Improved learning theory for kernel distribution regression with two-stage sampling

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2 Near-unbiased condition and improved rates

Distribution regression

We observe i.i.d. pairs

$$(\mu_i, Y_i), \quad i=1,\ldots,n.$$

• $Y_i \in \mathbb{R}$.

• μ_i is a probability distribution on Ω .

• Ω is compact in \mathbb{R}^d .

Goal: constructing a regression function

$$\widehat{f}_n: \mathcal{P}(\Omega) \to \mathbb{R},$$

• where $\mathcal{P}(\Omega)$ is the set of probability distributions on Ω .

Application fields described in [Szabó et al., 2015, Szabó et al., 2016, Meunier et al., 2022, Bachoc et al., 2023a].

Hilbertian embedding

Hilbertian embedding

$$egin{aligned} & x:\mathcal{P}(\Omega) o\mathcal{H}\ & \mu\mapsto x_{\mu}, \end{aligned}$$

where \mathcal{H} is a Hilbert space.

 \implies In order to use kernels on Hilbert spaces (see later)!

Hilbertian embedding 1: mean embedding

Consider a kernel k on Ω .

Very quick introduction to kernels and RKHS

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• k: \Omega \times \Omega \to \mathbb{R}.
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- For any $\ell \in \mathbb{N}$, $t_1, \ldots, t_\ell \in \Omega$, the $\ell \times \ell$ matrix $[k(t_i, t_j)]$ is symmetric non-negative definite.
- There is a (unique) Hilbert space \mathcal{H}_k of functions from Ω to \mathbb{R} ,
 - with inner product $\langle \cdot, \cdot
 angle_{\mathcal{H}_k}$
 - with norm $\|\cdot\|_{\mathcal{H}_k}$

such that

- \mathcal{H}_k contains all functions $k_t := k(t, \cdot)$ for $t \in \Omega$,
- for all $g \in \mathcal{H}_k$, for all $t \in \Omega$, $g(t) = \langle g, k_t \rangle_{\mathcal{H}_k}$ reproducing property.

 $\implies \mathcal{H}_k$ is the reproducing kernel Hilbert space (RKHS) of k.

Then mean embedding

$$x_{\mu} := \left(t \mapsto \int_{\Omega} k(t, x) \mathrm{d}\mu(x)\right) = \int_{\Omega} k_{x} \mathrm{d}\mu(x),$$

[Szabó et al., 2015, Szabó et al., 2016, Muandet et al., 2017].

Hilbertian embedding 2: sliced Wasserstein

The sliced Wasserstein distance [Kolouri et al., 2018, Manole et al., 2022, Meunier et al., 2022]

$$\mathcal{SW}(\mu,
u)^2 := \int_{\mathcal{S}^{d-1}} \int_0^1 \left(\mathcal{F}_{\mu_\theta}^{-1}(t) - \mathcal{F}_{
u_\theta}^{-1}(t)
ight)^2 \mathrm{d}t \mathrm{d}\Lambda(heta),$$

- with two distributions $\mu, \nu \in \mathcal{P}(\Omega)$,
- where \mathcal{S}^{d-1} is the unit sphere ,
- where Λ is the uniform distribution on \mathcal{S}^{d-1} ,
- where μ_{θ} is the univariate distribution of $\langle \theta, X \rangle$ for $X \sim \mu$,
- where $F_{\mu_{\theta}}^{-1}$ is the quantile function of μ_{θ} .

Hilbert distance of a Hilbertian embedding

•
$$\mathcal{H} = \mathcal{S}^{d-1} \times [0, 1],$$

•
$$x_{\mu}(\theta,t) = F_{\mu_{\theta}}^{-1}(t).$$

Hilbertian embedding 3: Sinkhorn distance and dual potential

Dual formulation of entropic-regularized (Sinkhorn) optimal transport [Genevay, 2019]

$$\sup_{h\in L^{1}(\mu),g\in L^{1}(\mathcal{U})} \int_{\Omega} h(x) d\mu(x) + \int_{\Omega} g(y) d\mathcal{U}(y) \\ -\epsilon \int_{\Omega\times\Omega} e^{\frac{1}{\epsilon} (h(x) + g(y) - \frac{1}{2} ||x - y||^{2})} d\mu(x) d\mathcal{U}(y).$$

- $\epsilon > 0$ regularization parameter.
- Fixed $\mathcal{U} \in \mathcal{P}(\Omega)$ called reference measure.
- For any $\mu \in \mathcal{P}(\Omega)$.

