

Conexion feuille de TD4

Ex. 1

$$1) \begin{cases} x(t) = t - \text{cht} \cdot \text{sh}t \\ y(t) = 2 \text{cht} \end{cases}, \quad r(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}, \quad t > 0$$

Rappels: $\text{sh}t = \frac{e^t - e^{-t}}{2}$, $\text{cht} = \frac{e^t + e^{-t}}{2}$, $(\text{sh}t)' = \text{cht}$, $(\text{cht})' = \text{sh}t$.

$$l = \int_0^t \|r'(s)\| ds, \quad \text{ou } \|r'(s)\| = \sqrt{(x'(s))^2 + (y'(s))^2}$$

$$\begin{aligned} x'(s) &= 1 - \text{ch}'(s) \cdot \text{sh}(s) - \text{ch}(s) \cdot \text{sh}'(s) \\ &= 1 - (\text{sh}(s))^2 - (\text{ch}(s))^2 = 1 - \frac{e^{2s} + e^{-2s}}{2} = 1 - \text{ch}(2s). \end{aligned}$$

$$y'(s) = 2 \text{sh}(s)$$

$$\hookrightarrow \sqrt{(x'(s))^2 + (y'(s))^2} = \sqrt{1 + \text{ch}^2(2s) - 2 \text{ch}(2s) + 4 \text{sh}^2(s)} = \sqrt{\text{ch}^2(2s) - 1}$$

$\frac{e^{2s} + e^{-2s}}{2}$ $\frac{e^{2s} + e^{-2s} - 2}{2}$

On a $\text{ch}^2(2s) - 1 = \text{sh}^2(2s)$ (exc). $\Rightarrow \sqrt{\text{ch}^2(2s) - 1} = \text{sh}(2s)$ > 0

$$\hookrightarrow l = \int_0^t \text{sh}(2s) ds = \frac{1}{2} [\text{ch}(2s)]_0^t = \frac{\text{ch}(2t) - 1}{2} = \text{sh}^2 t. \quad \text{car } s > 0.$$

$$2) \begin{cases} x(\theta) = r(\theta) \cos \theta = \text{th}\left(\frac{\theta}{2}\right) \cdot \cos \theta \\ y(\theta) = r(\theta) \sin \theta = \text{th}\left(\frac{\theta}{2}\right) \cdot \sin \theta. \end{cases}$$

Rappel: $\text{th}'(t) = \frac{1}{\text{ch}^2(t)}$ (exc).

$$\rightarrow \begin{cases} x'(\theta) = \frac{1}{2 \text{ch}^2(\frac{\theta}{2})} \cdot \cos \theta - \text{th}\left(\frac{\theta}{2}\right) \cdot \sin(\theta) \\ y'(\theta) = \frac{1}{2 \text{ch}^2(\frac{\theta}{2})} \sin \theta + \text{th}\left(\frac{\theta}{2}\right) \cdot \cos \theta \end{cases}$$

$$\begin{aligned} \hookrightarrow (x'(\theta))^2 + (y'(\theta))^2 &= \frac{\cos^2 \theta}{4 \text{ch}^4(\frac{\theta}{2})} + \left(\text{th}\left(\frac{\theta}{2}\right)\right)^2 \sin^2 \theta - \frac{1}{\text{ch}^2(\frac{\theta}{2})} \text{th}\left(\frac{\theta}{2}\right) \sin \theta \cos \theta \\ &\quad + \frac{\sin^2 \theta}{4 \text{ch}^4(\frac{\theta}{2})} + \left(\text{th}\left(\frac{\theta}{2}\right)\right)^2 \cos^2 \theta + \frac{1}{\text{ch}^2(\frac{\theta}{2})} \text{th}\left(\frac{\theta}{2}\right) \sin \theta \cos \theta \\ &= \frac{1}{4 \text{ch}^4(\frac{\theta}{2})} + \text{th}^2\left(\frac{\theta}{2}\right) = \end{aligned}$$

