

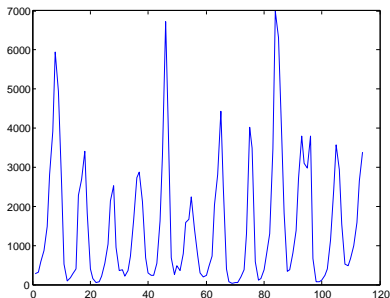
# Computing the maximum of random processes and series

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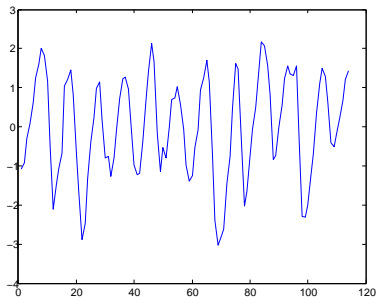
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# The lynx data



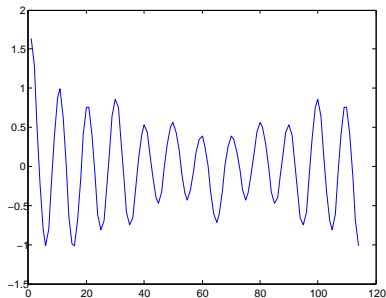
Annual record of the number of the Canadian lynx "trapped" in the Mackenzie River district of the North-West Canada for the period 1821 - 1934, (Elton and Nicholson, 1942)

After passage to the log and centering



# Testing

The maximum of absolute value of the series is **3.0224**. An estimation of the covariance with **WAFO** gives



Can we judge the significance of this quantity ?

We assume the series is Gaussian.

Let  $\varphi_{\Sigma}$  the Gaussian density in  $\mathbb{R}^{114}$ . We have to compute

$$\iint_{-3.0224}^{3.0224} \varphi_{\Sigma}(x_1, \dots, x_{114}) dx_1, \dots, dx_{114}$$

Let us consider our problem in a general setting.  $\Sigma$  is a  $n \times n$  covariance matrix

$$I := \int_{l_1}^{u_1} \cdots \int_{l_n}^{u_n} \varphi_{\Sigma}(\mathbf{x}) d\mathbf{x} \quad (1)$$

By conditioning or By Choleski decomposition we can write

$$x_1 = T_{11}z_1$$

$$x_2 = T_{12}z_1 + T_{22}z_2$$

.....

Where the  $Z_i$ 's are independent standard. Integral  $I$  becomes

$$I := \int_{l_1/T_{11}}^{u_1/T_{11}} \varphi(z_1) dz_1 \int_{\frac{l_2 - T_{12}z_1}{T_{22}}}^{\frac{u_2 - T_{12}z_1}{T_{22}}} \varphi(z_2) dz_2 \cdots \cdots \quad (2)$$

Now making the change of variables  $t_i = \Phi(z_i)$

$$I := \int_{\Phi^{-1}(l_1/T_{11})}^{\Phi^{-1}(u_1/T_{11})} dt_1 \int_{\Phi^{-1}\left(\frac{l_2 - T_{12}\Phi^{-1}(t_1)}{T_{22}}\right)}^{\Phi^{-1}\left(\frac{u_2 - T_{12}\Phi^{-1}(t_1)}{T_{22}}\right)} dt_2 \cdots \quad (3)$$

And by a final scaling this integral can be written as an integral on the hypercube  $[0, 1]^n$ .

$$I := \int_{[0,1]^n} h(\mathbf{t}) d\mathbf{t}. \quad (4)$$

At this stage, if form (4) is evaluated by MC it corresponds to an important reduction of variance ( $10^{-2}$ ,  $10^{-3}$ ) with respect to the form (1). **The transformation up to there is elementary but efficient.**



# QMC

In the form (4) the **MC** evaluation is based on

$$\hat{I} = 1/M \sum_{i=1}^M h(\mathbf{t}_i)$$

it is well known that its convergence is slow :  $\mathcal{O}(M^{-1/2})$ .

The **Quasi Monte Carlo Method** is based on the of searching sequences that are “more random than random”. A popular method is based on **lattice rules**. Let  $\mathbf{Z}_1$  be a “nice integer sequence” in  $\mathbb{N}^n$ , the rule consist of choosing

$$\mathbf{t}_i = \left\{ \frac{i \cdot \mathbf{Z}}{M} \right\},$$

where the notation  $\{ \}$  means that we have taken the fractional part componentwise.  $M$  is chosen prime.

