Inverse problem for a parabolic equation with periodic conditions

M. CRISTOFOL¹, I. KADDOURI^{1,2}, and D. E. TENIOU²

 (1) University of Aix Marseille LATP
 (2) University of sciences and technology Houari Boumediene, Faculty of mathematics, Laboratory AMNEDP, Department of Mathematics

Juin/2012

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Inverse problem

Juin/2012 1 / 20

Outline of the talk

Introduction

Objectives





Inverse problem



• Direct problem : the coefficients are known.

- \rightarrow we determine solution.
- **Inverse problem** : the solution is known (partially).
- ullet ightarrow we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - 2 The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- **Inverse problem** : the solution is known (partially).
- ullet ightarrow we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - 2 The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- Inverse problem : the solution is known (partially).
- ullet ightarrow we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - 2 The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- Inverse problem : the solution is known (partially).
- ullet ightarrow we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- Inverse problem : the solution is known (partially).
- ullet \to we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- Inverse problem : the solution is known (partially).
- ullet \to we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - The solution can "not be unique".
 - The solution can "not be stable".

- Direct problem : the coefficients are known.
- \rightarrow we determine solution.
- Inverse problem : the solution is known (partially).
- ullet \to we determine one of several coefficients.
- In general the inverse problems are ill posed in the sense of Hadamard :
 - The solution can "not exist".
 - 2 The solution can "not be unique".
 - The solution can "not be stable".

We prove an inequality of stability by using a Carleman estimate for the following parabolic periodic problem :

$$\begin{cases} \partial_t u = \Delta u + \mu(\mathbf{x})u - \nu(\mathbf{x})u^2, & 0 < t < T, \mathbf{x} \in \Omega \\ u(0, \mathbf{x}) = u_0(\mathbf{x}) & \mathbf{x} \in \Omega \\ u\big|_{\Gamma_j^0} = u\big|_{\Gamma_j^1}, & \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^1}, & 1 \le j \le n \end{cases}$$
(1)

• $\mu(x)$, $\nu(x)$ and $u_0(x)$ are *L*-periodic functions $(L = (L_j)_j)$.

• $\mu(x)$ unknown, $\nu(x)$ known.

• where $\Omega = \prod_{j=1}^{n} (0, L_j)$, $Q = (0, T) \times \Omega$, $Q_0 = (t_0, T) \times \Omega$ $\Sigma = (0, T) \times \partial \Omega$, $\partial \Omega$ is the boundary of Ω , $\Gamma_j^0 = \partial \Omega \cap \{x_j = 0\}, \Gamma_j^1 = \partial \Omega \cap \{x_j = L_j\}.$

< 日 > < 同 > < 回 > < 回 > < □ > <

We prove an inequality of stability by using a Carleman estimate for the following parabolic periodic problem :

$$\begin{cases} \partial_t u = \Delta u + \mu(\mathbf{x})u - \nu(\mathbf{x})u^2, & 0 < t < T, \mathbf{x} \in \Omega \\ u(0, \mathbf{x}) = u_0(\mathbf{x}) & \mathbf{x} \in \Omega \\ u\big|_{\Gamma_j^0} = u\big|_{\Gamma_j^1}, \quad \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^1}, & 1 \le j \le n \end{cases}$$
(1)

• $\mu(x)$, $\nu(x)$ and $u_0(x)$ are *L*-periodic functions $(L = (L_j)_j)$.

• $\mu(x)$ unknown, $\nu(x)$ known.

• where $\Omega = \prod_{j=1}^{n} (0, L_j)$, $Q = (0, T) \times \Omega$, $Q_0 = (t_0, T) \times \Omega$ $\Sigma = (0, T) \times \partial \Omega$, $\partial \Omega$ is the boundary of Ω , $\Gamma_j^0 = \partial \Omega \cap \{x_j = 0\}, \Gamma_j^1 = \partial \Omega \cap \{x_j = L_j\}.$

< 日 > < 同 > < 回 > < 回 > < □ > <

We prove an inequality of stability by using a Carleman estimate for the following parabolic periodic problem :

$$\begin{cases} \partial_t u = \Delta u + \mu(\mathbf{x})u - \nu(\mathbf{x})u^2, & 0 < t < T, \mathbf{x} \in \Omega \\ u(0, \mathbf{x}) = u_0(\mathbf{x}) & \mathbf{x} \in \Omega \\ u|_{\Gamma_j^0} = u|_{\Gamma_j^1}, \quad \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^1}, & 1 \le j \le n \end{cases}$$
(1)

• $\mu(x)$, $\nu(x)$ and $u_0(x)$ are *L*-periodic functions $(L = (L_j)_j)$.