$$\left. \begin{aligned} \text{th}^2(x) &= 1 - \frac{1}{\text{ch}^2(x)} \\ \text{car } \text{ch}^2(x) - \text{sh}^2(x) &= 1 \end{aligned} \right\} \Rightarrow \frac{1}{4 \text{ch}^4(\frac{\theta}{2})} + 1 - \frac{1}{\text{ch}^2(\frac{\theta}{2})} = \left(1 - \frac{1}{2 \text{ch}^2(\frac{\theta}{2})}\right)^2$$

$$\hookrightarrow l = \int_0^\theta \sqrt{(x'(t))^2 + (y'(t))^2} dt = \int_0^\theta \left(1 - \frac{1}{2 \text{ch}^2(\frac{t}{2})}\right) dt = \left[t - \text{th}\left(\frac{t}{2}\right)\right]_0^\theta = \boxed{\theta - \text{th}\left(\frac{\theta}{2}\right)}$$

Exc. 3

1)

$$T(s) = \begin{pmatrix} \cos \theta(s) \\ \sin \theta(s) \end{pmatrix}$$

$$\text{car } \|T(s)\| = 1; \quad T'(s) = \begin{pmatrix} -\sin \theta(s) \cdot \theta'(s) \\ \cos \theta(s) \cdot \theta'(s) \end{pmatrix}$$

$$\Rightarrow K(s) = \|T'(s)\| = \sqrt{\sin^2 \theta(s) \cdot (\theta'(s))^2 + \cos^2 \theta(s) \cdot (\theta'(s))^2} = \theta'(s) > 0.$$

$$2) \text{ si } K(s) = \frac{1}{R} \Rightarrow \theta'(s) = \frac{1}{R} \Rightarrow \theta(s) = \frac{s}{R} + \theta_0$$

$$\Rightarrow T(s) = \begin{pmatrix} \cos\left(\frac{s}{R} + \theta_0\right) \\ \sin\left(\frac{s}{R} + \theta_0\right) \end{pmatrix}$$

D'un autre côté : $T(s) = r'(s) = \begin{pmatrix} x'(s) \\ y'(s) \end{pmatrix}$
 car s abscisse curviligne

$$\hookrightarrow \begin{cases} x'(s) = \cos\left(\frac{s}{R} + \theta_0\right) \\ y'(s) = \sin\left(\frac{s}{R} + \theta_0\right) \end{cases} \Rightarrow \begin{cases} x(s) = \sin\left(\frac{s}{R} + \theta_0\right) \cdot R + x_0 \\ y(s) = -\cos\left(\frac{s}{R} + \theta_0\right) \cdot R + y_0 \end{cases}$$

$$\Rightarrow (x(s) - x_0)^2 + (y(s) - y_0)^2 = R^2 \Rightarrow (x(s), y(s)) \in \text{un cercle (de rayon } R \text{ et centre } (x_0, y_0))$$

$$3) \text{ si } K(s) = 0 \Rightarrow \theta'(s) = 0 \Rightarrow \theta(s) = \theta_0$$

$$\Rightarrow T(s) = \begin{pmatrix} \cos \theta_0 \\ \sin \theta_0 \end{pmatrix} \Rightarrow \begin{cases} x'(s) = \cos(\theta_0) \\ y'(s) = \sin(\theta_0) \end{cases}$$

$$\Rightarrow \begin{cases} x(s) = \cos(\theta_0) \cdot s + x_0 \\ y(s) = \sin(\theta_0) \cdot s + y_0 \end{cases}$$

$$\Rightarrow \begin{pmatrix} x(s) \\ y(s) \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + s \cdot \begin{pmatrix} \cos(\theta_0) \\ \sin(\theta_0) \end{pmatrix}$$