## Theorem

*(Nuyens and cools, 2006) Assume that  $h$  is the tensorial product of periodic functions that belong to a Koborov space (RKHS). Then the minimax sequence and the worst error can be calculated by a polynomial algorithm. Numerical results show that the convergence is roughly  $\mathcal{O}(M^{-1})$ .*

This result concerns the “**worst case**” so it is not so relevant

# A meta theorem

If  $h$  does not satisfies the conditions of the preceding theorem we can still hope **QMC** to be faster than **MC**

# MCQMC

Let  $(t_i, i)$  be the lattice sequence, the way of estimating the integral can be turned to be random but exactly unbiased by setting

$$\hat{I} = 1/M \sum_{i=1}^M h(\{t_i + U\})$$

where  $U$  is uniform on  $[0, 1]^n$ .

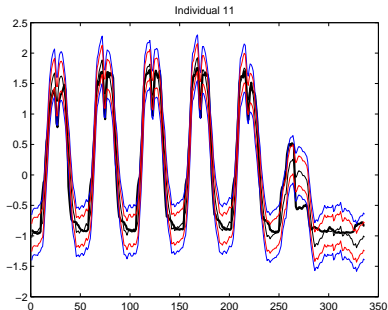
By the meta theorem  $\hat{I}$  has **small variance**.

So we can make  $N$  independent replications of this calculation and construct Student-type confidence intervals. It is correct whatever the properties of the function  $h$  are.

$N$  must be chosen small : in practical 12.

Conclusion : At the cost of a small loss in speed ( $\sqrt{12}$ ) we have a **reliable estimation of error**.

This method has been used to construct confidence bands for electrical load curves prediction. Azaïs, Bercu, Fort, Lagnoux Lé (2009)



In this figure the weekly cycle of a firm is decomposed on a Fourier basis. Each coefficient is learned on a **large learning sample**. The error is supposed Gaussian and its variance structure can be computed by linear models formulas.

# Do processes exist ?

In this part  $X(t)$  is a Gaussian process defined on a compact interval  $[0, T]$ .

Since such a process is always observed in a finite set of times and since the previous method work with say  $n = 1000$ , is it relevant to consider continuous case ?

Answer yes : random process occur as limit statistics. Consider for example the simple mixture model

$$\begin{cases} H_0 : Y \sim N(0, 1) \\ H_1 : Y \sim pN(0, 1) + (1 - p)N(\mu, 1) \quad p \in [0, 1], \quad \mu \in \mathcal{M} \subset \mathbb{R} \end{cases} \quad (5)$$

## Theorem (Asymptotic distribution of the LRT)

*Under some conditions the LRT of  $H_0$  against  $H_1$  has, under  $H_0$ , the distribution of the random variable*

$$\frac{1}{2} \sup_{t \in \mathcal{M}} \{Z^2(t)\}, \quad (6)$$

*where  $Z(\cdot)$  is a centered Gaussian process covariance function*

$$r(s, t) = \frac{e^{st} - 1}{\sqrt{e^{s^2} - 1} \sqrt{e^{t^2} - 1}}.$$

In this case there is no discretization.

# The record method

$$\mathbb{P}\{M > u\} = \mathbb{P}\{X(0) > u\} + \int_0^T \mathbb{E}(X'(t)^+ \mathbf{1}_{X(s) \leq u, \forall s < t} | X(t) = u) p_{X(t)}(u) dt \quad (7)$$

after discretization of  $[0, T]$ ,  $D_n = \{0, T/n, 2T/n, \dots, T\}$  Then

$$\mathbb{P}\{\sup_{t \in D_n} X(t) > u\} \leq \mathbb{P}\{M > u\} \leq \mathbb{P}\{X(0) > u\} + \int_0^T \mathbb{E}(X'(t)^+ \mathbf{1}_{X(s) \leq u, \forall s < t, s \in D_n} | X(t) = u) p_{X(t)}(u) dt \quad (8)$$



Now the integral is replaced by a **trapezoidal rule** using the same discretization. Error of the trapezoidal rule is easy to evaluate .

Moreover that the different terms involved can be computed in a recursive way.

# An example

Using MGP written by Genz, let us consider the centered stationary Gaussian process with covariance  $\exp(-t^2/2)$

```
[ pl, pu, el, eu, en, eq ] = MGP( 100000, 0.5, 50,  
@ (t) exp(-t.^2/2), 0, 4);
```

pu upper bound with

eu = estimate for total error,

en = estimate for discretization error, and

eq = estimate for MCQMC error;

pl lower bound

el = error estimate (MCQMC)

# Extensions

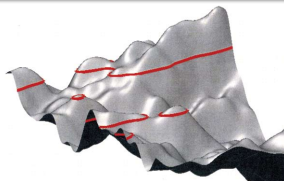
Treat all the cases : maximum of the absolute value, non centered, non-stationary. In each case some tricks have to be used.

**A great challenge is to use such formulas for fields .**

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