- $\mu(x)$ unknown, $\nu(x)$ known.
- where $\Omega = \prod_{j=1}^{n} (0, L_j)$, $Q = (0, T) \times \Omega$, $Q_0 = (t_0, T) \times \Omega$ $\Sigma = (0, T) \times \partial \Omega$, $\partial \Omega$ is the boundary of Ω , $\Gamma_j^0 = \partial \Omega \cap \{x_j = 0\}, \Gamma_j^1 = \partial \Omega \cap \{x_j = L_j\}.$

In ecology, this problem can modelize the spreading of insects in field of fruit trees.

In biology :

- *u* is the population density.
- μ is the intrinsic growth rate.
- ν measures the effects of competition.

In ecology, this problem can modelize the spreading of insects in field of fruit trees.

In biology :

- *u* is the population density.
- μ is the intrinsic growth rate.
- ν measures the effects of competition.

▲ 同 ▶ → 三 ▶

In ecology, this problem can modelize the spreading of insects in field of fruit trees.

In biology :

- *u* is the population density.
- μ is the intrinsic growth rate.
- ν measures the effects of competition.

▲ 同 ▶ → 三 ▶

Our main goal is to reconstruct the coefficient $\mu(x)$ from partial measurements of the solution u:

- We improve a Carleman inequality established by J.Choi¹ for a linear problem, by eliminating the constraints of the set of observation.
- We apply this inequality to a nonlinear problem.
- To end we prove the stability of the potential $\mu(x)$ (growth rate) with regard to the observations by using this Carleman inequality.

1. ("Inverse problem for a parabolic equation with space-periodic boundary conditions by a Carleman estimate", Inverse. III-posed Problems, 2003)

- Our main goal is to reconstruct the coefficient $\mu(x)$ from partial measurements of the solution u:
 - We improve a Carleman inequality established by J.Choi¹ for a linear problem, by eliminating the constraints of the set of observation.
 - We apply this inequality to a nonlinear problem.
 - To end we prove the stability of the potential $\mu(x)$ (growth rate) with regard to the observations by using this Carleman inequality.

1. ("Inverse problem for a parabolic equation with space-periodic boundary conditions by a Carleman estimate",Inverse. III-posed Problems, 2003)

- Our main goal is to reconstruct the coefficient $\mu(x)$ from partial measurements of the solution u:
 - We improve a Carleman inequality established by J.Choi¹ for a linear problem, by eliminating the constraints of the set of observation.
 - We apply this inequality to a nonlinear problem.
 - To end we prove the stability of the potential $\mu(x)$ (growth rate) with regard to the observations by using this Carleman inequality.

^{1. (&}quot;Inverse problem for a parabolic equation with space-periodic boundary conditions by a Carleman estimate", Inverse. Ill-posed Problems, 2003)

• Our goal is to prove the following theorem :

Theorem

Let $\omega \subset \Omega$ an open set, $\theta \in (0, T)$ fixed, then there exists a constant C > 0, $C = C(\omega, \Omega, T, \theta)$, such that :

 $||\mu - \tilde{\mu}||_{L^{2}(\Omega)} \leq C(||u - \tilde{u}||_{H^{1}(0,T;L^{2}(\omega))} + ||(u - \tilde{u})(\theta,.)||_{H^{2}(\Omega)})$

▲ 同 ▶ → 三 ▶

Existence and uniqueness

Nonlinear case :

Theorem of existence and uniqueness (Berestycki-Hamel-Roques 2005)

We assume that $\mu, \nu \in C^m(\mathbb{R}^n)$, $m \in (0, 1)$, $\mu(x)$, $\nu(x)$ et $u_0(x)$ are periodic functions, $\nu(x) > 0$. Then the problem (1) have an unique solution in $C^{1+\frac{m}{2},2+m}((0,\infty) \times \mathbb{R}^n) \cap C([0,\infty) \times \mathbb{R}^n)$.