Hilbertian embedding

There is a unique optimal (h^*, g^*) such that g^* is centered w. r. t. \mathcal{U} . Also $g^* \in L^2(\mathcal{U})$. [Bachoc et al., 2023a]:

- $x_{\mu} := g^*$.
- $\mathcal{H} := L^2(\mathcal{U}).$

Kernel ridge regression on Hilbert space

• Hilbertian covariates: for i = 1, ..., n, let

$$x_i := x_{\mu_i}$$

Squared exponential kernel on \mathcal{H} : for $u, v \in \mathcal{H}$,

$$K(u,v):=e^{-\|u-v\|_{\mathcal{H}}^2}$$

 \implies Yields the RKHS $\mathcal{H}_{\mathcal{K}}$ of functions from \mathcal{H} to \mathbb{R} .

Ridge regression

$$\widehat{f_n} = \operatorname*{argmax}_{f \in \mathcal{H}_K} R_n(f)$$

with

$$R_n(f) := \frac{1}{n} \sum_{i=1}^n (f(x_i) - Y_i)^2 + \lambda \|f\|_{\mathcal{H}_{\kappa}}^2,$$

• where $\lambda > 0$ is a regularization parameter.

Two-stage sampling

Studied in [Szabó et al., 2015, Szabó et al., 2016, Meunier et al., 2022].

- For $i = 1, \ldots, n$, μ_i is unobserved.
- We observe i. i. d. $(X_{i,j})_{j=1,\ldots,N}$ with $X_{i,j} \sim \mu_i$.

We let

$$\mu_i^{\mathsf{N}} = \frac{1}{\mathsf{N}} \sum_{j=1}^{\mathsf{N}} \delta_{\mathsf{X}_{i,j}}$$

and

$$x_{\mathbf{N},i} = x_{\mu_i^{\mathbf{N}}}.$$

Ridge regression with approximate covariates

$$\widehat{f}_{n,N} = \operatorname*{argmax}_{f \in \mathcal{H}_{K}} R_{n,N}(f)$$

with

$$R_{n,\mathbf{N}}(f) := \frac{1}{n} \sum_{i=1}^n \left(f(x_{\mathbf{N},i}) - Y_i \right)^2 + \lambda \|f\|_{\mathcal{H}_{\mathcal{K}}}^2.$$

1 Distribution regression, Hilbertian embedding and two-stage sampling

2 Near-unbiased condition and improved rates

Existing error bounds on $\hat{f}_n - \hat{f}_{n,N}$

- [Szabó et al., 2015, Szabó et al., 2016, Meunier et al., 2022] address their respective distribution regression settings.
- But their results are naturally made general.

Existing bounds

For all $s \ge 1$, conditionally to $(x_i, Y_i)_{i=1}^n$,

$$\mathbb{E}\left[\left\|\hat{f}_{n}-\hat{f}_{n,N}\right\|_{\mathcal{H}_{K}}^{s}\right]^{1/s} \leq \frac{\operatorname{constant}\left(\|\hat{f}_{n}\|_{\mathcal{H}_{K}}+Y_{\max,n}\right)}{\sqrt{N}\lambda}$$

• with $Y_{\max,n} = \max_{i=1,...,n} |Y_i|$.

Existing proofs are improvable?

