphi^{n+1}_{\ |\partial\Omega} = 0 \\ \Delta P^{n+1} &= -\nabla^2 : (\rho u \otimes u)^n \qquad \rightsquigarrow \qquad P^{n+1} = p_{\varepsilon}(\rho^{n+1}) - \frac{\varphi^{n+1} - \varphi^n}{\Delta t} \\ \frac{a^{n+1} - a^n}{\Delta t} + \operatorname{div} (\rho u \otimes u)^n + \nabla P^{n+1} = 0 \end{split}$$

$$(\rho u)^{n+1} = a^{n+1} - \nabla \varphi^{n+1}$$

ref: Degond, Jin, Liu (2007), Degond, Hua, Navoret (2011)

Time-Space discretization in 1D

$$\frac{\rho_{j}^{n+1} - \rho_{j}^{n}}{\Delta t} + \frac{1}{\Delta x} \left[Q_{j+1/2}^{n+1/2} - Q_{j-1/2}^{n+1/2} \right] = 0$$
$$\frac{(\rho u)_{j}^{n+1} - (\rho u)_{j}^{n}}{\Delta t} + \frac{1}{\Delta x} \left[F_{j+1/2}^{n} - F_{j-1/2}^{n} \right] + \frac{1}{2\Delta x} \left[\rho_{\varepsilon}(\rho_{j+1}^{n+1}) - \rho_{\varepsilon}(\rho_{j-1}^{n+1}) \right] = 0$$

with

$$\begin{aligned} Q_{j+1/2}^{n+1/2} &= \frac{1}{2} \left[(\rho u)_j^{n+1} + (\rho u)_{j+1}^{n+1} \right] - \frac{D_{j+1/2}^n}{2} \left(\rho_{j+1}^n - \rho_j^n \right) \\ F_{j+1/2}^n &= \frac{1}{2} \left[\frac{\left((\rho u)_j^n \right)^2}{\rho_j^n} + \frac{\left((\rho u)_{j+1}^n \right)^2}{\rho_{j+1}^n} \right] - \frac{D_{j+1/2}^n}{2} \left((\rho u)_{j+1}^n - (\rho u)_j^n \right) \end{aligned}$$

 $D_{j+1/2}^n = \max\{|u_j^n|, |u_{j+1}^n|\}$

$$\begin{split} \rho((\boldsymbol{p}_{\varepsilon})_{j}^{n+1}) &- \frac{\Delta t^{2}}{4\Delta x^{2}} \Big[\boldsymbol{p}_{\varepsilon}(\rho_{j+2}^{n+1}) - 2\boldsymbol{p}_{\varepsilon}(\rho_{j}^{n+1}) + \boldsymbol{p}_{\varepsilon}(\rho_{j-2}^{n+1}) \Big] \\ &= \rho_{j}^{n} - \frac{\Delta t}{2\Delta x} ((\rho u)_{j+1}^{n} - (\rho u)_{j-1}^{n}) + \frac{\Delta t^{2}}{2\Delta x^{2}} \Big[F_{j+3/2}^{n} - F_{j+1/2}^{n} - F_{j-1/2}^{n} + F_{j-3/2}^{n} \Big] \\ &+ \frac{\Delta t}{2\Delta x} \Big[D_{j+1/2}^{n}(\rho_{j+1}^{n} - \rho_{j}^{n}) - D_{j-1/2}^{n}(\rho_{j}^{n} - \rho_{j-1}^{n}) \Big] \end{split}$$

$$\begin{aligned} &\frac{1}{\Delta x^2} \Big[\varphi_{j+1}^{n+1} - 2\varphi_j^{n+1} + \varphi_{j-1}^{n+1} \Big] \\ &= \frac{1}{\Delta t} (\rho_j^{n+1} - \rho_j^n) - \frac{1}{2\Delta x} \Big[D_{j+1/2}^n (\rho_{j+1}^n - \rho_j^n) - D_{j-1/2}^n (\rho_j^n - \rho_{j-1}^n) \Big] \end{aligned}$$

$$egin{aligned} & m{a}^{n+1} = m{a}^n - \Delta t \Big((
ho u \otimes u)^n + m{p}_arepsilon (
ho^{n+1}) \Big) \Big|_0^1 \ & + rac{\Delta t}{2} \sum_{j=1}^{N_{ imes}} \Big[D_{j+1/2}^n (
ho_{j+1}^n -
ho_j^n) - D_{j-1/2}^n (
ho_j^n -
ho_{j-1}^n) \Big] \end{aligned}$$

$$(\rho u)_{j}^{n+1} = a^{n+1} - \frac{1}{2\Delta x} \left[\varphi_{j+1}^{n+1} - \varphi_{j-1}^{n+1} \right]$$