Lemma (Carleman inequality)

Let $\omega \subset \Omega$, $\omega \neq \Omega$, there exists s_0 , there exists constant C > 0, $C = C(\omega, \Omega, \theta, T)$, such that $\forall s \ge s_0$ the solution of the problem Lz = g with periodic conditions boundary verifies the following inequality :

$$\begin{split} \int_{Q_{t_0}} \left(\frac{1}{s\varphi} \left(\left| \frac{\partial z}{\partial t} \right|^2 + |\Delta z|^2 \right) + s\varphi |\nabla z|^2 + s^3 \varphi^3 |z|^2 \right) e^{2s\alpha} dx \, dt \\ & \leq C \big(\int_{Q_{t_0}} |g|^2 e^{2s\alpha} dx dt + \int_{]t_0, T[\times \omega} s^3 \varphi^3 |z|^2 e^{2s\alpha} dx dt \big) \end{split}$$

with

$$Lz = \frac{\partial z}{\partial t} - \Delta z = g(t, x)$$
 in Q

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Lemma (Weight function)

Let $\omega \subset \overline{\Omega}$, $\omega \neq \Omega$. Then there exists a periodic function $\psi \in C^2(\overline{\Omega})$, such that :

 $\psi(\mathbf{x}) > \mathbf{0}, \forall \mathbf{x} \in \Omega, \quad et \quad \nabla \psi(\mathbf{x}) \neq \mathbf{0}, \quad si \quad \mathbf{x} \notin \omega$

$$\psi|_{\Gamma_{j}^{0}} = \psi|_{\Gamma_{j}^{1}}, \quad \frac{\partial \psi}{\partial x_{j}}|_{\Gamma_{j}^{0}} = \frac{\partial \psi}{\partial x_{j}}|_{\Gamma_{j}^{1}}, \quad pour \quad 1 \leq j \leq n.$$

 $\varphi(t, x) = \frac{e^{\lambda \psi(x)}}{(t - t_{0})(T - t)},$

and

$$\alpha(t,x) = \frac{e^{\lambda\psi} - e^{2\lambda||\psi||_{C(\overline{\Omega})}}}{(t-t_0)(T-t)} < 0.$$

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Juin/2012 10 / 20

Remark

We use this periodic weight function to eliminate the boundary terms. Because of the boundary terms, Choi had to :

- consider two weight functions².
- 2 assume that the open set ω (on which the gradient of the weight function can vanish) contains corners (in \mathbb{R}^2).

2. A V. Fursikov-O Y. Imanuvilov, Controllability of Evolution Equations, 1996

Remark

We use this periodic weight function to eliminate the boundary terms. Because of the boundary terms, Choi had to :

- consider two weight functions².
- 2 assume that the open set ω (on which the gradient of the weight function can vanish) contains corners (in \mathbb{R}^2).

2. A V. Fursikov-O Y. Imanuvilov, Controllability of Evolution Equations, 1996

We have :

$$\begin{cases} \partial_t u(t,x) &= \Delta u(t,x) - p(x,u)u(t,x) & t_0 < t < T, x \in \Omega \\ u(t_0,x) &= u_0(x) & \\ u\big|_{\Gamma_j^0} &= u\big|_{\Gamma_j^1}, \quad \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial u}{\partial x_j}\Big|_{\Gamma_j^1}, & 1 \le j \le n \end{cases}$$
(P_{μ,u_0})

with $p(x, u) = \mu(x) - \nu(x)u$.

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

▶ < ≣ ▶ ≣ ∽ < ⊂ Juin/2012 12 / 20

イロト イヨト イヨト イヨト

and

$$\begin{cases} \partial_{t}\tilde{u}(t,x) &= \Delta \tilde{u}(t,x) - \tilde{\rho}(x,u)\tilde{u}(t,x) \qquad t_{0} < t < T, x \in \Omega \\ \tilde{u}(t_{0},x) &= \tilde{u}_{0}(x) \qquad \qquad \\ \tilde{u}|_{\Gamma_{j}^{0}} &= \tilde{u}|_{\Gamma_{j}^{1}}, \quad \frac{\partial \tilde{u}}{\partial x_{j}}\Big|_{\Gamma_{j}^{0}} = \frac{\partial \tilde{u}}{\partial x_{j}}\Big|_{\Gamma_{j}^{1}}, \qquad 1 \le j \le n \end{cases}$$

$$(P_{\tilde{\mu},\tilde{u}_{0}})$$

with $\tilde{p}(x, \tilde{u}) = \tilde{\mu}(x) - \nu(x)\tilde{u}$.