- Proofs based on explicit expressions of \hat{f}_n and $\hat{f}_{n,N}$.
- Somewhere:

$$\left\| \frac{1}{n} \sum_{i=1}^{n} \left(\hat{f}_n(x_i) K_{x_i} - \hat{f}_n(x_{N,i}) K_{x_{N,i}} \right) \right\|_{\mathcal{H}_{\kappa}} \\ \leq \frac{1}{n} \sum_{i=1}^{n} \left\| \hat{f}_n(x_i) K_{x_i} - \hat{f}_n(x_{N,i}) K_{x_{N,i}} \right\|_{\mathcal{H}_{\kappa}}$$

- But $\hat{f}_n(x_i)K_{x_i} \hat{f}_n(x_{N,i})K_{x_{N,i}}$ are independent conditionally on $(x_i, Y_i)_{i=1}^n$.
- Do they have approximately zero mean?

Near-unbiased condition

In [Bachoc et al., 2023b].

Near-unbiased condition

For i = 1, ..., n, there are random $a_{N,i}$ and $b_{N,i}$ such that

$$x_{N,i}-x_i=a_{N,i}+b_{N,i}.$$

•
$$||a_{N,i}||_{\mathcal{H}}$$
 has order $\frac{1}{\sqrt{N}}$.

$$\mathbb{E}(a_{N,i}|\mu_i) = 0 \in \mathcal{H}.$$

 $||b_{N,i}||_{\mathcal{H}} \text{ has order } \frac{1}{N}.$

For the 3 examples of Hilbertian embedding

- Mean embedding: $b_{N,i} = 0$ (exactly unbiased).
- Sinkhorn: indeed near unbiased, relying on [González-Sanz et al., 2022].
- Sliced Wasserstein: indeed near unbiased under conditions.

Improved rates

In [Bachoc et al., 2023b].

Theorem

Up to constant

$$\begin{split} \sqrt{\mathbb{E}_n \left[\|\hat{f}_n - \hat{f}_{n,N}\|_{\mathcal{H}_K}^2 \right]} &\leq \frac{Y_{\max,n} + \|\hat{f}_n\|_{\mathcal{H}_K}}{\lambda N} + \frac{Y_{\max,n} + \|\hat{f}_n\|_{\mathcal{H}_K}}{\lambda \sqrt{n}\sqrt{N}} \\ &+ \left(1 + \frac{\sqrt{N}}{\sqrt{n}}\right)^{-1} \left(\frac{Y_{\max,n} + \|\hat{f}_n\|_{\mathcal{H}_K}}{\lambda n} + \frac{Y_{\max,n} + \|\hat{f}_n\|_{\mathcal{H}_K}}{\lambda^2 n \sqrt{N}}\right) \end{split}$$

• with $Y_{\max,n} = \max_{i=1,...,n} |Y_i|$, • where \mathbb{E}_n denotes the conditional expectation given $(\mu_i, Y_i)_{i=1}^n$.

The \sqrt{n} we gain comes from average of independent centered variables.

Proof ingredient 1

$$\hat{f}_n = \operatorname*{argmin}_{f \in \mathcal{H}_K} \quad \frac{1}{n} \sum_{i=1}^n \left(f(x_i) - Y_i \right)^2 + \lambda \|f\|_{\mathcal{H}_K}^2$$

 and

$$\hat{f}_{n,N} = \underset{f \in \mathcal{H}_{\mathcal{K}}}{\operatorname{argmin}} \quad \frac{1}{n} \sum_{i=1}^{n} \left(f(x_{N,i}) - Y_i \right)^2 + \lambda \|f\|_{\mathcal{H}_{\mathcal{K}}}^2.$$

Then, exploiting convexity,

$$\begin{split} \lambda \| \hat{f}_n - \hat{f}_{n,N} \|_{\mathcal{H}_K}^2 &\leq \frac{1}{n} \sum_{i=1}^n \left\{ \left[\hat{f}_n(x_{N,i}) - \hat{f}_{n,N}(x_{N,i}) \right] \hat{f}_n(x_{N,i}) \\ &- \left[\hat{f}_n(x_i) - \hat{f}_{n,N}(x_i) \right] \hat{f}_n(x_i) \right\} \\ &+ \frac{1}{n} \sum_{i=1}^n Y_i \left\{ \left[\hat{f}_n(x_i) - \hat{f}_{n,N}(x_i) \right] - \left[\hat{f}_n(x_{N,i}) - \hat{f}_{n,N}(x_{N,i}) \right] \right\}. \end{split}$$