$\Rightarrow (x(s), y(s)) \in$ la droite passant par (x_0, y_0) et de vecteur directeur

$$\begin{pmatrix} \cos(\theta_0) \\ \sin(\theta_0) \end{pmatrix}$$

Correction Exercice 4 - feuille 4

1. Repère de Frenet : $\underline{N}'(s) = -\frac{1}{s\sqrt{2}} (\underline{T}(s) + \underline{B}(s))$

$$\begin{aligned} \underline{N}''(s) &= \frac{1}{s^2\sqrt{2}} (\underline{T}'(s) + \underline{B}'(s)) - \frac{1}{s\sqrt{2}} (\underline{T}'(s) + \underline{B}'(s)) \\ &= -\frac{1}{s} \underline{N}'(s) - \frac{1}{s\sqrt{2}} \left(\frac{1}{s\sqrt{2}} + \frac{1}{s\sqrt{2}} \right) \underline{N}(s) = -\frac{1}{s} \underline{N}'(s) - \frac{1}{s^2} \underline{N}(s) \end{aligned}$$

$$s^2 \underline{N}''(s) + s \underline{N}'(s) + \underline{N}(s) = 0. \quad \text{comme } \underline{T}'(s) = \frac{1}{s\sqrt{2}} \underline{N}(s)$$

$$s^2 \left(s\sqrt{2} \underline{T}' \right)''(s) + s \left(s\sqrt{2} \underline{T}' \right)'(s) + s\sqrt{2} \underline{T}'(s) = 0.$$

$$s^2 \left(s\sqrt{2} T''' + 2\sqrt{2} T'' \right) + s \left(s\sqrt{2} T'' + \sqrt{2} T' \right) + s\sqrt{2} T' = 0.$$

$$s^3 \sqrt{2} T''' + 3\sqrt{2} s^2 T'' + 2\sqrt{2} s T' = 0, \quad s\sqrt{2} (s^2 T''' + 3s T'' + 2T') = 0.$$

$$s\sqrt{2} (s^2 T'' + s T' + T)' = 0; \quad \text{on a alors par continuité en } 0$$

$$\boxed{(s^2 T'' + s T' + T)' = 0.}$$

Il s'ensuit que $s^2 \underline{T}'' + s \underline{T}' + \underline{T} = \underline{k}$ où \underline{k} est un vecteur constant de \mathbb{R}^3 .

2. On pose $z(u) = y(s)$ avec $s = e^u$ d'où $z'(u) = y'(s) \frac{ds}{du} = y'(s) s$.

$$z''(u) = (y'(s) s)' s = y'' s^2 + y' s; \quad z''(u) + z(u) = k$$

Soit 6^e eq. et 2nd membre $v(u) = c \cos u + d \sin u$.

Soit part. $w(u) = k$; d'où $z(u) = c \cos u + d \sin u + k$.

3. On a ainsi $\underline{T}(s) = \underline{C} \cos u + \underline{D} \sin u + \underline{K}$.

$$\eta'_u = \eta'_s s = \underline{T}(s) s = e^u (\underline{C} \cos u + \underline{D} \sin u + \underline{K})$$

$$\eta_u = \int e^u (\underline{C} \cos u + \underline{D} \sin u + \underline{K}) du + \underline{E}$$

Pour trouver une primitive $\int (\underline{C} \cos u + \underline{D} \sin u) e^u du$, on opère
 composante par composante; $(\underline{c} \cos u + \underline{d} \sin u) e^u$ étant cette composante,
 on cherche cette primitive sous la forme $(a \cos u + b \sin u) e^u$. On a
 ainsi

$$\begin{aligned}
 \left(e^u (a \cos u + b \sin u) \right)' &= e^u (a \cos u + b \sin u - a \sin u + b \cos u) \\
 &= e^u ((a+b) \cos u + (b-a) \sin u).
 \end{aligned}$$

Il suffit ainsi de résoudre le système linéaire

$$\begin{cases} a+b = c \\ -a+b = d \end{cases} \quad \text{d'où} \quad a = \frac{c-d}{2}, \quad b = \frac{c+d}{2}$$

D'où le paramétrage

$$\eta_u = e^u \left(\underline{A} \cos u + \underline{B} \sin u + \underline{K} \right) + \underline{E}$$

\underline{A} , \underline{B} , \underline{K} , \underline{E} étant 4 vecteurs constants de \mathbb{R}^2