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

▶ < E ト E ∽ へ ⊂ Juin/2012 13 / 20

イロト イヨト イヨト イヨト

We formulate the inverse problem. Let u, (resp. \tilde{u}) solution of the problem (P_{μ,u_0}) , (resp. $P_{\tilde{\mu},\tilde{u}_0})$. Let $w = u - \tilde{u}$, $f = \mu - \tilde{\mu}$, $a(.) = u(\theta, .) - \tilde{u}(\theta, .)$ We obtain :

$$\begin{cases} w_t = \Delta w + \mu w + \tilde{u}f - \nu w(u + \tilde{u}), & 0 \le t \le T, x \in \Omega \\ w(0, x) = u_0(x) - \tilde{u}_0(x), & x \in \Omega \\ w|_{\Gamma_j^0} = w|_{\Gamma_j^1}, & \frac{\partial w}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial w}{\partial x_j}\Big|_{\Gamma_j^1}, & 0 \le t \le T \end{cases}$$

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Juin/2012 14 / 20

A (10) A (10)

We set : $z(t,x) = w(t,x)/\tilde{u}(t,x)$

$$\begin{cases} z_t = \Delta z + P_1(z) + f, & t_0 \le t \le T, x \in \Omega \\ z(\theta, x) = a(x) / \tilde{u}(\theta, x), & x \in \Omega \\ z|_{\Gamma_j^0} = z|_{\Gamma_j^1}, & \frac{\partial z}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial z}{\partial x_j}\Big|_{\Gamma_j^1}, & t_0 \le t \le T \end{cases}$$

 P_1 : first order operator.

 $P_1(z) = a_1(t, x)z + A_1(t, x)\nabla z$

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

< 口 > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

We set $y = z_t$

$$\begin{cases} y_t = \Delta y + T_1(y) + Q_1(z) & t_0 \leq t \leq T, x \in \Omega, \\ y|_{\Gamma_j^0} = y|_{\Gamma_j^1}, \quad \frac{\partial y}{\partial x_j}\Big|_{\Gamma_j^0} = \frac{\partial y}{\partial x_j}\Big|_{\Gamma_j^1}, \quad t_0 \leq t \leq T \end{cases}$$

 T_1 , Q_1 : first order operator.

イロト イヨト イヨト イヨト

By applying Carleman inequality to y, we obtain :

$$\begin{split} &\int_{Q_{t_0}} \left(\frac{1}{s\varphi} \left(\left| \frac{\partial y}{\partial t} \right|^2 + |\Delta y|^2 \right) + s\varphi |\nabla y|^2 + s^3 \varphi^3 |y|^2 \right) e^{2s\alpha} dx \, dt \\ &\leq C \left(\int_{Q_{t_0}} \left((Q_1(z) + T_1(y))^2 e^{2s\alpha} dx dt + \int_{]t_0, T[\times \omega} s^3 \varphi^3 |y|^2 e^{2s\alpha} dx dt \right) \end{split}$$

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Juin/2012 17 / 20

イロト イヨト イヨト イヨト

To summarise, from :

$$f = \mu - \tilde{\mu},$$

$$f = z_t - \Delta z - P_1(z)$$

and

$$y = z_t$$

The Carleman estimate gives the following inequality of stability :

 $||\mu - \tilde{\mu}||_{L^{2}(\Omega)} \leq C(||u - \tilde{u}||_{H^{1}(0,T;L^{2}(\omega))} + ||(u - \tilde{u})(\theta,.)||_{H^{2}(\Omega)})$

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

< 日 > < 同 > < 回 > < 回 > < □ > <

Work in progress



• We study the same problem, but with non-smooth coefficient $\mu(x)$.

M. Cristofol, I. Kaddouri, D. Teniou (LATP)

Juin/2012 19/20

Work in progress

- We study the same problem, but with non-smooth coefficient $\mu(x)$.
- 2 We use another idea for the reconstruction of the potential $\mu(x)$, we work in \mathbb{R}^n with the same problem but we use differents data.

Thank you for your attention.