Proof ingredient 2

We are led to bound (in $\mathbb{R}!$) terms such as

$$\mathbb{E}\left(\frac{1}{n}\sum_{i=1}^{n}Y_{i}\left\{\left[\hat{f}_{n}(x_{i})-\hat{f}_{n,N}(x_{i})\right]-\left[\hat{f}_{n}(x_{N,i})-\hat{f}_{n,N}(x_{N,i})\right]\right\}\right).$$

By coupling arguments, we approximate by

$$\mathbb{E}\left(\frac{1}{n}\sum_{i=1}^{n}Y_{i}\left\{\left[\hat{f}_{n}(x_{i})-\tilde{f}_{n,N}(x_{i})\right]-\left[\hat{f}_{n}(x_{N,i})-\tilde{f}_{n,N}(x_{N,i})\right]\right\}\right),$$

• with $\tilde{f}_{n,N}$ constructed from new independent $(\tilde{x}_{N,i})_{i=1}^{n}$.

Application to sufficient N for minimax rate (1/2)

- [Caponnetto and De Vito, 2007] provide minimax rates as $n \to \infty$ with one-stage sampling (for \hat{f}_n).
- Target: conditional expectation function

 $f^* = \mathbb{E}(Y_i | x_i = \cdot)$ assumed to be in \mathcal{H}_K .

• We let \mathcal{L} be the distribution of x_i .

Problem class on ${\cal H}$

Hardness of $(\mathcal{L}, \mathcal{K}, f^*)$ measured by

- b > 1 effective dimension of $\mathcal{H}_{\mathcal{K}}$ w. r. t. distribution \mathcal{L} ,
- $c \in (1, 2]$ complexity of f^* .

Minimax rate

$$\sqrt{\int_{\mathcal{H}} \left(f^{\star}(x) - \hat{f}_n(x)\right)^2 \mathrm{d}\mathcal{L}(x)} = \mathcal{O}_{\mathbb{P}}\left(n^{-\frac{bc}{2(bc+1)}}\right)$$

• With
$$\lambda = n^{-\frac{b}{bc+1}}$$

Application to sufficient N for minimax rate (2/2)

In [Bachoc et al., 2023b], from our bounds:

Sufficient N for minimax

$$\sqrt{\int_{\mathcal{H}} \left(f^{\star}(x) - \hat{f}_{n,N}(x)\right)^2 \mathrm{d}\mathcal{L}(x)} = \mathcal{O}_{\mathbb{P}}\left(n^{-\frac{bc}{2(bc+1)}}\right).$$

With
$$\lambda = n^{-\frac{b}{bc+1}}$$
.

• With $N = n^a$,

$$\begin{cases} a = \max(\frac{b + \frac{bc}{2}}{bc+1}, \frac{2b-1}{bc+1}, \frac{4b-bc-2}{bc+1}) \ (\le 1) & \text{if } b(1-\frac{c}{2}) \le \frac{3}{4} \\ a = \max(\frac{b + \frac{bc}{2}}{bc+1}, \frac{2b-\frac{1}{2}}{bc+1}) \ (> 1) & \text{if } b(1-\frac{c}{2}) > \frac{3}{4} \end{cases}$$

In [Szabó et al., 2015, Szabó et al., 2016], same result for mean embedding with $N = n^{\frac{b(c+1)}{bc+1}}$,

$$\bullet \ \frac{b(c+1)}{bc+1} > a.$$

Conclusion

- Hilbertian embedding for (symmetric non-negative definite) kernels.
- Two-stage sampling as an additional source of error.
- Main contribution: tighter control of this error.
- The paper [Bachoc et al., 2023b]: arXiv:2308.14335.
- Paper [Bachoc et al., 2023a] on Sinkhorn kernel.
- Public Python codes (links in papers).

Thank you for your attention!

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