Numerical simulations: $\gamma = 2$, $\Delta t = 5.10^{-4}$, $\Delta x = 5.10^{-3}$

t = 0

t = 0.04



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Workshop Bas Macl

November 20-22, 2017

Gauge Method vs Direct Method $\varepsilon = 10^{-3}$, $\gamma = 2$, $\Delta t = 5.10^{-4}$, $\Delta x = 5.10^{-3}$



Lagrangian approach in 1d, $\mathbb{S} = 0$

$$\begin{cases} \partial_t \rho + \partial_x (\rho u) = 0\\ \partial_t (\rho u) + \partial_x (\rho u^2) + \partial_x p = 0\\ 0 \le \rho \le 1, \quad (1 - \rho)p = 0, \quad p \ge 0 \end{cases}$$

• we introduce the monotone rearrangement $X_t:(0,1) o\mathbb{R}$ such that 1

$$\rho(t, X_t(w)) = rac{1}{\partial_w X_t(w)} \quad \text{for} \quad w \in (0, 1)$$

$$ho_t \leq 1, \;\; \int_{\mathbb{R}} |x|^2
ho(t,x) \,\mathrm{d}x < +\infty \quad \Leftrightarrow \quad X_t = \mathrm{Id} + S_t \in L^2(0,1) \;\; ext{avec} \;\; \partial_w S_t \geq 0$$

• existence of global weak solutions characterized by the formula

$$\begin{split} \overline{X_t = \mathbf{P}_{\widetilde{K}}(X_0 + tU_0)} & \text{where } \widetilde{K} = \{X \in L^2 \,|\, X = \mathrm{id} + S, \ \partial_w S \ge 0\} \\ & \rightarrow \quad U_t = \frac{\mathrm{d}}{\mathrm{d}t} X_t \text{ a.e } t, \quad \partial_w P_t = -\frac{\mathrm{d}}{\mathrm{d}t} U_t \text{ in } \mathcal{D}' \end{split}$$

ref : Perrin, Westdickenberg (2017)

Associated numerical scheme

$$X_t = \mathrm{P}_{\widetilde{K}}(X_0 + tU_0)$$

• minimization at each time step of $\|X_0 + tU_0 - X\|_2^2$ under the constraint $X \in \widetilde{K}$

- comparison with exact solutions:
 - \rightarrow case of sticky blocks (ref: Berthelin, 2002)
- dynamics of congested blocks
- free dynamics until a collision at t = t*
- from time t* the blocks form a bigger block

$$I^* = I_1 + I_2$$
$$u^* = \frac{I_1 u_1 + I_2 u_2}{I_1 + I_2}$$



Comparison with the soft approach $\Delta x = 5.10^{-3}$, $\Delta t = 10^{-4}$, $\varepsilon = 10^{-4}$



Conclusion, ongoing works

- singular limit "soft" \rightarrow "hard"
 - extension to inviscid fluids, complex fluids, etc.
 - qualitative properties of the limit solutions
 - other numerical schemes
- on the limit "hard" system
 - extension of the Lagrangian method to 2d/3d ?

Implicit / Explicit scheme (Degond, Hua, Navoret)

splitting of the pressure
$$p_arepsilon=p_arepsilon^{\mathsf{ex}}(
ho^n)+p_arepsilon^{\mathsf{im}}(
ho^{n+1})$$

$$p_{\varepsilon}^{\mathsf{ex}}(\rho) = \begin{cases} p_{\varepsilon}(\rho)/2 & \text{if } \rho \leq 1-\delta \\ \text{poly of order } 2 & \text{if } \rho > 1-\delta \end{cases}$$

ightarrow good choice of parameter: $\delta = \varepsilon^{rac{1}{\gamma+2}}$

$$\implies \sqrt{(\pmb{p}^{\mathsf{ex}}_arepsilon)'(1)}, \; (\pmb{p}^{\mathsf{ex}}_arepsilon)''(1) \leq C$$

$$p_{\varepsilon}(\rho) = \varepsilon \left(\frac{\rho}{1-\rho}\right)^{\gamma}$$

